

On the frequency domain detection of high dimensional time series

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Introduction - Setting

M-dimensional complex time series $(\mathbf{y}_n)_{n \in \mathbb{Z}}$ modeled as

$$\mathbf{y}_n = \underbrace{\sum_{k=0}^{+\infty} \mathbf{H}_k \epsilon_{n-k}}_{=\mathbf{u}_n} + \mathbf{v}_n \in \mathbb{C}^M$$

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Frequency domain detection hypothesis test - \mathbf{S}_y

$\mathcal{H}_0 : \mathbf{S}_y(\nu) = \text{diag}(\mathbf{S}_y(\nu)) = \mathbf{S}_v(\nu)$ (noise only) vs

$\mathcal{H}_1 : \mathbf{S}_y(\nu) = \mathbf{H}(\nu)\mathbf{H}(\nu)^* + \mathbf{S}_v(\nu) \neq \text{diag}(\mathbf{S}_y(\nu))$ (signal+noise)

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($\mathbf{H}(\nu)$ is the Fourier transform of $(\mathbf{H}_k)_k$)

With $\mathbf{C}_y(\nu) := \text{diag}(\mathbf{S}_y(\nu))^{-\frac{1}{2}} \mathbf{S}_y(\nu) \text{diag}(\mathbf{S}_y(\nu))^{-\frac{1}{2}}$

Frequency domain detection hypothesis test - \mathbf{C}_y

\mathcal{H}_0 : $\mathbf{C}_y = \mathbf{I}_M$ (pure noise) vs \mathcal{H}_1 : $\mathbf{C}_y \neq \mathbf{I}_M$ (signal + noise). Use frequency domain estimators of \mathbf{C}_y to test if $\mathbf{u}_n = 0$.

Introduction - Signal detection context

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- finite $K \times \mathcal{O}(1)$ signal eigenvalues vs $M \times \mathcal{O}(1)$ noise eigenvalues
- SNR $\rho = \frac{\mathbb{E}\|\mathbf{u}_n\|^2}{\mathbb{E}\|\mathbf{v}_n\|^2} = \mathcal{O}\left(\frac{1}{M}\right)$ is of special interest.

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- Considerable work still needed for **dynamic / wideband models**
- Temporal approaches also possible, but frequency ones turns out to be simpler.

Introduction - Notations & Smoothed periodogram estimator

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Smoothed periodogram estimator of the spectral density matrix :

$$\hat{\mathbf{S}}_y(\nu) = \frac{1}{B+1} \sum_{b=-B/2}^{B/2} \xi_y\left(\nu + \frac{b}{N}\right) \xi_y\left(\nu + \frac{b}{N}\right)^* \quad (B : \text{smoothing span})$$

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Estimator of the spectral coherency matrix :

$$\hat{\mathbf{C}}_y(\nu) = \text{diag}(\hat{\mathbf{S}}_y(\nu))^{-\frac{1}{2}} \hat{\mathbf{S}}_y(\nu) \text{diag}(\hat{\mathbf{S}}_y(\nu))^{-\frac{1}{2}}$$

Main result on \hat{C}_y

High dimensional regime : consider $B := B(N)$, $M := M(N)$ such that

$$M, B, N \xrightarrow{N \rightarrow \infty} +\infty, \quad \frac{B}{N} \xrightarrow{N \rightarrow \infty} 0, \quad \frac{M}{B} \xrightarrow{N \rightarrow \infty} c \in (0, 1)$$

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Theorem - Wishart approximation of $\hat{\mathbf{C}}_y$

Under proper technical assumptions on the signal and noise, there exists a $M \times (B + 1)$ random matrix $\mathbf{X}(\nu)$ with i.i.d. $\mathcal{N}_{\mathbb{C}}(0, 1)$ entries such that

$$\max_{\nu \in \mathcal{V}_N} \left\| \hat{\mathbf{C}}_y(\nu) - \Xi(\nu)^{\frac{1}{2}} \frac{\mathbf{X}(\nu)\mathbf{X}(\nu)^*}{B+1} \Xi(\nu)^{\frac{1}{2}} \right\| \xrightarrow[N \rightarrow \infty]{a.s.} 0 \quad (1)$$

where $\Xi(\nu) = \underbrace{\mathbf{S}_v(\nu)^{-\frac{1}{2}} \mathbf{H}(\nu)\mathbf{H}(\nu)^* \mathbf{S}_v(\nu)^{-\frac{1}{2}}}_{\text{rank } K < M} + \mathbf{I}_M$ and $\mathbf{H}(\nu) := \sum_{k=0}^{+\infty} \mathbf{H}_k e^{-i2\pi\nu k}$

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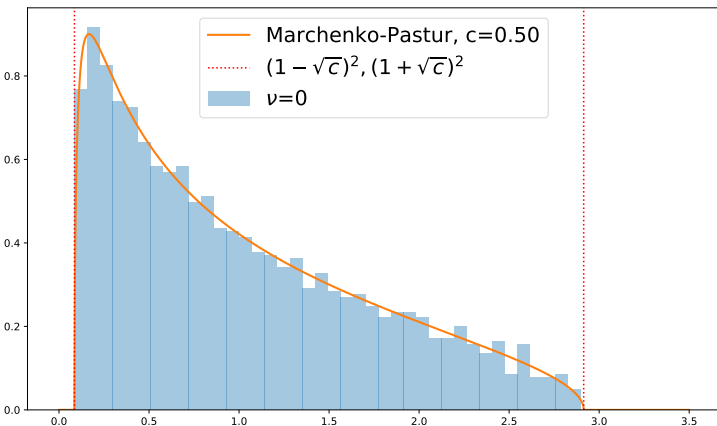
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Key idea :

- $\Xi(\nu)$ **fixed rank K perturbation of the identity matrix**. This is not the case with temporal approaches.
- first order behaviour of $\Xi(\nu)^{\frac{1}{2}} \frac{\mathbf{X}(\nu)\mathbf{X}(\nu)^*}{B+1} \Xi(\nu)^{\frac{1}{2}}$ known.

Simulation in the pure noise case ($K = 0$)

- $K = 0$ ($\mathbf{y}_n = \mathbf{v}_n$ as MA(1)), $M = 100$, $B = 200$, $N = 4000$
- asymptotically, eigenvalues of $\hat{\mathbf{C}}_{\mathbf{y}}(\nu) \in [(1 - \sqrt{c})^2, (1 + \sqrt{c})^2]$ (Marchenko & Pastur, 1967)
- good fit even for small dimensions (20 realisations)



Application - Spectral behaviour of \hat{C}_y

Recall $\Xi(\nu) = \mathbf{S}_v(\nu)^{-\frac{1}{2}} \mathbf{H}(\nu) \mathbf{H}(\nu)^* \mathbf{S}_v(\nu)^{-\frac{1}{2}} + \mathbf{I}_M \in \mathbb{C}^{M \times M}$, rank K .

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Define $\nu_N^* \in \mathcal{V}_N$ such that :

$$\nu_N^* \in \operatorname{argmax}_{\nu \in \mathcal{V}_N} \lambda_1 \left(\mathbf{S}_v(\nu)^{-\frac{1}{2}} \mathbf{H}(\nu) \mathbf{H}(\nu)^* \mathbf{S}_v(\nu)^{-\frac{1}{2}} \right)$$

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Assumption - Spike

For all $k \in \{1, \dots, K\}$, there exists $\gamma_k > 0$ such that

$$\lambda_k \left(\mathbf{S}_v(\nu_N^*)^{-\frac{1}{2}} \mathbf{H}(\nu_N^*) \mathbf{H}(\nu_N^*)^* \mathbf{S}_v(\nu_N^*)^{-\frac{1}{2}} \right) \xrightarrow{N \rightarrow \infty} \gamma_k$$

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Corollary - Behaviour of the spectrum of $\hat{\mathbf{C}}_y(\nu)$

Under proper technical assumptions, for all $k = 1, \dots, K$ and all $\nu \in \mathcal{V}_N$,

$$\lambda_k \left(\hat{\mathbf{C}}_y(\nu_N^*) \right) \xrightarrow{N \rightarrow \infty} \begin{cases} \frac{(\gamma_k + 1)(\gamma_k + c)}{\gamma_k} > (1 + \sqrt{c})^2 & \text{if } \gamma_k > \sqrt{c} \\ (1 + \sqrt{c})^2 & \text{if } \gamma_k \leq \sqrt{c} \end{cases}$$

whereas

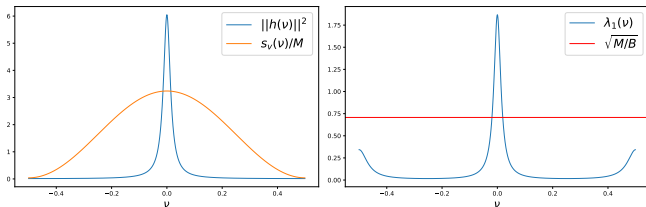
$$\lambda_{K+1} \left(\hat{\mathbf{C}}_y(\nu_N^*) \right) \xrightarrow{N \rightarrow \infty} (1 + \sqrt{c})^2$$

Application - Spectral behaviour of $\hat{\mathbf{C}}_y$ - Simulation

- rank one signal ($\mathbf{h}(\nu)$ vector) + M -dimensional noise MA(1) process.
- $K=1$, same $M = 100$, $B = 200$, $N = 4000$, $c = 0.5 \implies \sqrt{c} \approx 0.7$
- separation starting at $SNR := \gamma_1 = \sqrt{c} \implies$ detection for low frequencies

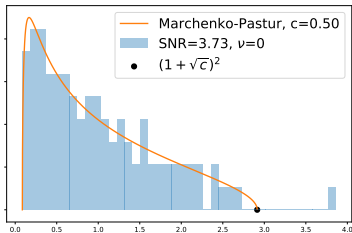
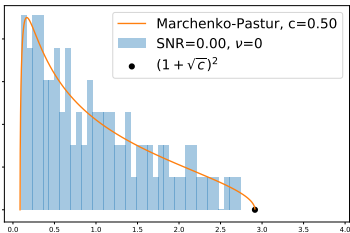
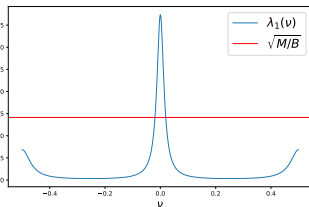
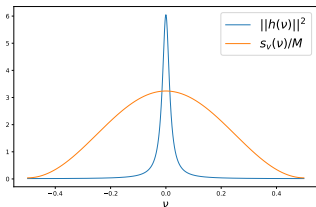
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Application - Simulation - Varying parameters

- $M = 20, B = 40, N = 4000, c = 0.5$, ma parameter = 0.6, medium SNR.
- as $\frac{B}{N} \rightarrow 0$, the finite sample results are closer to the asymptotics

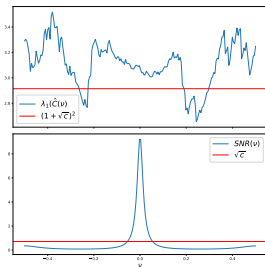


FIGURE - $B/N = 0.5$

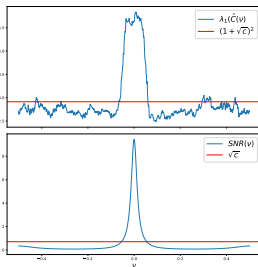


FIGURE - $B/N = 0.1$

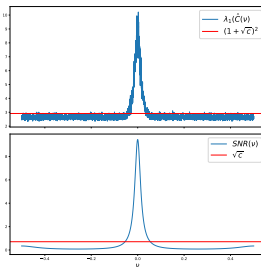


FIGURE - $B/N = 0.01$

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New frequency domain detection algorithm

Consider, for some threshold $\epsilon > 0$ the following procedure :

$$\begin{cases} \lambda_1(\hat{\mathbf{C}}_{\mathbf{y}}(\nu_N^*)) < (1 + \sqrt{\epsilon})^2 + \epsilon & \text{absence of } u \text{ is decided} \\ \lambda_1(\hat{\mathbf{C}}_{\mathbf{y}}(\nu_N^*)) > (1 + \sqrt{\epsilon})^2 + \epsilon & \text{presence of } u \text{ is decided} \end{cases}$$

This leads to define the test statistics :

$$T_{\epsilon} = \mathbb{1}_{((1+\sqrt{\epsilon})^2+\epsilon, +\infty)} \left(\max_{\nu \in \mathcal{V}_N} \left\| \hat{\mathbf{C}}_{\mathbf{y}}(\nu) \right\| \right)$$

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Theorem - Spectral detection testing

Under proper assumptions, the previous test is consistent iff $\gamma_1 > \sqrt{c}$ and ϵ small enough.

Conclusion

Contributions :

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- Well known results provide first order behaviour of its eigenvalues
- Our detection algorithm is based on a phase transition phenomenon of the largest eigenvalues of $\hat{C}_y(\nu)$:
 - weak energy signals \implies eigenvalue absorbed in the noise bulk
 - high energy signals \implies eigenvalue separated from the noise bulk