

PROBABILISTIC GRAPH NEURAL NETWORKS FOR TRAFFIC SIGNAL CONTROL

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Presenter: Zheyang Xu

Introduction

- **Background**
- **Existing Methods**
- **Challenges**
- **Our model: TSC-GNN**

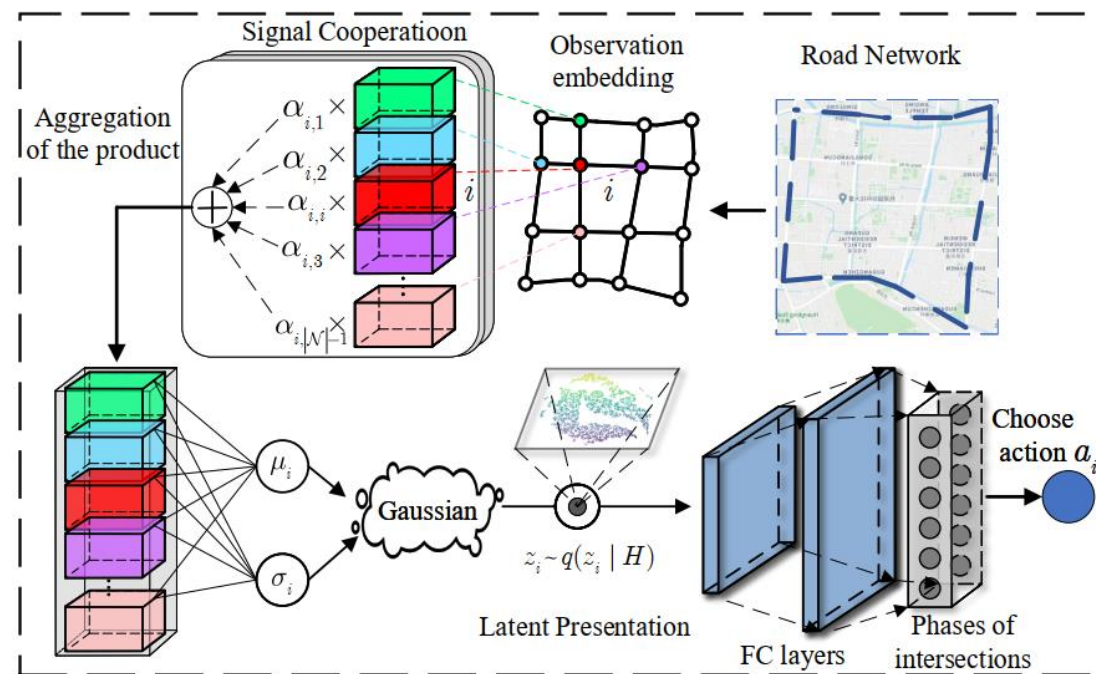
Problem Definition

- **Reinforcement Learning for Traffic Signal Control**

$\langle S, \mathcal{O}, \mathcal{A}, \mathcal{P}, \mathcal{R}, \pi, \gamma \rangle$

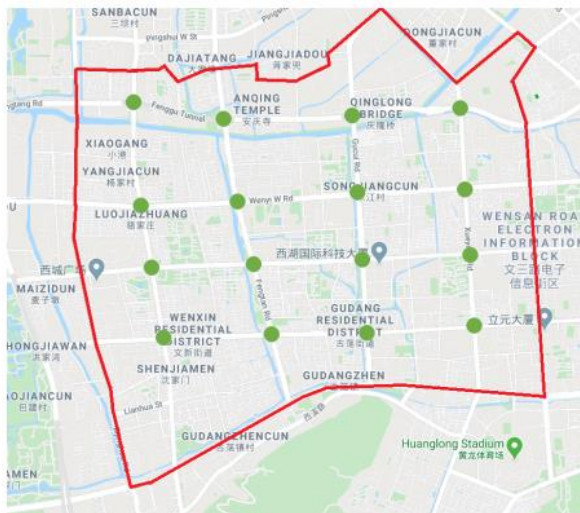
Our model: TSC-GNN

- Cooperation of traffic signals
- Variational Graph Inference
- Q-value Prediction



Experiments

- **Datasets**



(a) Gudang sub-district



(b) Dongfeng sub-district

Experiments

- **Baselines**

1) FixedTime

2) MaxPressure

3) CGRL

4) Individual RL

5) OneModel

6) Neighbor RL

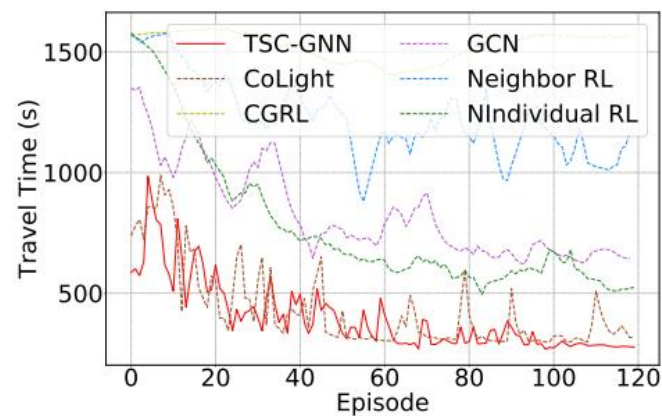
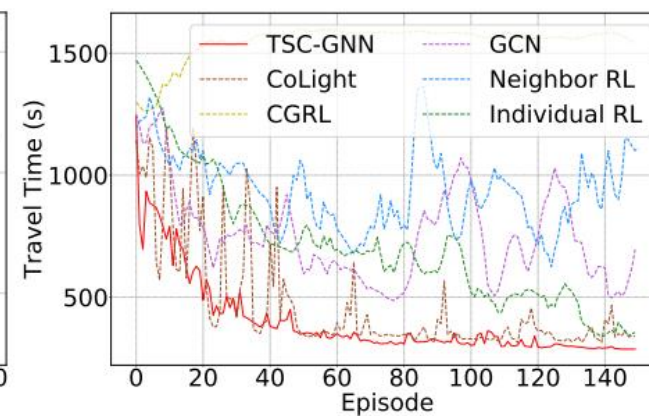
7) GCN

8) CoLight

Experiments

• Results

Model	D_{Jinan}	$D_{Hangzhou}$
Fixedtime	869.85	728.79
MaxPressure	361.33	422.15
CGLR	1210.7	1528.26
Individual RL	325.56	345.00
OneModel	728.63	394.56
Neighbor RL	1168.32	1053.45
GCN	625.66	768.43
CoLight	316.52	309.06
TSC-GNN	291.24	281.19

(a) $D_{Hangzhou}$ (b) D_{Jinan}

IEEE ICASSP 2021



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Thank you for listening!