

Abu Dhabi



IEEE International Conference
on Image Processing
25-28 October 2020, United Arab Emirates



B-Spline Level Set For Drosophila Image Segmentation

Session

TEC-07

Biomedical and
Biological Image
Processing II

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Outline

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B-Spline Level Set For Image Segmentation

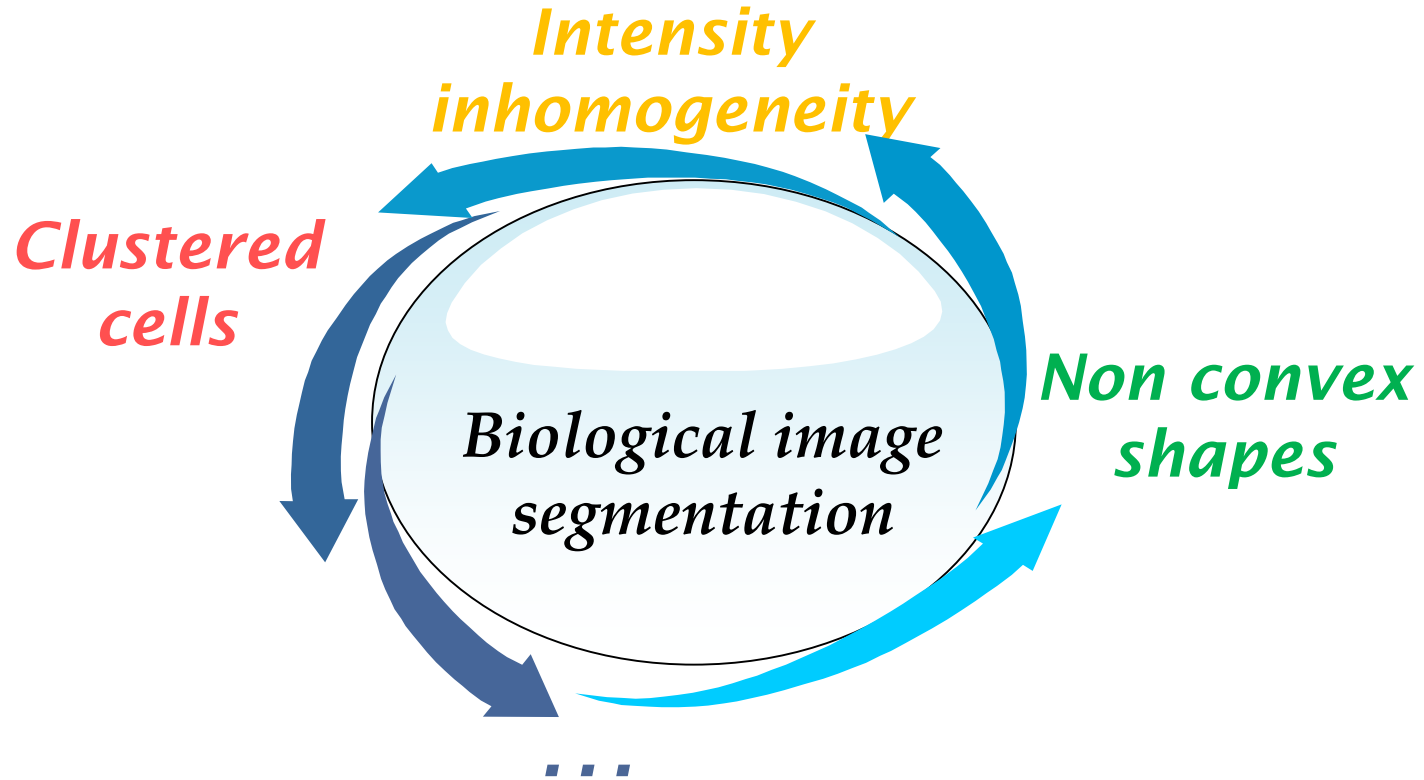
4

Segmentation Results

5

Conclusion and Perspectives

1. Introduction



1. Introduction

Segmentation algorithms

- DNA, F-actin and GFP-Rac are used for nuclei and cytoplasm detection
- Fuzzy C-means based Multi-Threshold segmentation and Sharpening technology
- Watershed algorithm based on simulation of flooding process
- Deep-Learning with different Network Structures

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2. Problem statement

However

*Most of algorithms cited above are based on the discrete level set implementation
requires a periodical re-normalization step to reshape the contour
which increases the computational cost*



Continuous representation of level set function using the B-spline coefficients is proposed



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3. B-spline Level Set for Image Segmentation

The key idea of the B-spline level set is

- Expressing the level set ϕ as a linear combination of B-spline coefficients

$$\phi(x) = \sum_{K \in^d} c[k] \beta^n \left(\frac{x}{h} - k \right)$$

- The energy function J is minimized with regard to B-spline coefficients c_i

$$\nabla_c J = \frac{\partial J}{\partial c[k]} = \int_{\Omega} \omega(x) \beta_h^n(x - hk) dx$$

3. B-spline Level Set for Image Segmentation

Given by

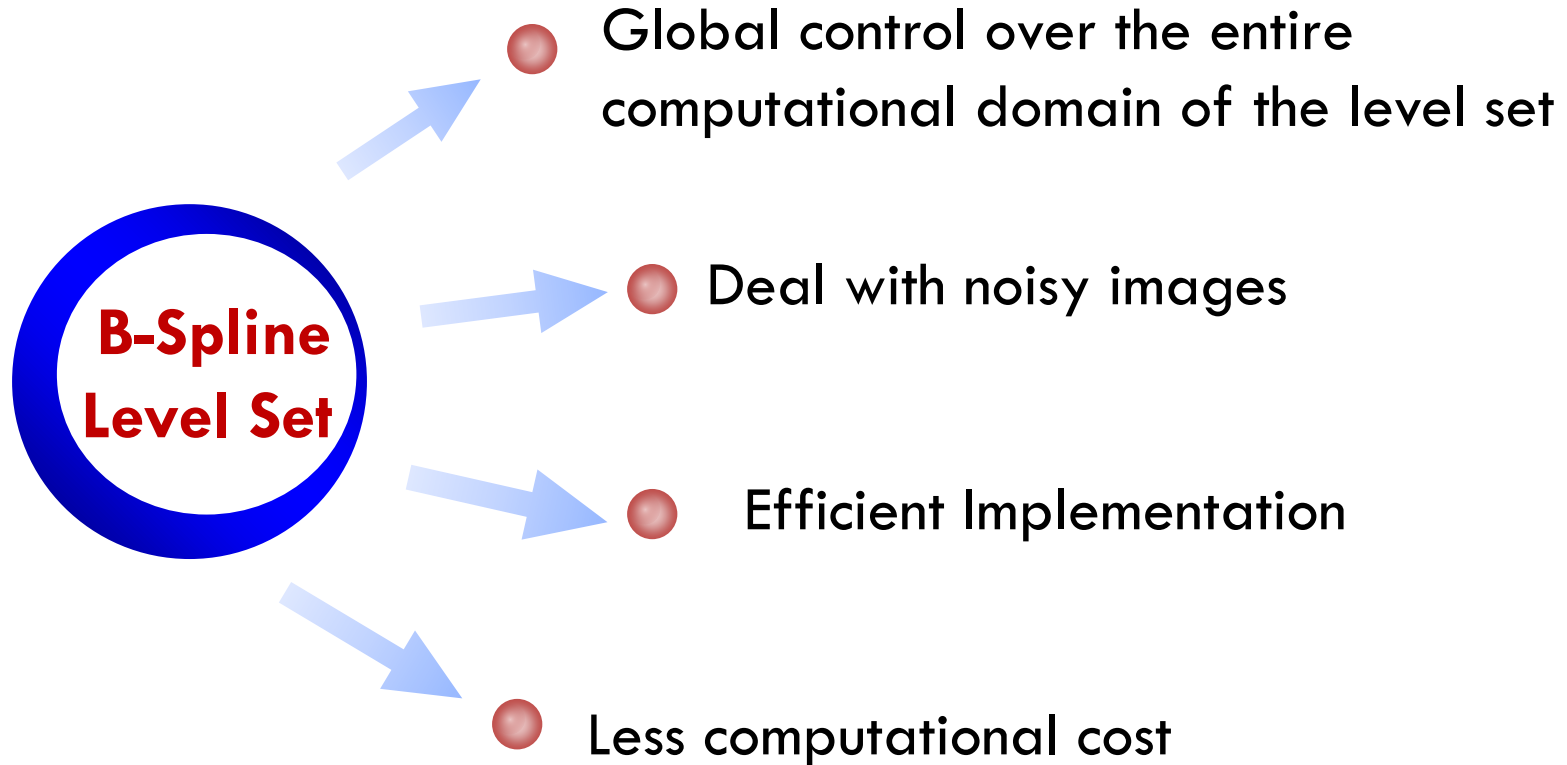
$$\omega(x) = \left(\lambda_{in} (f(x) - \mu_{in})^2 - \lambda_{out} (f(x) - \mu_{out})^2 - \nu \operatorname{div} \left(\frac{\nabla \phi(x)}{|\nabla \phi(x)|} \right) \right) \times \delta(\phi(x))$$

**Active
Contour
model**

*Chan Vese model is used for B-spline
level set implementation*

*Partitioning the image into two regions
with piecewise constant intensity*

3. B-spline Level Set for Image Segmentation



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4. Segmentation Results



- Drosophila RNAi experiments.
- Presence of locally low contrast values
- Large number of cells to be segmented
- Clustered cells.

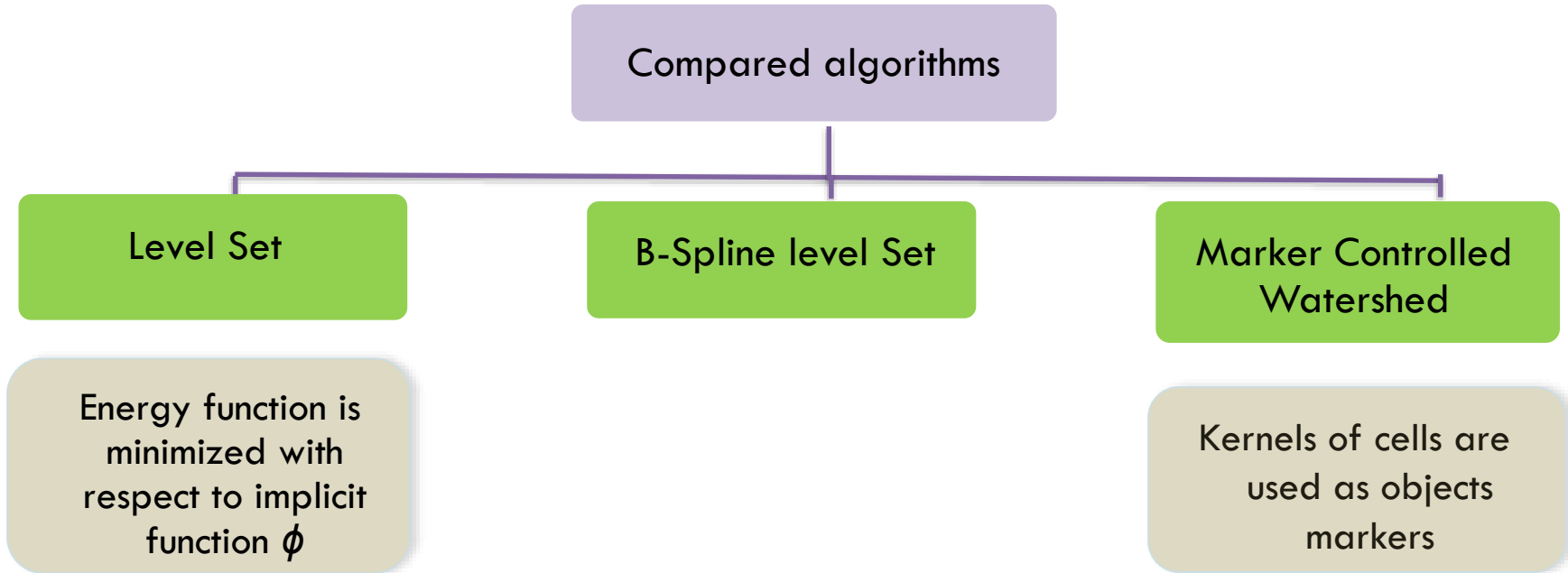
Drosophila images

What kind of images are used in this work ?

- Dimension : 686×518 pixels
- Image Preprocessing : Local Normalization
- Source : Valrose institute of Biology (iBV)



4. Segmentation Results



4. Segmentation Results

In this work:



Results are presented for fixed parameters



Results are presented for varying parameters h and initialization



Results are presented for noisy images

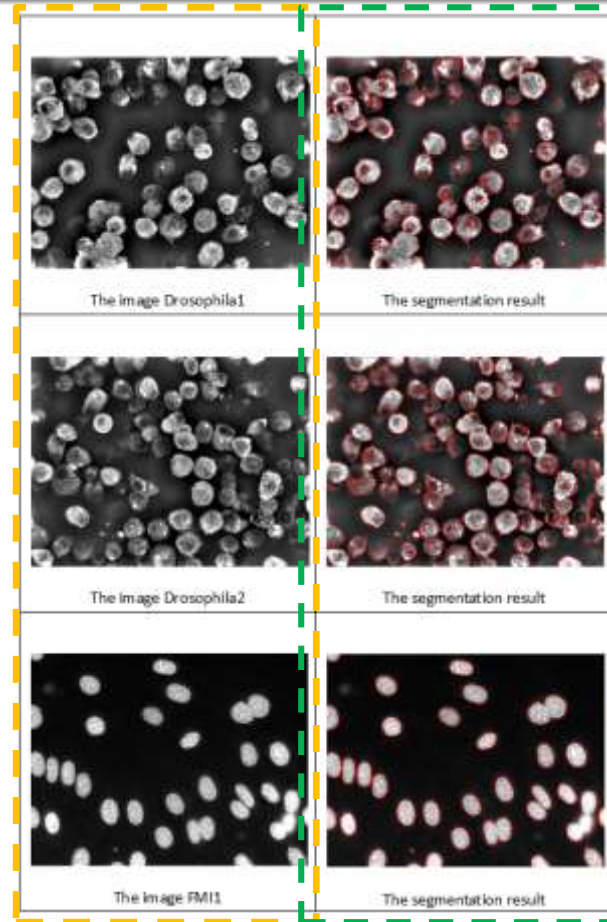
4. Segmentation Results

**Fixed
Parameters**

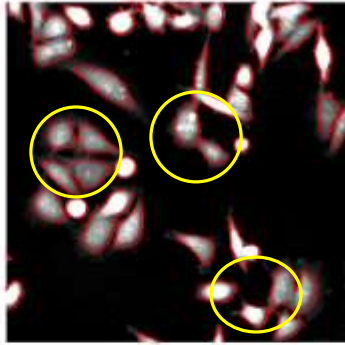
Results are presented for the same initialization and a fixed h

4. Segmentation Results

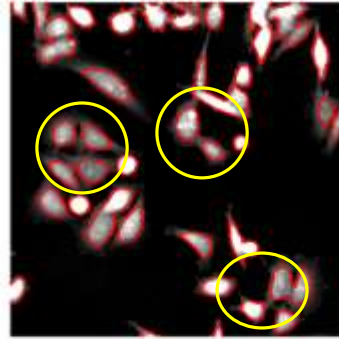
Good segmentation performance is clearly noticed



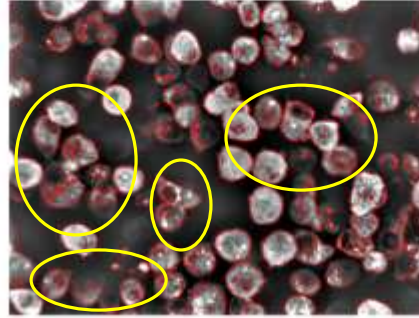
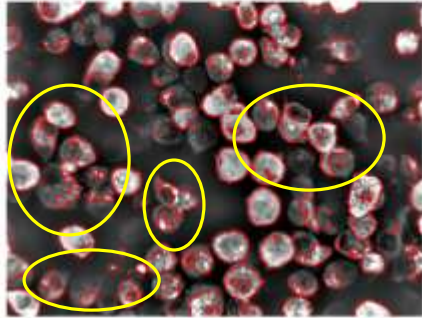
4. Segmentation Results



Level Set



B-spline Level Set



FMI 2

Superiority of the B-spline level set

Drosophila 2

4. Segmentation Results

DICE

- Calculates the degree of similarity between the segmented image and the ground truth.
- Ground truth are given with manual segmentation (provided by biologist)
- 1 == identical regions 0 == different regions

4. Segmentation Results

	B-spline level set	Level set	Marker Controlled Watershed
Drosophila 1	0.7861	0.7279	0.6501
Drosophila 2	0.7422	0.6423	0.6819
Drosophila 3	0.7993	0.6999	0.6975
Drosophila 4	0.7423	0.6256	0.6422
FMI2	0.7648	0.6698	--

DICE coefficient for Drosophila images and FMI 2

4. Segmentation Results

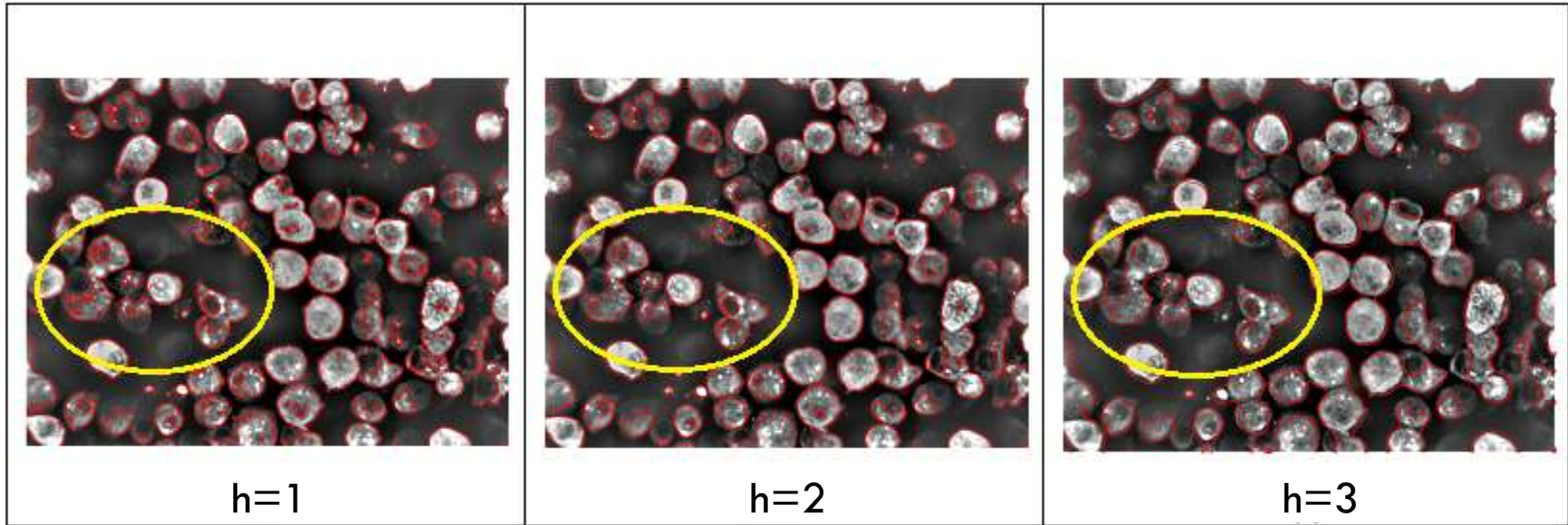
**Varing
Parameters**

*Results are presented for varing values of parameters
scale h and initialization*

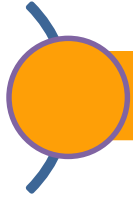
4. Segmentation Results

Scale h

*h controls smoothing of level set
With increasing h , the high level of smoothing makes cells blurry*



4. Segmentation Results



Initialization

The same results are obtained through a simple diversification of the expansion coefficients of the B-spline allows a flexible initialization

4. Segmentation Results

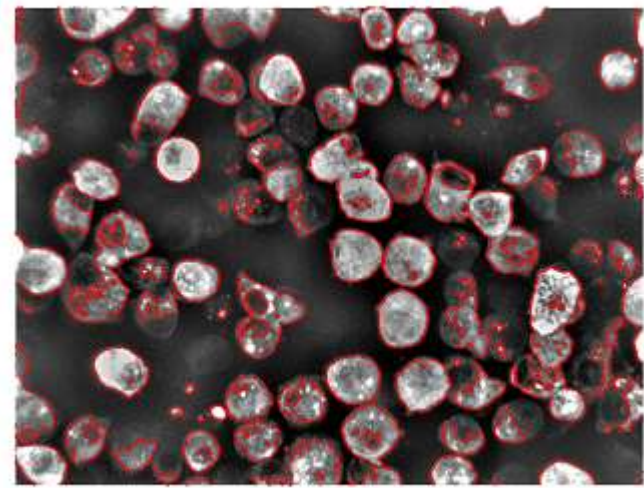
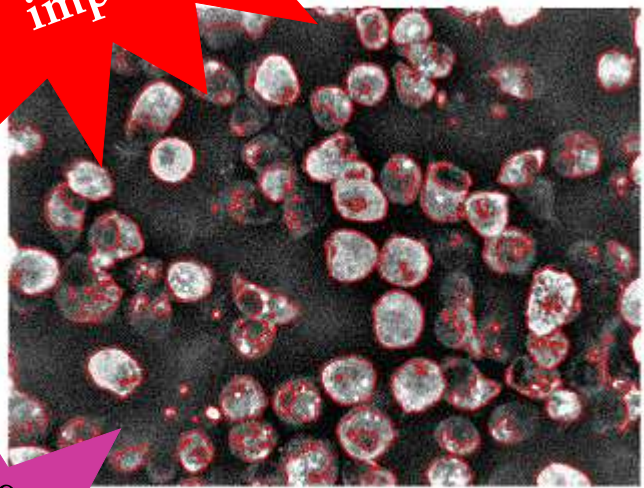
Noisy
Images

What about noisy images ?

4. Segmentation Results

Drosophila 2

No significant impact



Dice
0.6644

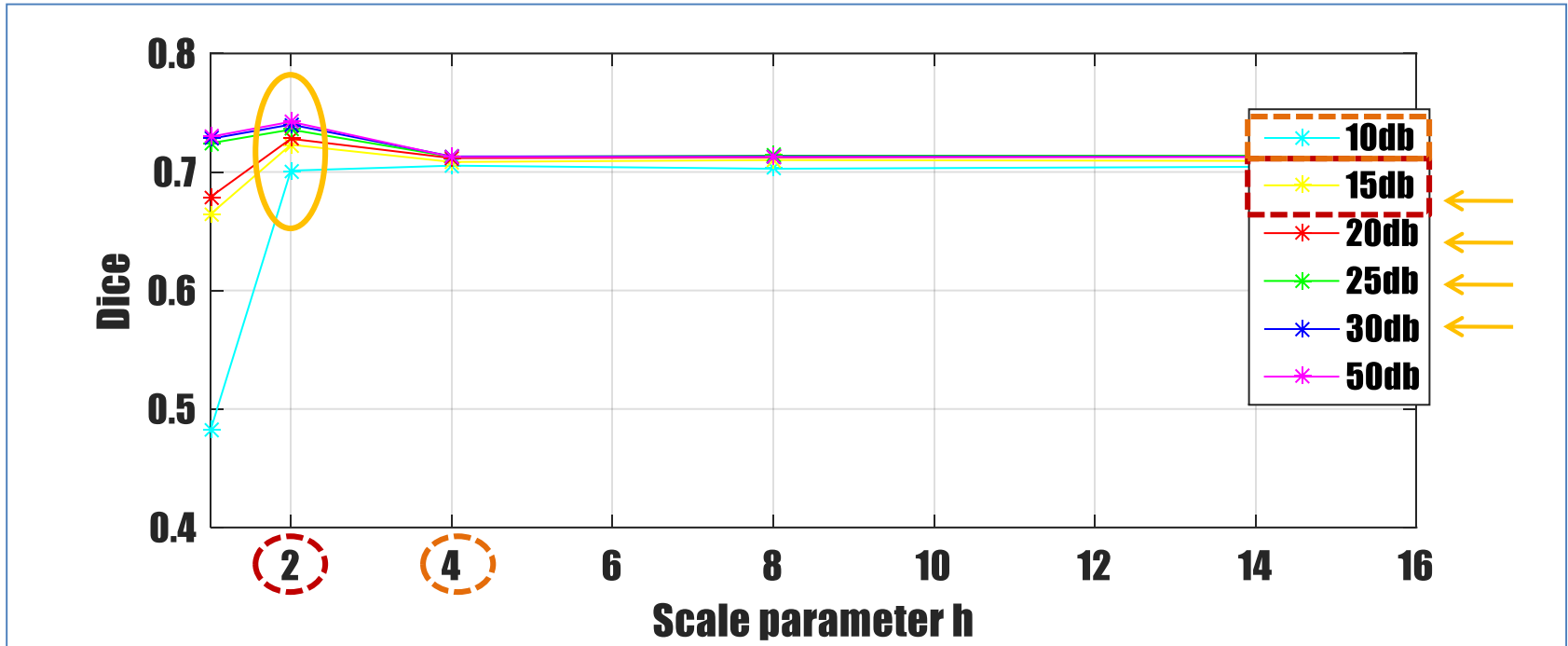
Dice
0.7400

15 db

30 db

Dice= 0.6423
for level set

4. Segmentation Results



DICE coefficient as a function of the scale parameter for varying noise levels

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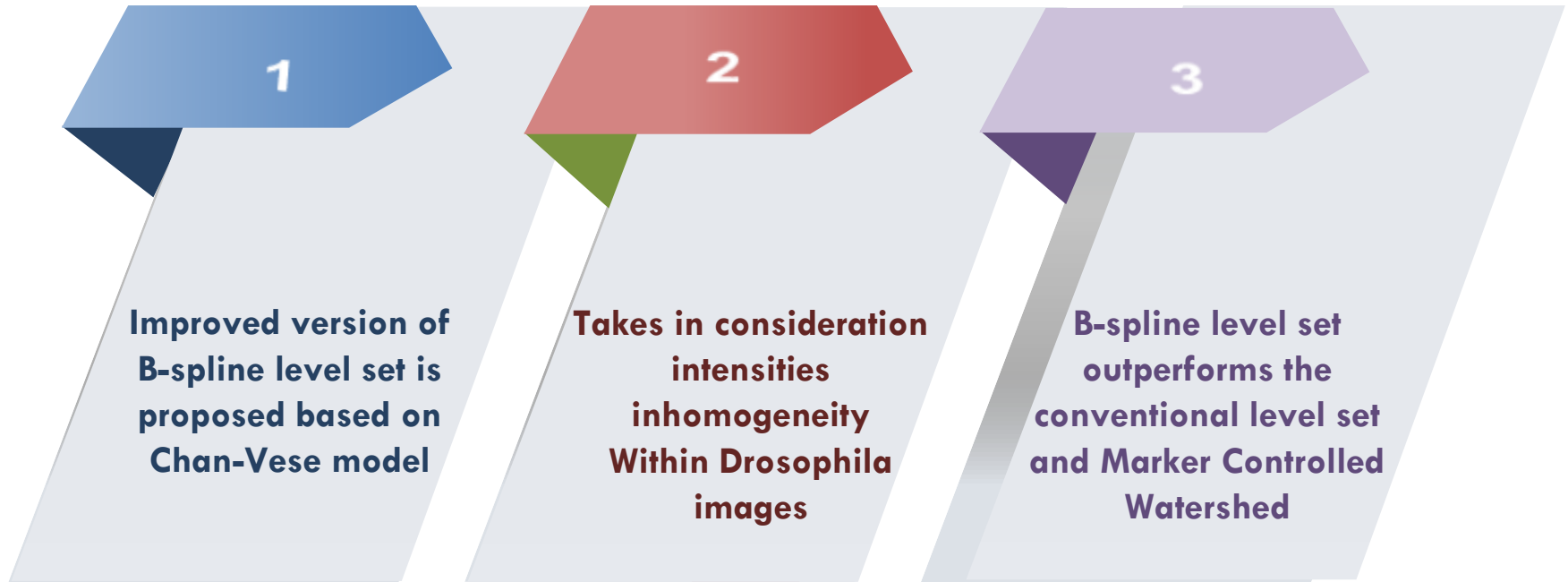
Segmentation Results

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Conclusion and Perspectives

5. Conclusion et perspectives

Conclusion



5. Conclusion et perspectives

PERSPECTIVES

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Using different model

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Preprocessing and postprocessing steps

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Using other evaluation metrics

Thank you for your attention
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