## Continual Learning through One-Class Classification using VAE ICASSP 2020 paper by Felix Wiewel, Andreas Brendle and Bin Yang



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Continual Learning One-Class Classification

## Proposed Method

## Experiments

Data sets Architecture & Training Results

## Conclusion

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## **Continual Learning**



- Goal
  - Train a DNN on sequence of tasks
- Restriction
  - Only data of most recent task available
- Challenges
  - Catastrophic forgetting [Fre99]
  - Knowledge transfer
  - Model size
- Methods
  - $\Box$  Regularization [ZPG17, KPR<sup>+</sup>17]
  - □ Structural [YYLH18]
  - □ Rehearsal [SLKK17, LP<sup>+</sup>17, vdVT18]
  - Bayesian [NLBT18]



## Figure: Training on a sequence of tasks

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One-Class Classifier [MH96]

- Distinguish target class vs others
- Within-class generalization
- Between-class generalization
- Out-of-class generalization
- Approaches
  - Density based
  - Boundary methods
  - Reconstruction based [AC15, XCZ<sup>+</sup>18, KKH18, SCKC16]

• Target class  $\Rightarrow \diamond \bullet >$  Other classes



Figure: One-Class Classification example

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- Basic idea
  - $\hfill\square$  Interpret CL as series of OCC problems
  - $\hfill\square$  Use generative model to build memory
  - $\hfill\square$  Share latent space
- Realization
  - $\hfill\square$  VAE for OCC of every class
  - Shared encoder
  - Generative replay using learned decoders



Figure: Proposed method structure

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## **Proposed Method**

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- General formulation using
  - $\ \square$  Shared encoder  ${oldsymbol{\Phi}}$
  - $\ \square$  Class specific decoders  $oldsymbol{\Psi}^i$
  - $\hfill\square$  Supervised loss  ${\cal L}$
  - $\hfill\square$  Regularization  ${\mathcal R}$  against catastrophic forgetting

$$\max_{\boldsymbol{\Phi}, \boldsymbol{\Psi}^1, \dots \boldsymbol{\Psi}^M} \ \mathcal{L}(\boldsymbol{\Phi}, \boldsymbol{\Psi}^1, \dots \boldsymbol{\Psi}^M) + \mathcal{R}(\boldsymbol{\Phi})$$
(1)



- Formulation using VAE
  - $\ \square$  Shared encoder  $oldsymbol{\Phi}$
  - $\square$  Class specific decoders  $oldsymbol{\Psi}^i$
  - $\Box \text{ Evidence lower bound (ELBO), i.e. } \mathbb{E}_{p_{\mathbf{x}}} \left[ \mathbb{E}_{q_{\boldsymbol{\varPhi}}} \left[ \ln p_{\boldsymbol{\varPsi}}(\mathbf{x} | \mathbf{z}) \right] \mathrm{D}(q_{\boldsymbol{\varPhi}} \parallel p_{\mathbf{z}}) \right]$

$$\max_{\boldsymbol{\varPhi}, \boldsymbol{\varPsi}^{1}, \dots \boldsymbol{\varPsi}^{M}} \sum_{m=1}^{M} \mathbb{E}_{p_{\mathbf{x}}^{m}} \left[ \mathbb{E}_{q_{\boldsymbol{\varPhi}}} \left[ \ln p_{\boldsymbol{\varPsi}^{m}}(\mathbf{x} | \mathbf{z}) \right] - \mathrm{D}(q_{\boldsymbol{\varPhi}} \parallel p_{\mathbf{z}}^{m}) \right] \\ + \sum_{n=1}^{N} \mathbb{E}_{p_{\mathbf{x}}^{n}} \left[ \mathbb{E}_{q_{\boldsymbol{\varPhi}}} \left[ \ln p_{\boldsymbol{\varPsi}_{s}^{n}}(\mathbf{x} | \mathbf{z}) \right] - \mathrm{D}(q_{\boldsymbol{\varPhi}} \parallel p_{\mathbf{z}}^{n}) \right]$$
(2)

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## **Proposed Method**

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- What prior distribution  $p_{\mathbf{z}}$  to use?
  - $\hfill\square$  Commonly a Gaussian is used for VAE
  - $\hfill\square$  Each class is assigned one prior  $p_{\mathbf{z}}^m$
  - $\hfill\square$  Means  $\pmb{\mu}_m$  are chosen such that  $\|\pmb{\mu}_m-\pmb{\mu}_n\|_2=c\;\forall\;m\neq n$



Figure: Prior placement for individual classes



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## Data sets



## SplitMNIST

- $\square$  Based on MNIST:  $\mathbf{x} \in \mathbb{R}^{28 \times 28}$ ,  $y \in \{0, \dots, 9\}$
- $\hfill\square$  60000 training and 10000 test examples
- Split into ten tasks containing only one class

# 0123456789

## Figure: MNIST examples

- SplitFashionMNIST
  - $\square$  Based on Fashion MNIST:  $\mathbf{x} \in \mathbb{R}^{28 imes 28}$ ,  $y \in \{0, \dots, 9\}$
  - $\hfill\square$  60000 training and 10000 test examples
  - $\hfill\square$  Split into ten tasks containing only one class



Figure: Fashion MNIST examples

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- Shared encoder
  - $\hfill\square$  Densely connected
  - $\ \ \, \square \ \ \, 400,300,200,100,10/10 \text{ Neurons}$
  - $\hfill\square$  ReLU, linear and softplus activation
- Class specific decoders
  - $\hfill\square$  One densely connected layer
  - □ 49 ReLU activated neurons
  - Convolutional layers
  - $\hfill 16, 32, 1$  filters with  $3\times 3$  kernel
  - $\hfill\square$  ReLU and Sigmoid activation
  - Bilinear upsampling after conv. layer

- Optimizer
  - RMSprop
- Learning rate □ 0.001
- Batch size
  - $\Box$  128
- Reporting
  - $\hfill\square$  Avg. and Std. over ten runs
- Threshold estimation
  - $\hfill\square$  On training data only

$$\neg \gamma^n = \mu_{ELBO}^n - 6\sigma_{ELBO}^n$$

Results





Figure: Comparison of proposed method for incrementally learning all classes in MNIST and FashionMNIST data sets with upper bound (UB), lower bound (LB) and base line (BL).

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## Results





Table: Accuracy on data sets after learning all classes.

Method	splitMNIST [%]	splitFashionMNIST [%]
SI	$19.67 \pm 0.29$ [HLK18]	-
EWC	$19.80 \pm 0.05$ [HLK18]	$15.96 \pm 4.86$
DGR	$91.24 \pm 0.33$ [HLK18]	$72.84 \pm 3.03$
RtF	$92.56 \pm 0.21$ [HLK18]	$75.21 \pm 2.42$
Ours	$96.39 \pm 0.23$	$79.38 \pm 0.69$

Figure: Classification accuracy on seen (splitM-NIST) and detection of unseen (Fashion-MNIST) classes during ICL.

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## Conclusion



- New method for CL based on OCC
- Multi-class classification as series of OCC problems
- CL is enabled through generative replay
- Results competitive on common benchmarks
- Our method detects unknown classes

## Thank you for your attention!

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