Estimating Centrality Blindly from Low-pass Filtered Graph Signals

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Motivation



Tonnage on Highways, Railroads and Inland Waterways: 2002

[Source: Wikipedia]

Graphs are useful for describing the geometric structures of data from numerous fields, including social, energy, transportation, and neuronal networks.

Motivation



[Source: Wikipedia]

- Importance of nodes in the graph => node centrality
- E.g., social network most influential individuals, transport network – cities with largest population mobility.

Research Question: Can we learn node centrality from data?

Prior works

Graph learning: recover the complete topology

- Statistical/physical models GMRF [Friedman et al., 2008], dynamical systems / causation [Shen et al., 2017].
- Graph signal processing (GSP) models smoothness of graph signals [Dong et al., 2016], inference with structural constraints [Egilmez et al., 2017], spectral template [Segarra et al., 2017].
- and many others...

This work: learning graph features without the graph

- Community inference blind community detection [Wai et al., 2018], Bayesian learning [Hoffmann et al., 2018], recovery from multi-graph [Roddenberry et al., 2020].
- Centrality learning centrality ranking inference [Roddenberry and Segarra, 2019], and this work.

Contribution

- We show that the folklore heuristic based on PCA works if data is generated from a 'strong' low-pass filter.
- For data generated from a 'weak' low-pass filter, we propose a boosting method with provably better estimation quality.

Numerical experiments on synthetic and stocks data.

Graph Model and Centrality Measure

- ► Undirected graph $G = (V, E, \mathbf{A})$ with $V = \{1, ..., N\}$, symmetrix adjacency matrix $\mathbf{A} \in \mathfrak{R}_+^{N \times N}$
- The adjacency matrix admits an eigenvalue decomposition (EVD) as A = VΛV^T s.t. V = orthogonal, Λ = Diag(λ₁, ..., λ_N).
- Centrality is given by the eigen-centrality

$$c_{\mathsf{eig}} := \mathsf{TopEV}(\mathbf{A}) = \mathbf{v}_1$$



Graph Signal Model

Observed data y^t is produced by an excitation x^t to be 'processed' by a graph filter H(A)

$$y^t = \mathcal{H}(\mathbf{A})x^t$$



Graph Signal Model (cont'd)

Graph Filter

The graph filter H(A) is a matrix polynomial:

 $\mathcal{H}(\mathbf{A}) = \sum_{t=0}^{T-1} h_t \mathbf{A}^t$

Set $h(\lambda) := \sum_{t=0}^{T-1} h_t \lambda^t$.

Assume 1-low pass H(A):

$$\max_{j=2,...,N} |h(\lambda_j)| / |h(\lambda_1)| =: \eta < 1$$

- $\eta \ll 1 \Longrightarrow$ strong low-pass. $\eta \approx 1 \Longrightarrow$ weak low-pass.
- E.g., diffusion, op. dynamics.

Excitation Signal

The input x^t is controlled by an external source z^t:

 $x^t = \mathbf{B}z^t$

- Assume a sparse influence matrix
 B ∈ ℜ^{N×k}, (k < N).
- E.g., influence from external source z^t are localized to specific nodes on graph.

Blind centrality estimation

Idea: apply PCA on the covariance of filtered graph signals, use the principal eigenvector as an estimate for c_{eig}



Blind centrality estimation

$$C_{y} = \mathcal{H}(\mathbf{A})\mathbf{B}\mathbf{B}^{\mathsf{T}}(\mathcal{H}(\mathbf{A}))^{\mathsf{T}} = \mathbf{V} \begin{bmatrix} {}^{h(\lambda_{1})} \\ & \\ & \\ {}^{h(\lambda_{N})} \end{bmatrix} \mathbf{V}^{\mathsf{T}}\mathbf{B}\mathbf{B}^{\mathsf{T}}\mathbf{V} \begin{bmatrix} {}^{h(\lambda_{1})} \\ & \\ & \\ {}^{h(\lambda_{N})} \end{bmatrix} \mathbf{V}^{\mathsf{T}}$$
(for 'strong' low pass filter) $\approx \text{const} \cdot \mathbf{V}_{1}\mathbf{V}_{1}^{\mathsf{T}}$

Lemma Suppose $h(\lambda_1) > \max_{j=2,...,n} h(\lambda_j)$. Then it holds that $\|c_{eig} - \hat{v}_1\|_2 = O(\frac{\max_{j=2,...,n} |h(\lambda_j)|}{|h(\lambda_1)|}) = O(\eta)$

Centrality estimation may be inaccurate for 'weak' low pass filter (i.e., η ≈ 1).

Boosted centrality estimation

- A simple modification to strengthen the low-pass filter.
- ▶ Let *ρ* > 0. Consider

$$\widetilde{\mathcal{H}}(\mathbf{A}) := \mathcal{H}(\mathbf{A}) - \rho \mathbf{I}, \quad \widetilde{h}_{\rho}(\lambda) := h(\lambda) - \rho.$$

• Let $\mu := \frac{\max_{j=2,\dots,n} |\lambda_j|}{|\lambda_1|}$

Observation: there exists p > 0 such that

$$\frac{\max_{j=2,\dots,n}|\tilde{h}_{\rho}(\lambda_{j})|}{|\tilde{h}_{\rho}(\lambda_{1})|} = O(\frac{\max_{j=2,\dots,n}|\lambda_{j}|}{|\lambda_{1}|}\frac{\max_{j=2,\dots,n}|h(\lambda_{j})|}{|h(\lambda_{1})|}) = O(\mu\eta)$$

• $\widetilde{\mathcal{H}}(\mathbf{A})$ has a better low-pass condition than $\mathcal{H}(\mathbf{A})$.

Boosted centrality estimation

- ► Assume the external signals $Z \in \Re^{k \times M}(k < M)$ are known, $\mathcal{H}(A)B =: \widehat{HB} = YZ^{T}(ZZ^{T})^{-1}$
- $\mathcal{H}(\mathbf{A})\mathbf{B}$ admits a low-rank + sparse decomposition as:

$$\mathcal{H}(\mathbf{A})\mathbf{B} = \widetilde{\mathcal{H}}(\mathbf{A})\mathbf{B} + \rho\mathbf{B} \equiv \mathbf{L} + \mathbf{S}$$

- L is a low-rank matrix and S is a sparse matrix.
- To obtain L, we solve the convex problem:

$$\min_{\hat{\mathbf{L}},\hat{\mathbf{S}}} \|\widehat{\mathbf{HB}} - \hat{\mathbf{L}} - \hat{\mathbf{S}}\|_{F}^{2} + \lambda_{L} \|\hat{\mathbf{L}}\|_{\star} + \lambda_{S} \|\operatorname{vec}(\hat{\mathbf{S}})\|_{1}$$

where λ_L , λ_S – regularization for low-rankness, sparseness.

The whole process:



Corollary

Let \tilde{v}_1 be the top left singular vector of **L**. Under the same conditions as the previous Lemma. It holds

$$\|\boldsymbol{c}_{\textit{eig}} - \widetilde{\boldsymbol{v}}_1\|_2 = O(\frac{\max_{j=2,...,n}|\lambda_j|}{|\lambda_1|}\frac{\max_{j=2,...,n}|\boldsymbol{h}(\lambda_j)|}{|\boldsymbol{h}(\lambda_1)|}) = O(\mu\eta)$$

Numerical Results

• Graph G: Core periphery model with connectivity p = 0.05

- N = 100 nodes (10 core nodes), M = 10⁵ observations
- Graph filter: $\mathcal{H}(\mathbf{A}) = (\mathbf{I} 0.1\mathbf{A})^{-1}, \lambda_L = 0.1, \lambda_S = 0.2 + \frac{2}{\sqrt{k}}.$

Three settings of B for different locations of external sources (black - central, blue - regular, red - external):



Numerical Results



- $\widehat{\mathbf{S}}^{\text{thres}} = \mathbf{1}(\widehat{\mathbf{S}} \ge 0.1) \odot \widehat{\mathbf{S}}$ and replace $\widehat{\mathbf{L}}$ with $\widehat{\mathbf{HB}} \widehat{\mathbf{S}}^{\text{thres}}$.
- Error rate = $\mathbb{E}\left[\frac{1}{10}|\{1, ..., 10\} \cap \tilde{v}_1|\right]$
- PCA suffers from a higher error rate than the robust methods.
- The error rate for the robust methods decreases with k.
- Results are consistent with our theoretical analysis

Real data

- Data: daily return data from S&P100 stocks in May 2018 to Aug 2019, consisting of n = 99 stocks and m = 300 samples, collected from https://alphavantage.co.
- External source: the latent input z^t on the relevant days estimated from the *interest level* on Google Trend (https://trends.google.com) on k = 5 key words: 'trade war', 'sales tax', 'Iran', 'oil crisis' and 'election'.

Method: Robust Estimation with Quantization

Real data

Estimated most influenced stocks:

PCA:





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Real data

Estimated most affected areas:



Summary

PCA works if the related filter is 'strong' low-pass.

- With 'weak' low-pass filter, **boosting** method is applied.
- Numerical experiments on synthetic and stocks data.

Future Question: Can we learn node centrality from data without knowing external sources?

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