



# ENHANCING END-TO-END MULTI-CHANNEL SPEECH SEPARATION VIA SPATIAL FEATURE LEARNING

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# Outline

- Introduction
- Proposed method
- Experiments and results
- Conclusion

# Speech separation

- **Cocktail Party problem** [Cherry 1953]

- recover the speech of each speaker from overlapped speech mixture

$$\mathbf{y}[n] = \sum_{s=1}^S \mathbf{x}_s[n]$$

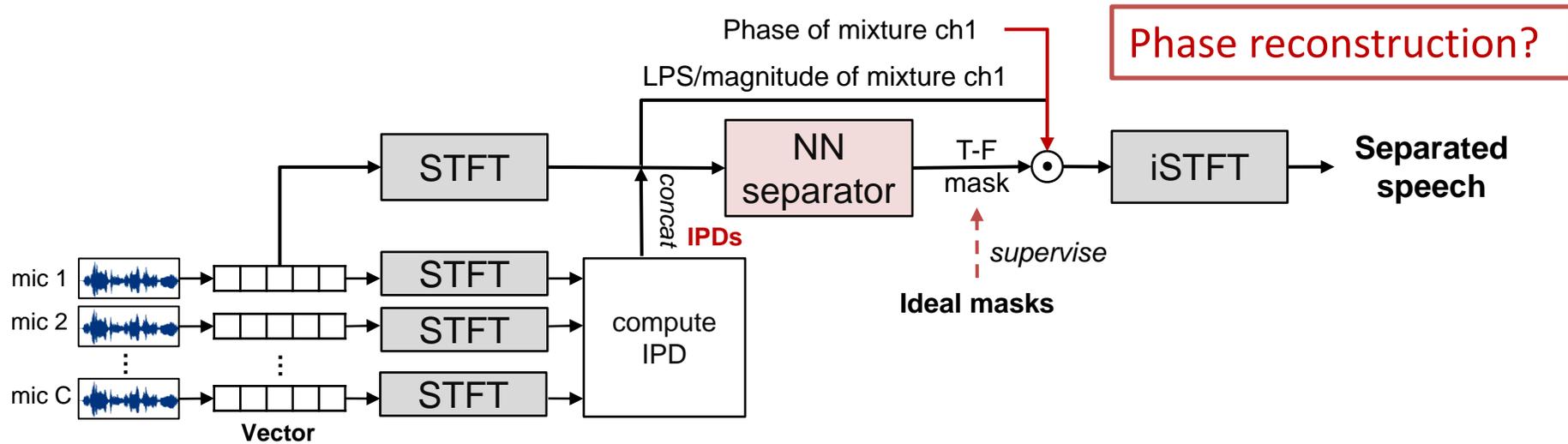


- $\mathbf{y}[n] = [y^I[n], \dots, y^C[n]]^T$ : observed multi-channel mixture signal
- $\mathbf{x}_s[n] = [x_s^I[n], \dots, x_s^C[n]]^T$ : reverberant image for source  $s$

# Methods for multi-channel speech separation

- T-F masking

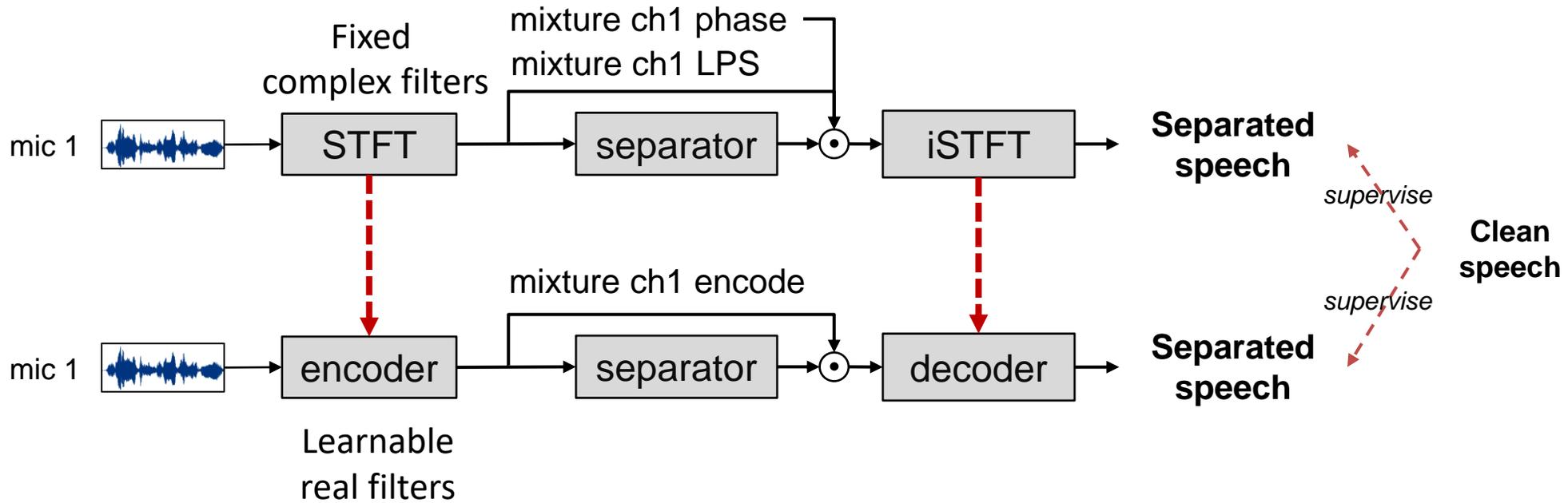
- formulate speech separation as a supervised learning task in frequency domain



- Integration of T-F masking and beamforming
- End-to-end approaches

# Single-channel TasNet

- Encoder-decoder structure

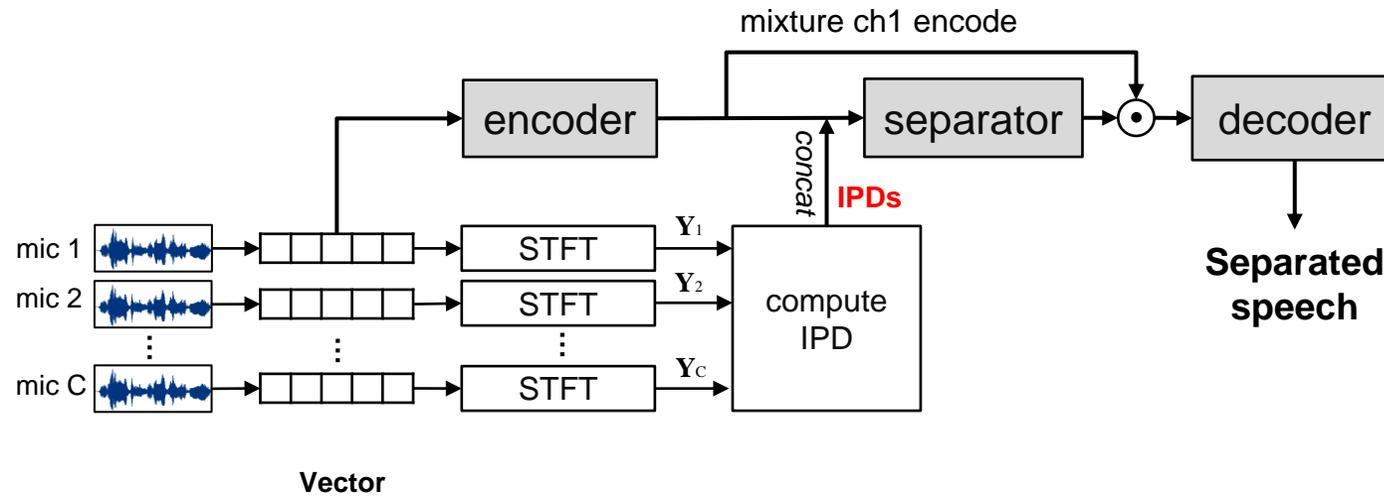


- Unsatisfactory performance under far-field scenario

# Our previous try – Data mismatch

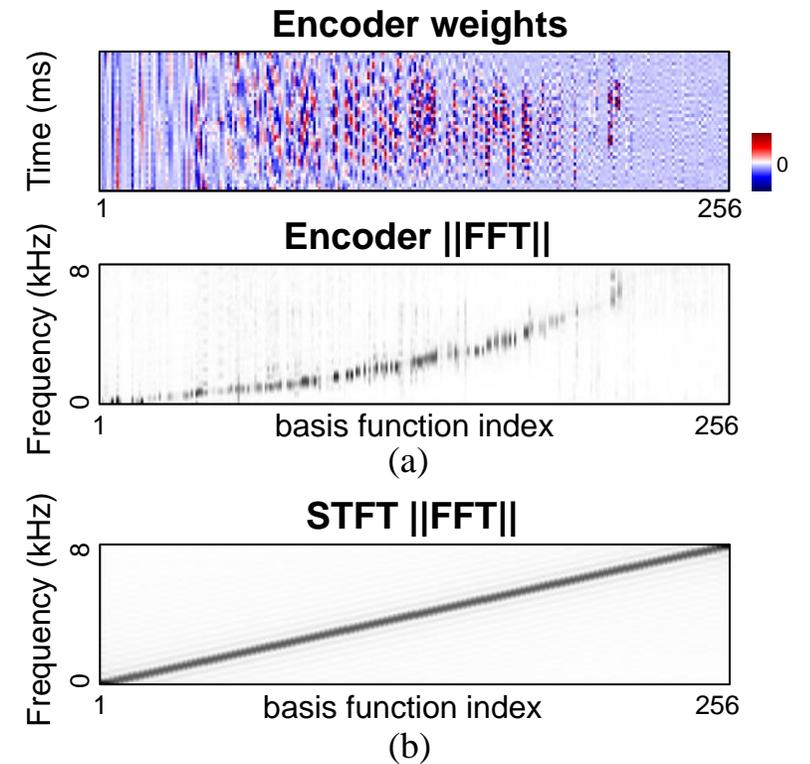
## • A multi-channel speech separation approach:

- encode + IPDs
- a multi-channel speech separation approach

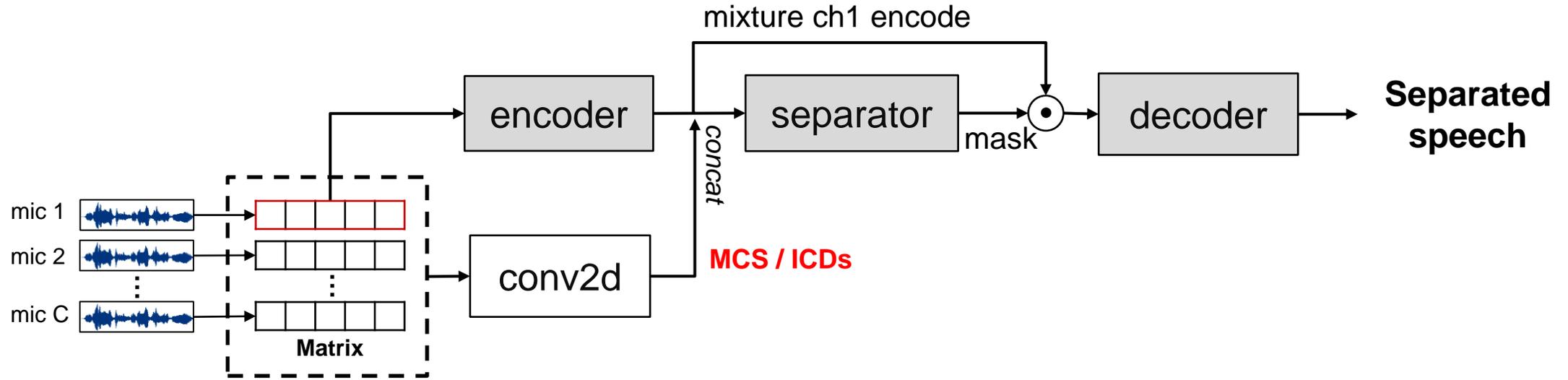


## • Data mismatch: encoder & STFT

- **Encoder**: learned in purely data-driven fashion
- **STFT**: fixed complex filters (with evenly distributed frequency responses)



# Proposed model



- **Aim: an end-to-end multi-channel speech separation model**
  - **Encoder:** transform mixture waveform into the mixture encode
  - **Conv2d:** spatial feature learning
  - **Separator:** estimate a mask in encoder output domain for each speaker
  - **Decoder:** reconstruct the separated speech waveform

# Spatial feature learning – multi-channel convolution sum

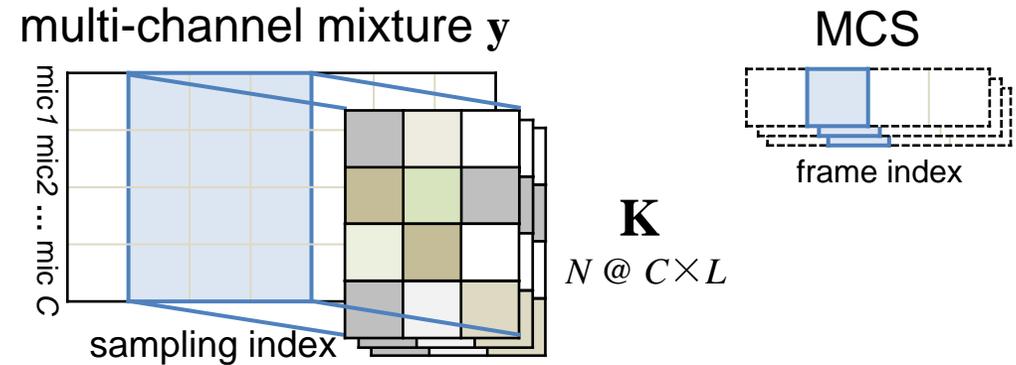
- Main idea:

- learn time-domain filters spanning all signal channels  $\mathbf{K} = \{\mathbf{k}^{(n)}\} \in \mathbb{R}^{C \times L \times N}$  to perform adaptive spatial filtering

- Multi-channel convolution sum (MCS):

$$\text{MCS}^{(n)} = \sum_{c=1}^C \mathbf{y}_c \circledast \mathbf{k}_c^{(n)}$$

- a DAS beamformer-like formation
- Each set of filters  $\mathbf{k}^{(n)}$  is expected to steer at a different direction



- Implementation:

- Conv2d, kernel:  $N @ C \times L$

# Spatial feature learning – inter-channel convolution difference

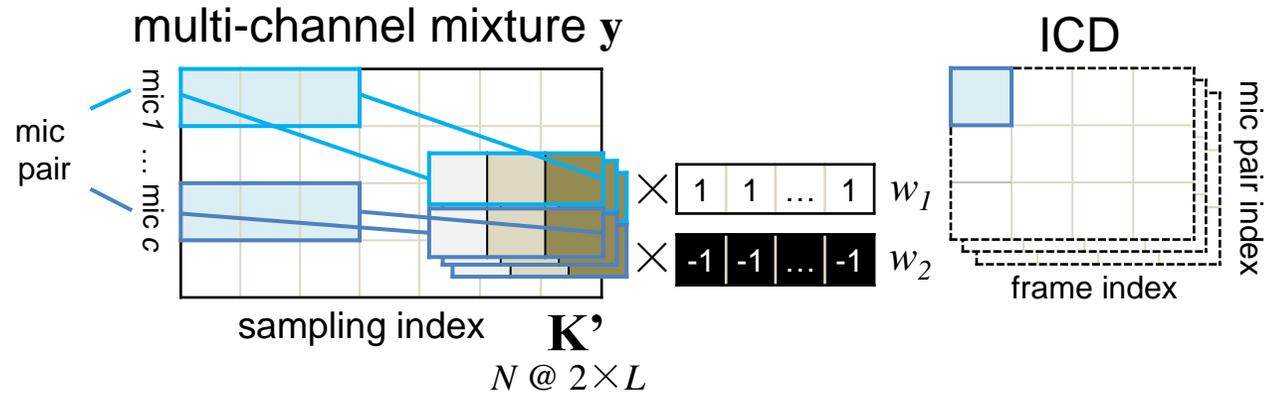
- inspired by IPD formulation:

- T-F bins that dominated by the same source share the same time delay
- IPDs of these T-F bins naturally form a cluster within each frequency band

- Inter-channel convolution difference (ICD)

$$ICD_m^{(n)} = \sum_{c=1}^2 w_c \cdot (\mathbf{y}_{m_c} \otimes k^{(n)})$$

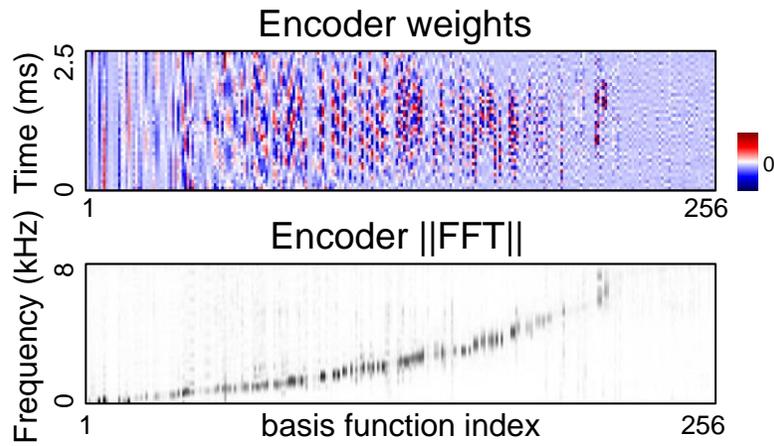
- $m$ : microphone pair index
- $w_c \in \mathbb{R}^{1 \times L}$ : window function
- Initialization:  $w_1 = [1, \dots, 1]$ ,  $w_2 = [-1, \dots, -1]$



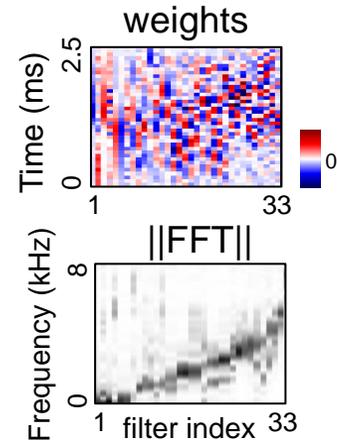
- Implementation:

- A customized conv2d kernel

# Visualization of learned filters



Encoder

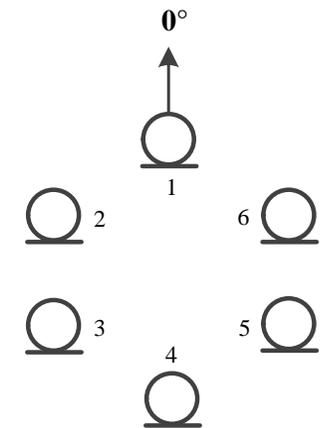


Conv2d kernel  $\mathbf{K}$

# Experiments - Data

- spatialized reverberant WSJ0 2-mix

<b>Train</b>	20000 utterances / 30h / 101 speakers
<b>Validation</b>	8000 utterances / 8h / 101 speakers
<b>Test</b>	5000 utterances / 5h / 18 speakers (unseen)
<b>Sampling rate</b>	16kHz
<b>Mix SNR</b>	[-5, 5] dB
<b>Overlap Ratio</b>	100%
<b>RT60</b>	0.05~0.5s
<b>Microphone array</b>	6-microphone circular array of 7cm diameter
<b>Included angle</b>	0-15: 16%, 15-45: 29%, 45-90: 26%, 90-180: 29%
<b>Selected pairs for IPD/ICD</b>	[1, 4], [2, 5], [3, 6], [1, 2], [3, 4], [5, 6]



# Experiments

- Training objective: SI-SDR

$$\begin{cases} x_{\text{target}} := \frac{\langle \hat{x}, x \rangle x}{\|x\|_2^2} \\ e_{\text{noise}} := \hat{x} - x_{\text{target}} \\ \text{SI-SDR} := 10 \log_{10} \frac{\|x_{\text{target}}\|_2^2}{\|e_{\text{noise}}\|_2^2} \end{cases}$$

- $\hat{x}$ : estimated reverberant speech
- $x$ : ground truth reverberant speech

- Permutation invariant training

- Evaluation Metrics

- SI-SDR improvement
- SDR improvement

## Results – different conv2d configurations

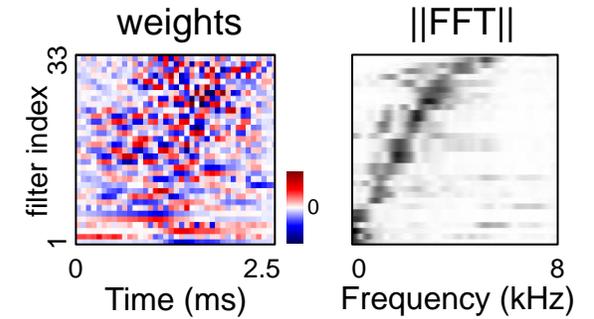
Setup	window $w$	# filters $N$	SI-SDR improvement (dB)				Ave.	SDRi (dB)
			<15	15-45	45-90	>90		
Single-channel Conv-TasNet	-	-	8.5	9.0	9.1	9.3	9.1	9.4
+ MCS (conv2d ( $6 \times 40$ ))	-	256	5.7	10.3	11.9	12.9	10.8	11.2
+ ICD (conv2d ( $2 \times 40$ ))	fix -1	256	5.5	10.9	12.3	12.9	11.0	11.4
+ ICD (conv2d ( $2 \times 40$ ))	init. -1	256	6.2	11.2	12.6	13.2	11.4	11.8
+ ICD (conv2d ( $2 \times 40$ ))	init. randomly	33	8.2	8.1	9.0	9.1	8.9	9.2
+ ICD (conv2d ( $2 \times 40$ ))	fix -1	33	6.9	11.1	12.3	12.9	11.3	11.7
+ ICD (conv2d ( $2 \times 40$ ))	init. -1	33	6.7	11.7	13.1	13.9	11.9	12.3

- The performances with 33 filters are relatively superior to those with 256 filters.
- The value of  $w$  contributes significantly to the separation performance
  - Init randomly: no subtraction operation
  - Fix -1: exact inter-channel convolution difference
  - Init -1: initialize  $w$  as -1 and set  $w$  learnable during training

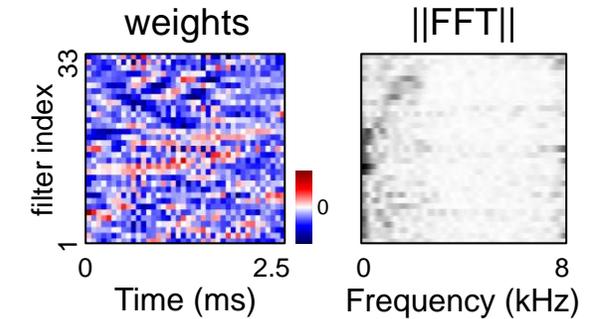
# Results – IPD vs ICD

Setup	SI-SDR improvement (dB)		
	<15°	>15°	average
cosIPD, sinIPD	7.7	12.2	11.5
cosIPD, sinIPD (trainable kernel)	7.9	12.3	11.6
ICD	6.7	12.9	11.9
ICD, cosIPD, sinIPD	8.1	13.2	12.4

- IPD provide beneficial spatial information of sources and help the multi-channel speech separation.
- With the trainable kernel, the performance improves slightly.
- ICD based separation model obtains 0.4dB improvement over cosIPD+sinIPD based
- The incorporation of ICDs and IPDs achieves further 0.5dB improvement.



Learned filters K' (ICD)



Learned filters K' (ICD+cosIPD+sinIPD)

# Conclusions

- **This work proposes an end-to-end multi-channel speech separation model**
  - learn effective spatial cues directly from the multi-channel speech waveforms
  - end-to-end optimization in a purely data-driven fashion
- **The learned spatial features**
  - can be computed with few parameters and computation cost
  - can be combined with well-designed IPDs and obtain better results

Thank you!

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Thank you!  
Q&A