

Translation of a Higher Order Ambisonics Sound Scene Based on Parametric Decomposition

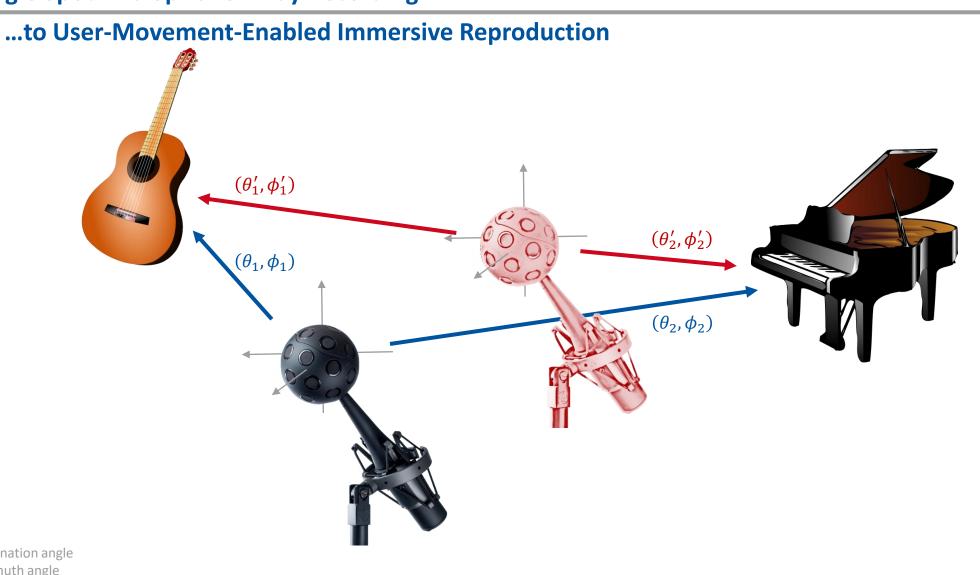
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IEEE ICASSP 2020





From Single Spot Microphone Array Recording...



 θ inclination angle

 ϕ azimuth angle

2

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Signal Model

■ Higher Order Ambisonics (HOA) signal $x(\lambda, \mu) \in \mathbb{C}^{(N+1)^2}$ with Spherical Harmonics truncation order N:

 $\boldsymbol{x}(\lambda,\mu) = \boldsymbol{x}_{s}(\lambda,\mu) + \boldsymbol{x}_{a}(\lambda,\mu)$

 λ : frame index μ : frequency bin

- **Direct part** $x_s(\lambda, \mu)$: variable number of $I(\lambda, \mu) \in \{0, 1, 2, ..., (N + 1)^2\}$ plane wave sources:

$$\boldsymbol{x}_{s}(\lambda,\mu) = \underbrace{\left[\boldsymbol{y}(\theta_{1},\phi_{2}) \mid \dots \mid \boldsymbol{y}(\theta_{I(\lambda,\mu)},\phi_{I(\lambda,\mu)}) \right]}_{= \operatorname{array manifold matrix} \boldsymbol{Y}_{s}} \cdot \begin{pmatrix} \boldsymbol{s}_{1}(\lambda,\mu) \\ \vdots \\ \boldsymbol{s}_{I(\lambda,\mu)}(\lambda,\mu) \end{pmatrix}$$

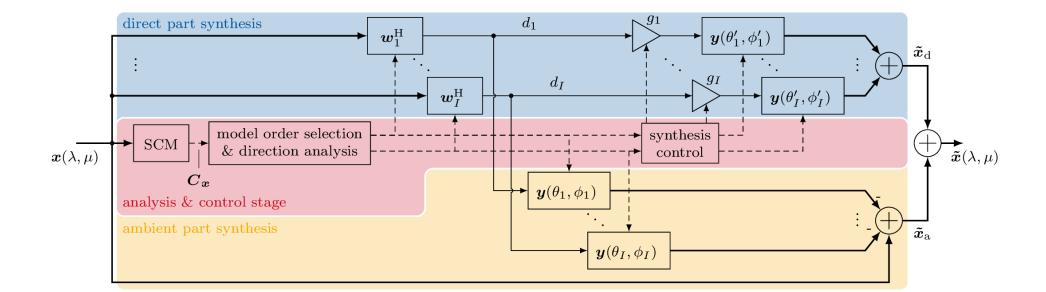
- **Ambient part** $x_a(\lambda, \mu)$: spatially diffuse
- Spatial covariance matrix (SCM):

 $C_{\boldsymbol{x}}(\lambda,\mu) = \mathrm{E}\{\boldsymbol{x}(\lambda,\mu)\boldsymbol{x}^{H}(\lambda,\mu)\}$ $= \mathrm{E}\{\boldsymbol{x}_{S}(\lambda,\mu)\boldsymbol{x}_{S}^{H}(\lambda,\mu)\} + \mathrm{diag}(\boldsymbol{\sigma}_{a}^{2})$





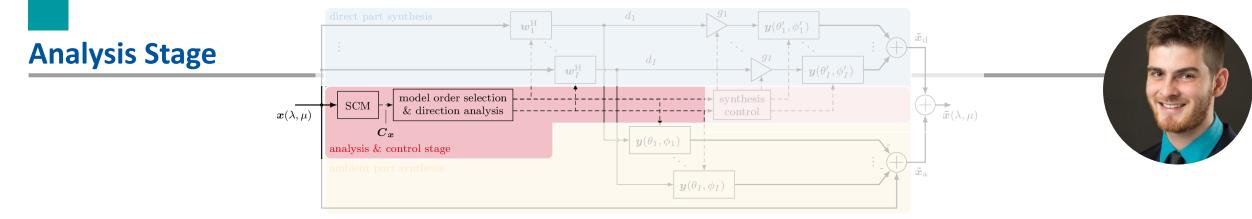




- SCM Estimation of Spatial Covariance Matrix
- (θ, ϕ) Angles: (inclination, azimuth)
- λ Frame index
- μ Frequency index
- *w_i* Beamforming weights
- $y(\theta, \phi)$ Vector of Spherical Harmonics evaluated at (θ, ϕ)



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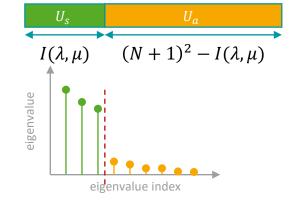
Segregation into multiple direct time-frequency components & ambient residuum

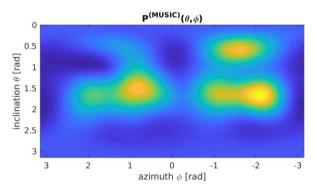
Variant 1: Subspace approach using SORTE & MUSIC

Adopted from [Politis, Tervo & Pulkki, ICASSP'18]

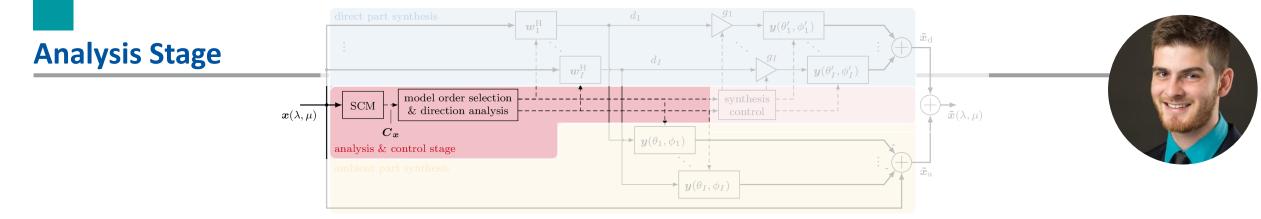
- Use eigenvalue decomposition to segregate $C_x(\lambda, \mu)$ into
 - direct components subspace $U_s(\lambda, \mu)$
 - residual subspace $U_a(\lambda, \mu)$
- Model order selection: determine number $I(\lambda, \mu)$
 - find gap in eigenvalue sequence using second-order statistic of the eigenvalues (SORTE)
- Use MUSIC to find $I(\lambda, \mu)$ source directions which are local maxima in

$$P^{(\text{MUSIC})}(\theta, \phi) = \frac{1}{\|\mathbf{y}^{H}(\theta, \phi)\mathbf{U}_{a}\|_{2}^{2}}$$







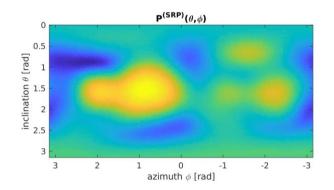


Segregation into multiple direct time-frequency components & ambient residuum

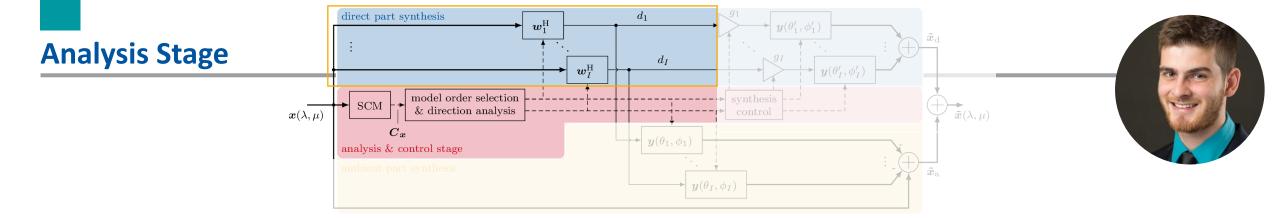
- Variant 2: Steered Response Power (SRP) Map
 - Source directions: find all local maxima in

 $P^{(\text{SRP})}(\theta,\phi) = \boldsymbol{y}^{\text{H}}(\theta,\phi)\boldsymbol{\mathcal{C}}_{\boldsymbol{x}}\boldsymbol{y}(\theta,\phi)$

- Model order selection: I = # minima found







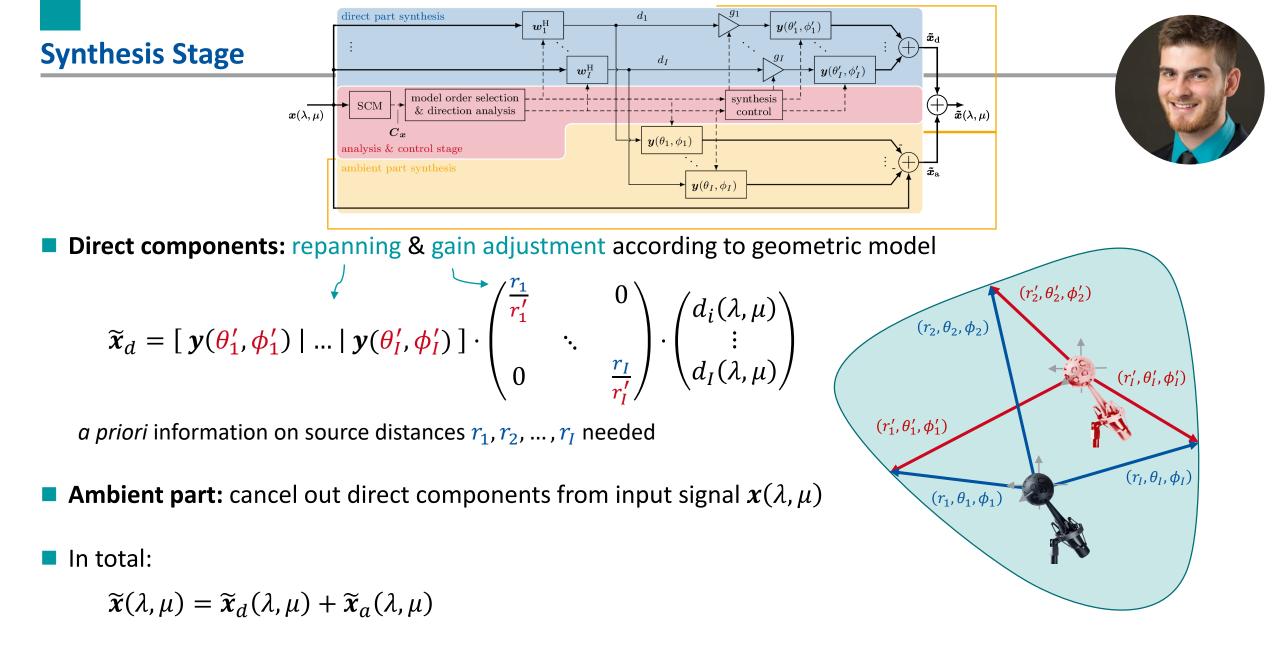
Beamforming to extract direct components i = 1, 2, ..., I

 $d_i(\lambda,\mu) = \boldsymbol{w}_i^H(\lambda,\mu)\boldsymbol{x}(\lambda,\mu)$

weights w_i : distortionless-response constraint in direction (θ_i, ϕ_i) and null constraints for (θ_j, ϕ_j) , $j \neq i$

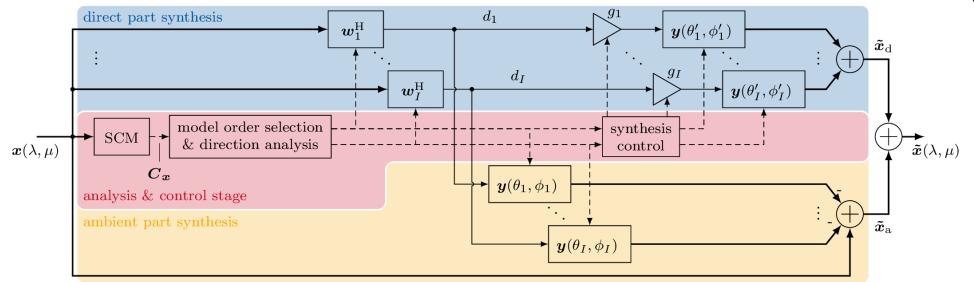
No semantic relation between direct components in time and frequency!









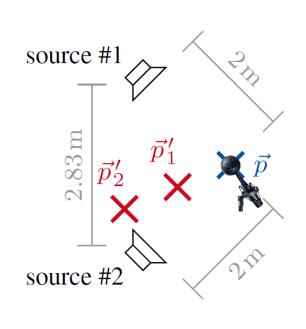


Early reflections not considered in signal model

- Likely to be modified as if they were direct sound
- Precedence effect: early reflections do not contribute to perceived source direction



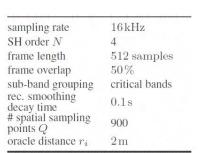
MUSHRA Listening Test for Localization & Overall Audio Quality | 18 Participants



T_{60}	$0.4\mathrm{s}$
source #1	pop music
source #2	male speaker
noise	diffuse $(-30 \mathrm{dB})$
sample duration	8s

HOA scene (order N=4) with two sound sources

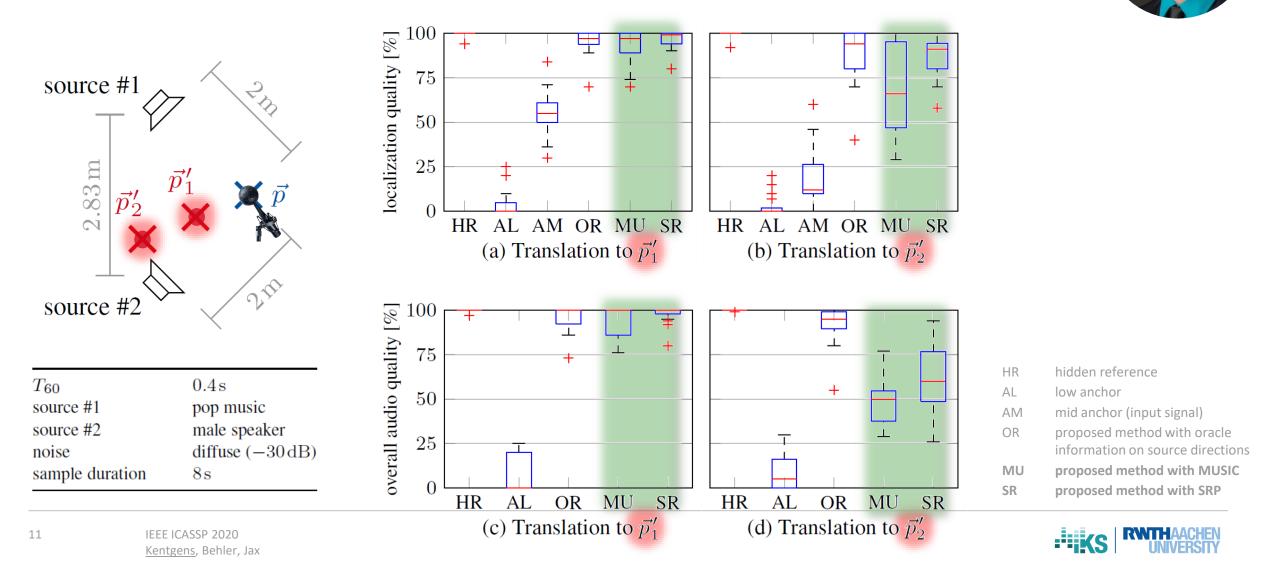
- Translation to \vec{p}'_1 and \vec{p}'_2
- Two variants of the proposed algorithm:
 - <u>MU</u>SIC/SORTE
 - <u>SR</u>P-based
- For reference:
 - **OR**ACLE: direction estimates replaced by actual source directions
 - Low anchor (<u>AL</u>): omni-directional sound, 4 kHz low-pass filtered
 - Mid anchor (<u>AM</u>): non-translated input signal $x(\lambda, \mu)$
 - Hidden reference (**HR**): ground truth at \vec{p}'_1 and \vec{p}'_2 , respectively











Novel 3DoF+ system for translation in scene-based HOA content

- Only single capture device needed

- Excellent subjective performance...
 - ... despite model error due to early reflections not treated differently than direct sound (→ psychoacoustic precedence effect)
 - Median subject ratings in localization between 91 % and 99 % (SRP method)

Applications: VR/AR systems, immersive teleconferencing & telepresence



