

## Optimal Power Flow Using Graph Neural Networks

Damian Owerko, Fernando Gama, and Alejandro Ribeiro Dept. of Electrical and Systems Engineering University of Pennsylvania

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▶ Requires a constant balance between supply and demand ⇒ supply = demand



 $\blacktriangleright \text{ The grid is a network } \Rightarrow \text{power is generated}/\text{demanded at each node by generators}/\text{consumers}$ 



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- ▶ Use graph neural networks to learn the optimal power allocation in a network.
  - $\Rightarrow$  Local computations, distributed implementations, scalability



Electrical Grids as Graphs

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Imitating Optimal Power Flow

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► The physical characteristics of the grid are described by the power flow equations

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- $\Rightarrow$  Relate local net power generation with the global state
- $\Rightarrow$  Depends on the topology  $\bm{W}$  of the grid W is the set of electrical components in the grid



Thus optimal power flow is a minimization problem

$$\underset{\{p_n\}}{\text{minimize}} \sum_{n=1}^{N} c_n(p_n, q_n)$$
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- $\Rightarrow$  (2) and (3) are the powerflow equations  $\Rightarrow$  sinusoidal constraints
- $\Rightarrow$   $\textbf{X}^{\textit{min}}$  and  $\textbf{X}^{\textit{max}}$  collect the minimum and maximum values each state entry can take

$$\Rightarrow \mathbf{X} \preceq \mathbf{Y} \iff [\mathbf{X}]_{ij} \leq [\mathbf{Y}]_{ij}$$



# DCOPF

- Most commonly used in practice
- Uses small angle approximations to linearize

 $\boldsymbol{\delta}=\mathbf{0}$ 

 Assumption invalid for moderately/heavily loaded grids



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# **ACOPF**

- Provides exact solution to OPF
- Solved using interior point methods (IPOPT)
- Very slow for large networks
  - $\Rightarrow$  Impractical for real-time optimization



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Electrical grid weighted graph



IEEE118 Power System Network



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  - $\Rightarrow$  How close the two nodes are two each other

$$\mathbf{A}_{ij} = exp(-k|z_{ij}|^2)$$



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$$\mathbf{x} \ast \mathbf{h} = \sum_{k=0}^{K-1} \mathbf{h}_k \mathbf{x}_{n-k}$$





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- ▶ Notion of shift  $S \Rightarrow$  Matrix description of graph (adjacency, Laplacian)
- ► Linear combination of neighboring signal ⇒ Local operation





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  - $\Rightarrow$  Graph convolutions with filters  $\mathcal{H} = \{\mathbf{h}_{\ell}\}$
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- Nonlinear mapping  $\Phi(\mathbf{x}; \mathbf{S}, \mathcal{H})$ 
  - $\Rightarrow$  Exploit underlying graph structure S
  - $\Rightarrow$  Local information
  - $\Rightarrow$  **Distributed** implementation





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• Once  $\Phi$  is trained we do not need the costly  $\mathbf{p}^*$  to make predictions



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#### We compare GNNs against Multi-Layer Perceptrons



#### Global vs Local MLP

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  - $\Rightarrow$  Finding  $p^*$  using IPOPT takes 2s for IEEE30 18s for IEEE118



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  - $\Rightarrow$  213% improvement of Global GNN over Global MLP
  - $\Rightarrow$  1082% improvement of Local GNN over Local MLP
- GNNs are also much faster than traditional methods
  - $\Rightarrow$  Finding  $p^*$  using IPOPT takes 2s for IEEE30 18s for IEEE118
  - $\Rightarrow$  The GNN takes  $\approx$  50 $\mu s$  to make predictions  $\Rightarrow$  GNNs are 10<sup>5</sup> times faster



- Solving OPF is central to electrical grid operation
- ▶ OPF  $\Rightarrow$  How to satisfy demand while **minimizing** operational costs?
  - $\Rightarrow$  Non-linear constrains  $\Rightarrow$  computationally expensive (NP hard)
- GNNs are well suited to applications on the electrical grid
  - $\Rightarrow$  Scalable  $\Rightarrow$  number of taps independent on network size
  - $\Rightarrow$  Exploit the network structure of the data
- GNNs are up to  $10^5$  times faster than IPOPT

Thank You!