



Motivation

- The **uncoordinated random access** is a challenging task in **massive machine-type communication (mMTC)**.
- A large number of **sporadically active devices** wish to send small data to the **base-station (BS)** in the uplink.
- The BS acquires the active devices and their data by **detecting the transmitted preassigned nonorthogonal signature sequences**.
- Covariance based approach** [1, 2, 3]: formulate the detection problem as a **maximum likelihood estimation (MLE) problem**.
- The state-of-the-art **coordinate descent (CD) algorithm** doesn't take advantage of the **sparsity of the true solution**.

Main Contribution

- Perform the **covariance based approach** for **joint data and activity detection**.
- Propose a computationally efficient **active set algorithm** with convergence guarantee.

System Model

- Single cell with one BS equipped with M antennas.
- N **single-antenna devices**, K of which are active at a time.
- Each active device wishes to transmit J bits of data to the BS.
- Each device n has a **unique signature sequence set** $\mathcal{S}_n = \{\mathbf{s}_{n,1}, \mathbf{s}_{n,2}, \dots, \mathbf{s}_{n,Q}\}$, where $\mathbf{s}_{n,q} \in \mathbb{C}^{L \times 1}$, $1 \leq q \leq Q \triangleq 2^J$, and L is the signature sequence length.
- Channel $\sqrt{g_n} \mathbf{h}_n \in \mathbb{C}^{M \times 1}$ of user n includes both
 - large-scale fading component** $g_n \geq 0$;
 - Rayleigh fading component** $\mathbf{h}_n \in \mathbb{C}^{M \times 1}$ following the i.i.d. complex Gaussian distribution.
- Whether or not $\mathbf{s}_{n,q}$ is transmitted is indicated as $\chi_{n,q} \in \{0, 1\}$, which satisfies $\sum_{q=1}^Q \chi_{n,q} \in \{0, 1\}$
 - $\sum_{q=1}^Q \chi_{n,q} = 1$ indicates that device n is **active**;
 - $\sum_{q=1}^Q \chi_{n,q} = 0$ indicates that device n is **inactive**.
- Define
 - $\mathbf{S} = [\mathbf{S}_1, \dots, \mathbf{S}_N] \in \mathbb{C}^{L \times NQ}$, where $\mathbf{S}_n = [\mathbf{s}_{n,1}, \dots, \mathbf{s}_{n,Q}]$.
 - $\mathbf{\Gamma}^{1/2} = \text{diag}\{\mathbf{D}_1, \dots, \mathbf{D}_N\} \in \mathbb{C}^{NQ \times NQ}$, where $\mathbf{D}_n = \sqrt{g_n} \text{diag}\{\chi_{n,1}, \dots, \chi_{n,Q}\}$.
 - $\mathbf{H} = [\mathbf{H}_1^T, \dots, \mathbf{H}_N^T]^T \in \mathbb{C}^{NQ \times M}$, where $\mathbf{H}_n = [\mathbf{h}_n, \dots, \mathbf{h}_n]^T$.

System Model (Cont.)

- The **received signal** $\mathbf{Y} \in \mathbb{C}^{L \times M}$ at the BS can be expressed as

$$\begin{aligned} \mathbf{Y} &= \sum_{n=1}^N \sum_{q=1}^Q \chi_{n,q} \mathbf{s}_{n,q} \sqrt{g_n} \mathbf{h}_n^T + \mathbf{W} \\ &= \mathbf{S} \mathbf{\Gamma}^{1/2} \mathbf{H} + \mathbf{W}, \end{aligned} \quad (1)$$

where $\mathbf{W} \in \mathbb{C}^{L \times M}$ is the **effective i.i.d. Gaussian noise** with variance σ_w^2 .

- For given $\boldsymbol{\gamma}$ (diagonal entries of $\mathbf{\Gamma}$), the m -th column of \mathbf{Y} can be seen as **independent samples** from a complex Gaussian distribution as

$$\mathbf{y}_m \sim \mathcal{CN}(\mathbf{0}, \mathbf{S} \mathbf{\Gamma}^{1/2} \mathbf{\Lambda} \mathbf{\Gamma}^{1/2} \mathbf{S}^H + \sigma_w^2 \mathbf{I}), \quad (2)$$

where $\mathbf{\Lambda}$ is a **block diagonal matrix** with each block being the all-one matrix $\mathbf{E} \in \mathbb{R}^{Q \times Q}$, and \mathbf{I} is an identity matrix.

- Since there is **at most one non-zero entry in each diagonal block** \mathbf{D}_n in $\mathbf{\Gamma}^{1/2}$, the covariance matrix in (2) can be simplified as

$$\mathbf{S} \mathbf{\Gamma}^{1/2} \mathbf{\Lambda} \mathbf{\Gamma}^{1/2} \mathbf{S}^H + \sigma_w^2 \mathbf{I} = \mathbf{S} \mathbf{\Gamma} \mathbf{S}^H + \sigma_w^2 \mathbf{I}.$$

- The **MLE problem** can be formulated as

$$\min_{\boldsymbol{\gamma}} \log |\mathbf{S} \mathbf{\Gamma} \mathbf{S}^H + \sigma_w^2 \mathbf{I}| + \text{Tr} \left((\mathbf{S} \mathbf{\Gamma} \mathbf{S}^H + \sigma_w^2 \mathbf{I})^{-1} \hat{\boldsymbol{\Sigma}} \right) \quad (3a)$$

$$\text{s. t. } \boldsymbol{\gamma} \geq \mathbf{0}. \quad (3b)$$

- The **sample covariance matrix** $\hat{\boldsymbol{\Sigma}} = \mathbf{Y} \mathbf{Y}^H / M$ is computed by averaging over different antennas.

- The **constraint** $\boldsymbol{\gamma} \geq \mathbf{0}$ is due to the fact that $\gamma_{n,q} = g_n \chi_{n,q} \geq 0$ for all n and q .

Problem Formulation and Analysis

- Let $f(\boldsymbol{\gamma})$ denote the objective function of problem (3). The **gradient** of $f(\boldsymbol{\gamma})$ with respect to $\gamma_{n,q}$ is

$$[\nabla f(\boldsymbol{\gamma})]_{n,q} = \mathbf{s}_{n,q}^H \boldsymbol{\Sigma}^{-1} \mathbf{s}_{n,q} - \mathbf{s}_{n,q}^H \boldsymbol{\Sigma}^{-1} \hat{\boldsymbol{\Sigma}} \boldsymbol{\Sigma}^{-1} \mathbf{s}_{n,q}.$$

- The **first-order (necessary) optimality condition** of problem (3) is

$$[\nabla f(\boldsymbol{\gamma})]_{n,q} \begin{cases} = 0, & \text{if } \gamma_{n,q} > 0; \\ \geq 0, & \text{if } \gamma_{n,q} = 0, \end{cases} \quad \forall q, n, \quad (4)$$

- Let $[\cdot]_+$ denote the **projection operator onto the nonnegative orthant**. Then (4) is equivalent to

$$[\boldsymbol{\gamma} - \nabla f(\boldsymbol{\gamma})]_+ - \boldsymbol{\gamma} = \mathbf{0}.$$

Active Set Algorithm

- To fully exploit the **sparsity of the true solution of (3)**, the active set should

- contain the **indices of active sequences**;
- have the **smallest possible cardinality**.

- At the k -th iteration, the proposed **selection strategy** of the active set \mathcal{A}^k is

$$\mathcal{A}^k = \left\{ (i, q) \mid \gamma_{i,q}^k > \omega_k \text{ or } [\nabla f(\boldsymbol{\gamma}^k)]_{i,q} < -\nu_k \right\}, \quad (5)$$

where $\omega_k, \nu_k > 0$ and $\omega_k \downarrow 0$ and $\nu_k \downarrow 0$ (monotonically decrease and converge to zero).

- Once the active set \mathcal{A}^k is selected, we solve the following subproblem

$$\min \hat{f}(\boldsymbol{\gamma}_{\mathcal{A}^k}) \quad (6a)$$

$$\text{s. t. } \boldsymbol{\gamma}_{\mathcal{A}^k} \geq \mathbf{0}, \quad (6b)$$

where $\boldsymbol{\gamma}_{\mathcal{A}^k}$ is the subvector of $\boldsymbol{\gamma}$ indexed by \mathcal{A}^k and $\hat{f}(\boldsymbol{\gamma}_{\mathcal{A}^k})$ is $f(\boldsymbol{\gamma})$ defined over $\boldsymbol{\gamma}_{\mathcal{A}^k}$ with **all the other variables fixed being zero**.

- If the set \mathcal{A}^k in (6) is properly chosen, the **dimension of problem (6)** is potentially **much smaller** than that of problem (3).

- We apply the **spectral PG algorithm** [4] to solve the subproblem in (6) until $\boldsymbol{\gamma}_{\mathcal{A}^k}^{k+1}$ satisfying

$$\left\| \left[[\boldsymbol{\gamma}_{\mathcal{A}^k}^{k+1} - \nabla \hat{f}(\boldsymbol{\gamma}_{\mathcal{A}^k}^{k+1})]_+ - \boldsymbol{\gamma}_{\mathcal{A}^k}^{k+1} \right] \right\| < \varepsilon_k, \quad (7)$$

where $\varepsilon_k > 0$ is the **solution tolerance** at the k -th iteration.

- The pseudocodes of the proposed algorithm are given in Algorithm 1.

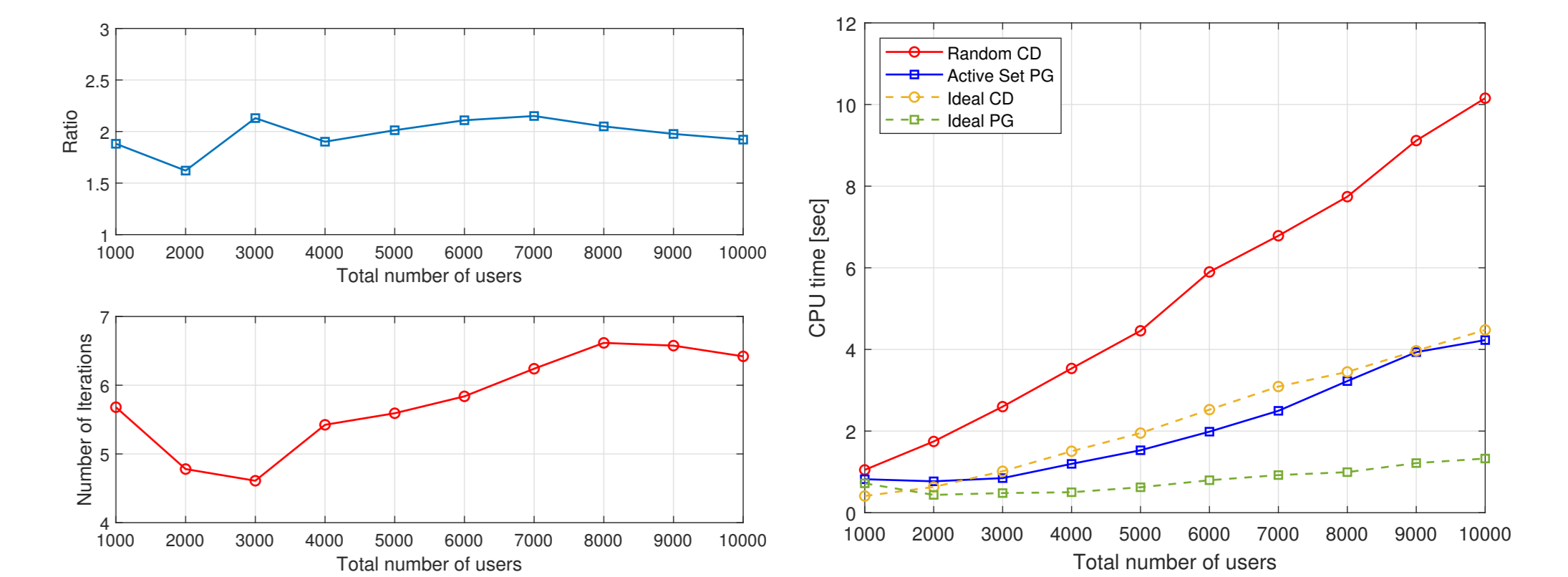
Algorithm 1 Proposed active set PG algorithm for solving problem (3)

- Initialize:** $\boldsymbol{\gamma}^0 = \mathbf{0}$, $k = 0$, $\{\omega_k, \nu_k, \varepsilon_k\}_{k \geq 0}$, and $\varepsilon > 0$;
- repeat**
- Select the active set \mathcal{A}^k according to (5);
- Apply the spectral PG algorithm [4] to solve the subproblem (6) until (7) is satisfied;
- Set $k \leftarrow k + 1$;
- until** $\|[\boldsymbol{\gamma}^k - \nabla f(\boldsymbol{\gamma}^k)]_+ - \boldsymbol{\gamma}^k\| < \varepsilon$
- Output:** $\boldsymbol{\gamma}^k$

- Convergence property:** For any given tolerance $\varepsilon > 0$, suppose that the parameters ω_k and ν_k in (5) satisfy $\omega_k \downarrow 0$ and $\nu_k \downarrow 0$ and the parameter ε_k in (7) satisfy $\lim_{k \rightarrow \infty} \varepsilon_k < \varepsilon$, then the active set PG Algorithm 1 will **terminate within a finite number of iterations**.

Simulation Results

- The power spectrum density of the background noise is -169dBm/Hz over 10 MHz and the transmit power of each device is 25dBm;
- A single cell of radius 1000m, all devices are located in the cell edge, g_n 's are the same for all devices;
- All signature sequences from **i.i.d. complex Gaussian distribution** with zero mean and unit variance
- Parameters setting: $M = 256$, $L = 150$, and $J = 1$ (and thus $Q = 2$), $K/N = 0.1$ (**10% of the total devices are active**).
- Compare the proposed Algorithm 1 with
 - random CD algorithm** in [1];
 - Ideal CD/PG algorithm:** apply the CD/PG algorithm to solve problem (3) defined over the indices of active sequences;
- Parameters setting: $\omega_k = 10^{-6-k}$, $\varepsilon_k = \max\{10^{-k}, 0.8 * 10^{-3}\}$, $\nu_k = \min\{10^{4-k}, 0.5 \mid \min_{n,q} \{[\nabla f(\boldsymbol{\gamma}^k)]_{n,q}\}\}$, $\varepsilon = 10^{-3}$.
- Average over 500 Monte-Carlo runs.



Left: Average ratio $|\mathcal{A}^k|/K$; Average number of iterations to terminate; Right: Average CPU time comparison.

- The ratio is in the **interval [1.5, 2.5]**, and Algorithm 1 will generally terminate within **4–7 iterations**.
- The proposed active set **selection strategy (5)** is very efficient.
- In CPU time, the proposed Algorithm 1 **significantly outperforms the random CD algorithm**, and even **achieves slightly better efficiency than the ideal CD algorithm**.

References

- S. Haghghatshoar, P. Jung, and G. Caire, "Improved scaling law for activity detection in massive MIMO systems," in *Proc. IEEE Int. Symp. Inf. Theory (ISIT)*, Vail, CO, USA, June 2018, pp. 381–385.
- Z. Chen, F. Sohrabi, Y.-F. Liu, and W. Yu, "Covariance based joint activity and data detection for massive random access with massive MIMO," in *Proc. IEEE Int. Conf. Commun. (ICC)*, Shanghai, China, May 2019, pp. 1–6.
- Z. Chen, F. Sohrabi, Y.-F. Liu, and W. Yu, "Phase transition analysis for covariance based massive random access with massive MIMO," 2020. [Online]. Available: <https://arxiv.org/abs/2003.04175>
- E. G. Birgin, J. M. Martínez, and M. Raydan, "Nonmonotone spectral projected gradient methods on convex sets," *SIAM J. Optim.*, vol. 10, no. 4, pp. 1196–1211, 2000.