

# ICASSP2021

## TORONTO

Canada 

June 6-11, 2021

Metro Toronto Convention Centre

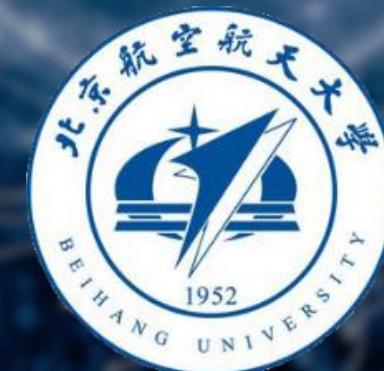
2021 IEEE International Conference on Acoustics,  
Speech and Signal Processing

6-11 June 2021 • Toronto, Ontario, Canada  
Extracting Knowledge from Information

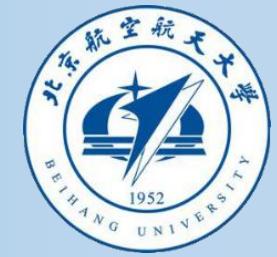
## CANET: CONTEXT-AWARE LOSS FOR DESCRIPTOR LEARNING

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# Introduction



## What is Local Feature Descriptor?

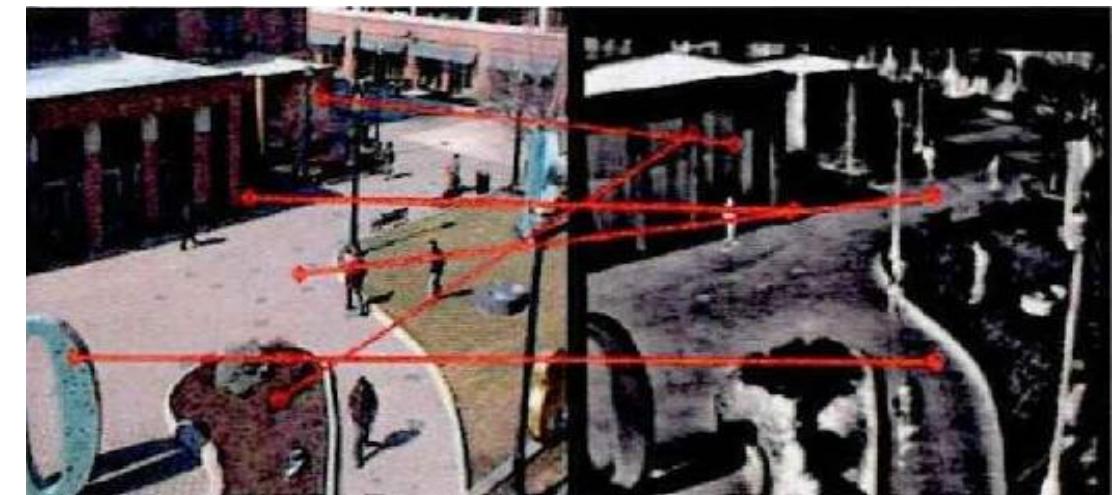
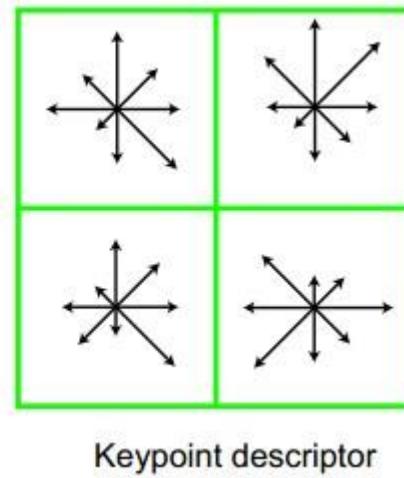
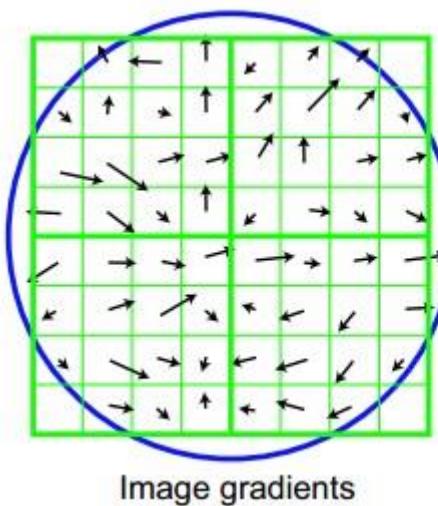
Encoding local images into representative vectors to compare local patches across images.

## Application domains

- 3D reconstruction
- Wide-baseline matching
- Image retrieval

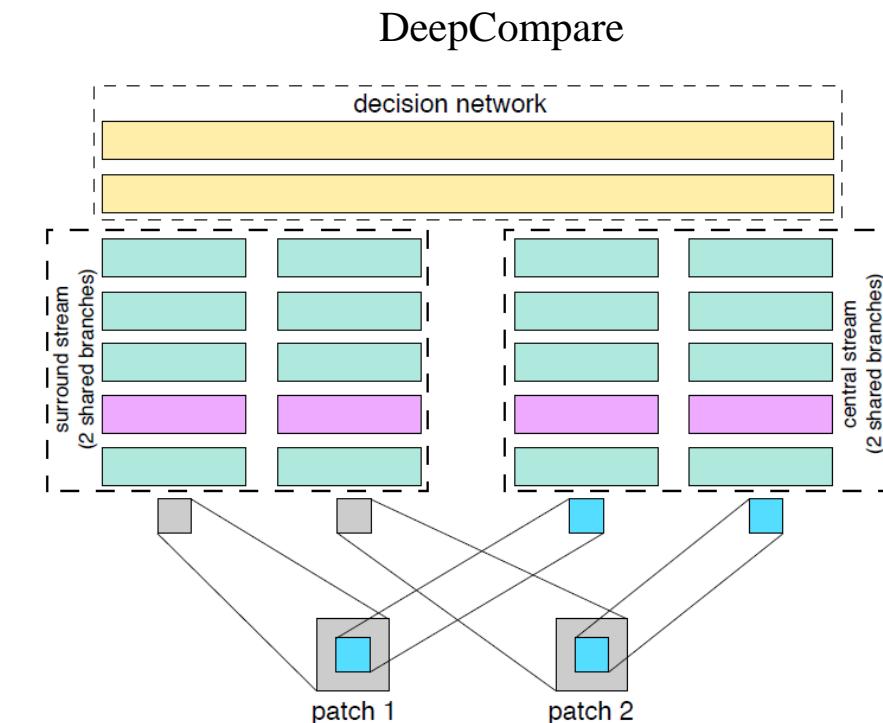
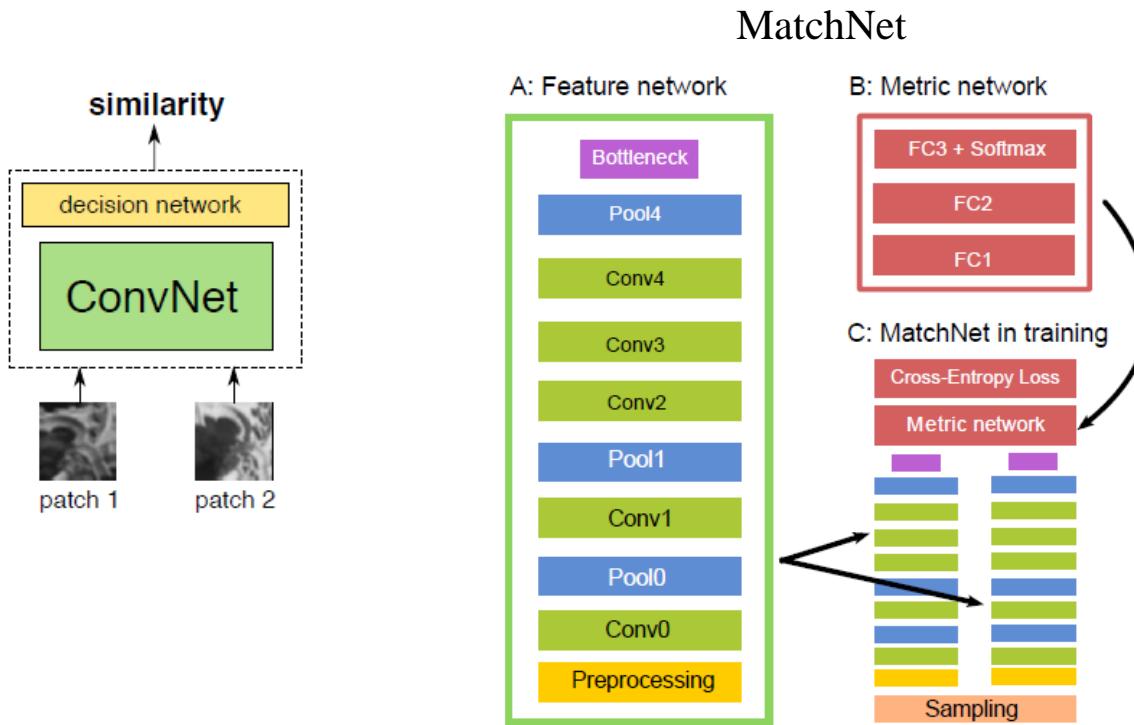
# Existing works

Traditional approaches



# Existing works

Deep learning based approaches (Siamese network)



MatchNet: Han et al., MatchNet: Unifying feature and metric learning for patch-based matching. CVPR 2015.

DeepCompare: Zagoruyko et al., Learning to compare image patches via convolutional neural networks. CVPR 2015.

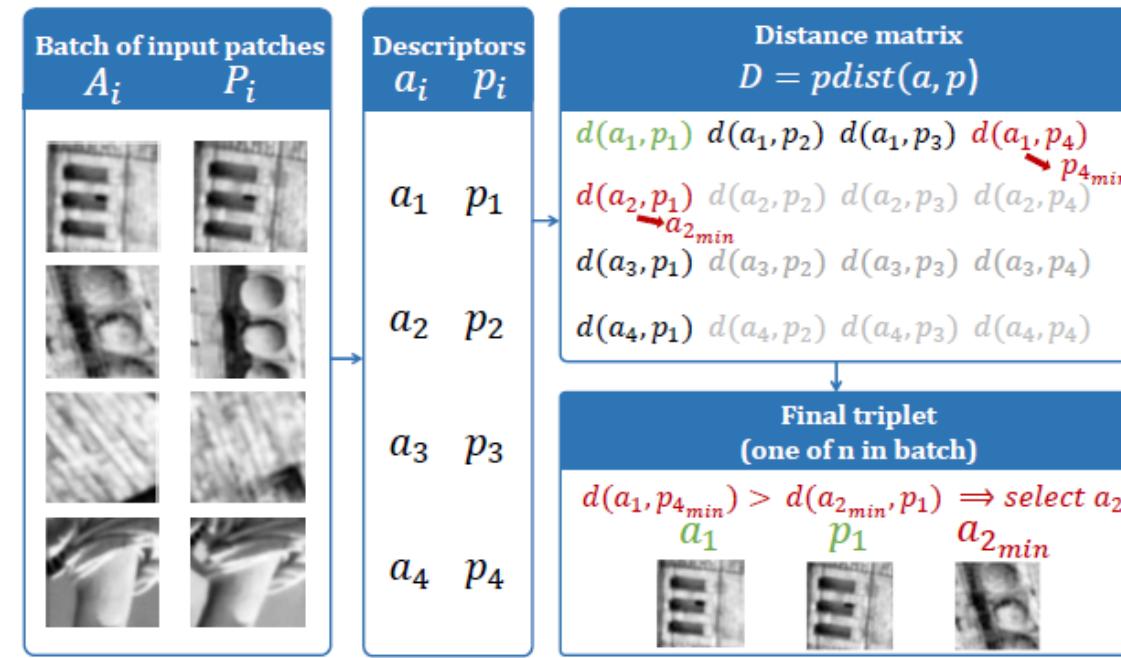
# Introduction

Deep learning based approaches (Single network)

L2-Net



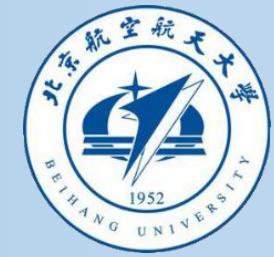
HardNet



L2-Net: Tian et al., L2-Net: Deep learning of discriminative patch descriptor in Euclidean space. CVPR 2017.

HardNet: Mishchuk et al., Working hard to know your neighbor's margins: Local descriptor learning loss. NIPS 2017.

# Drawbacks



## **Siamese network**

Networks with metric learning layers typically treat the matching of local patches as a binary classification task, so there does not exist the concept of descriptor.

## **Single network**

Networks perform descriptor learning by combining hard mining sampling strategies with Siamese loss or triplet loss without fully utilizing context information.



# Solution



- First order similarity loss
1. Generate a batch of matching patches  $X = \{(A_i, P_i), i = 1, 2, \dots, n\}$  and the corresponding descriptors  $\chi = \{(a_i, p_i), i = 0, 1, \dots, n\}$
  2. Compute the distance matrix  $D = \{d(a_i, p_j) = \|a_i - p_j\|_2, i = 0, 1, \dots, n; j = 1, 2, \dots, n\}$
  3. Find  $k$  closest non-matching descriptors  $K_i = \{q_{i,m}, m = 1, 2, \dots, k\}$  for each anchor patch descriptor  $a_i$  and ensure  $d(a_i, q_{i,1}) \leq d(a_i, q_{i,2}) \leq \dots \leq d(a_i, q_{i,k})$
  4. Build a virtual descriptor  $v_i$  for  $a_i$ ,  $d(a_i, v_i) = \sum_{m=1}^k W_{i,m} d(a_i, q_{i,m})$ ,  $w_{i,m} = \left(\frac{d(a_i, q_{i,k})}{d(a_i, q_{i,m})}\right)^2$ ,  $W_{i,m} = \frac{w_{i,m}}{\sum_{l=1}^k w_{i,l}}$
  5. Adopt the anchor swap strategy and create another virtual descriptor  $z_i$  for  $p_i$

$$\mathcal{L}_1 = \frac{1}{n} \sum_{i=1}^n \max(0, 1 + d(a_i, p_i) - \min(d(a_i, v_i), d(p_i, z_i)))$$

# Solution



- Second order similarity regularization
1. Compute two distance matrixes  $D_a = \{d(a_i, a_j), i = 1, 2, \dots, n; j = 1, 2, \dots, n\}$  and  $D_p = \{d(p_i, p_j), i = 1, 2, \dots, n; j = 1, 2, \dots, n\}$
  2. Find  $t$  closest descriptors  $S_i = \{(a_{s_{i,j}}), j = 1, 2, \dots, t\}$  for  $a_i$  and ensure  $d(a_i, a_{s_{i,1}}) \leq d(a_i, a_{s_{i,2}}) \leq \dots \leq d(a_i, a_{s_{i,t}})$
  3. Find  $t$  closest descriptors  $C_i = \{(p_{c_{i,j}}), j = 1, 2, \dots, t\}$  for  $p_i$  and  $d(p_i, p_{C_{i,1}}) \leq d(p_i, p_{C_{i,2}}) \leq \dots \leq d(p_i, p_{C_{i,t}})$ .
  4. Compute the regularization term  $\mathcal{L}_2 = \mathcal{L}_{2a} + \mathcal{L}_{2p}$

$$\mathcal{L}_{2a} = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^t W_{i,j}^A |d(a_i, a_{s_{i,j}}) - d(p_i, p_{s_{i,j}})|,$$

$$w_{i,j}^a = \left( \frac{d(a_i, a_{s_{i,t}})}{d(a_i, a_{s_{i,j}})} \right)^2,$$

$$W_{i,j}^A = \frac{w_{i,j}^a}{\sum_{l=1}^t w_{i,l}^a},$$

$$\mathcal{L}_{2p} = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^t W_{i,j}^P |d(a_i, a_{C_{i,j}}) - d(p_i, p_{C_{i,j}})|,$$

$$w_{i,j}^p = \left( \frac{d(p_i, p_{C_{i,t}})}{d(p_i, p_{C_{i,j}})} \right)^2,$$

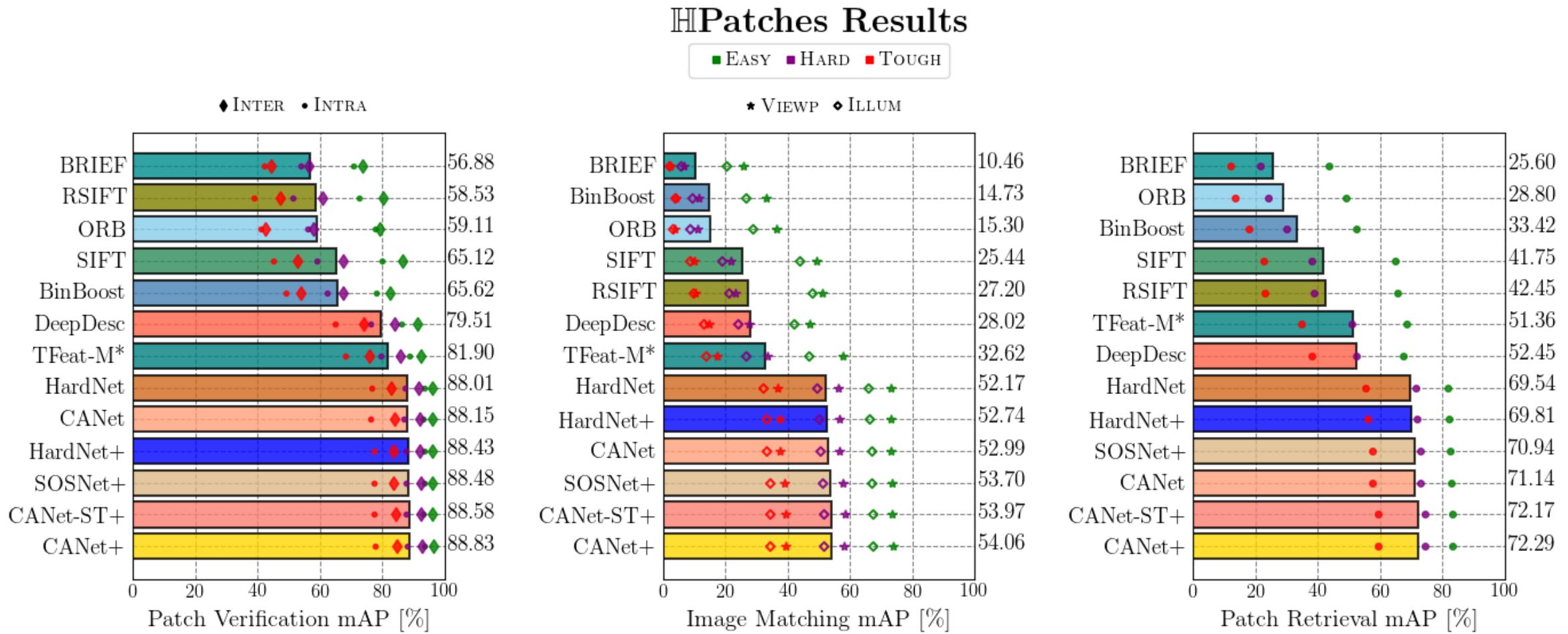
$$W_{i,j}^P = \frac{w_{i,j}^p}{\sum_{l=1}^t w_{i,l}^p}.$$

# Results and comparisons

UBC Phototour dataset

Training	Notredame	Yosemite	Liberty	Yosemite	Liberty	Notredame	Mean
Test	Liberty		Notredame		Yosemite		
SIFT [4]	29.84			22.53		27.29	26.55
DeepDesc [14]	10.9			4.40		5.69	6.99
MatchNet [20]	7.04	11.47	3.82	5.65	11.6	8.7	8.05
TFeat-M [15]	7.39	10.31	3.06	3.8	8.06	7.24	6.64
L2Net [21]	3.64	5.29	1.15	1.62	4.43	3.30	3.24
CS L2Net [21]	2.55	4.24	0.87	1.39	3.81	2.84	2.61
HardNet [10]	1.47	2.67	0.62	0.88	2.14	1.65	1.57
Keller et. al. [16]	1.79	2.96	0.68	1.02	2.51	1.64	1.77
SOSNet [11]	1.25	2.84	0.58	0.87	1.95	1.25	1.46
CANet (Ours)	1.19	2.69	0.42	0.77	1.58	1.15	1.30
Data Augmentation							
L2Net+ [21]	2.36	4.7	0.72	1.29	2.57	1.71	2.23
CS L2Net+ [21]	1.71	3.87	0.56	1.09	2.07	1.3	1.76
HardNet+ [10]	1.49	2.51	0.53	0.78	1.96	1.84	1.51
DOAP+ [23]	1.54	2.62	0.43	0.87	2.00	1.21	1.45
DOAP-ST+ [23-24]	1.47	2.29	0.39	0.78	1.98	1.35	1.38
SOSNet+ [11]	1.08	2.12	0.35	0.67	1.03	0.95	1.03
CANet+ (Ours)	1.29	2.46	0.45	0.75	1.23	1.10	1.21
CANet-ST+ (Ours)	1.25	2.49	0.42	0.69	1.36	1.15	1.23

# Results and comparisons



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Thanks for your attention

