# Nonnegative unimodal Matrix Factorization

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- Content
  - ► What is Nu? Introduction
  - Why? Motivation
  - ► How to solve? Algorithm
  - What is known about Nu? Theory

$$\min_{\mathbf{x}} \|\mathbf{A}\mathbf{x} - \mathbf{b}\| \quad \text{s.t.} \quad \mathbf{x} \in \mathcal{C} \qquad \min_{\mathbf{x}} \|\mathbf{A}\mathbf{x} - \mathbf{b}\| + \lambda c(\mathbf{x}).$$

 $\ell_2, \ell_1, \ell_0, \ell_p$  norm, sparsity, TV-norm, smoothness, nonnegativity, cone,  $\ldots$ 

### This talk: **unimodal**<sup>1</sup> structure.

<sup>&</sup>lt;sup>1</sup>Not the **unimodular** structure in combinatorial optimization.

## Nu

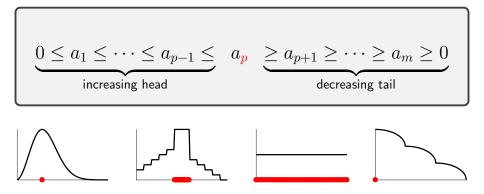


Figure: Nu vectors. Black: the sequence. Red dots: locations of p.

Characterizing the Nu set

$$\mathbf{x} \in \mathbb{R}^m \text{ is } \mathsf{Nu} \iff \underbrace{\exists p \in [m] \text{ s.t. } 0 \le x_1 \le \cdots \le x_p \ge \cdots \ge x_m \ge 0}_{\mathbf{x} \in \mathcal{U}_+^{m,p}}.$$

- Notations:  $\mathbf{x} \in \mathcal{U}^m_+$  means  $\mathbf{x} \in \mathbb{R}^m$  is Nu but p unknown.
- Facts
  - $\mathcal{U}^{m,p}_+$  is cvx •  $\mathcal{U}^m_+ = \bigcup_k \mathcal{U}^{m,k}_+$  is **non**cvx

• The set 
$$\mathcal{U}^{m,p}_+ \cup \mathcal{U}^{m,p+1}_+$$
 is cvx.

 $\mathbf{x} \in \mathbb{R}^m$  is Nu  $\iff \exists p \in [m] \text{ s.t. } \mathbf{x} \in \mathcal{U}^{m,p}_+ \cup \mathcal{U}^{m,p+1}_+$ 

\*  $\mathbf{U}_p$  is full rank.

### NuMF

► GIVEN  $\mathbf{M} \in \mathbb{R}^{m \times n}_+$  and  $r \in \mathbb{N}$ , FIND  $\mathbf{W} \in \mathbb{R}^{m \times r}$  and  $\mathbf{H} \in \mathbb{R}^{r \times n}$  such that Matrix Factorization  $M \in \mathbb{R}^{m \times n}$  ≈ W

by solving

$$\begin{split} \min \ \frac{1}{2} \|\mathbf{M} - \mathbf{W}\mathbf{H}\|_{F}^{2} \quad \text{s.t.} \quad \mathbf{H} \geq \mathbf{0}, \\ \mathbf{w}_{j} \in \mathcal{U}_{+}^{m} \text{ for all } j \in [r], \\ \mathbf{w}_{j}^{\top} \mathbf{1}_{m} = 1 \text{ for all } j \in [r], \end{split}$$

- ▶ Apply Nu characterization:  $\mathbf{w}_j \in \mathcal{U}^m_+ \rightarrow \mathbf{U}_{p_j} \mathbf{w}_j \ge \mathbf{0}$ , where integers  $p_1, p_2, \ldots, p_r$  are unknown.
- ► How to solve: BCD.
  - ► Subproblem on **H** is simple.
  - ► Main difficulty: subproblem on W.

HALS: Column-wise block coordinate descent

$$\frac{1}{2} \|\mathbf{M} - \mathbf{W}\mathbf{H}\|_{F}^{2} = \frac{1}{2} \left\|\mathbf{M} - \sum_{j=1}^{r} \mathbf{w}_{j} \mathbf{h}^{j}\right\|_{F}^{2}$$
$$= \frac{1}{2} \left\|\underbrace{\mathbf{M} - \sum_{j \neq i}^{r} \mathbf{w}_{j} \mathbf{h}^{j}}_{:=\mathbf{M}_{i}} - \underbrace{\mathbf{w}_{i} \mathbf{h}^{i}}_{:=\mathbf{M}_{i}}\right\|_{F}^{2}$$

$$= \frac{1}{2} \|\mathbf{M}_i - \mathbf{w}_i \mathbf{h}^i\|_F^2$$

= a quadratic function on  $\mathbf{w}_i$ 

m

$$= \frac{h^{i}}{w_{i}} + + \frac{1}{7/18}$$

#### The $w_i$ -subproblem

► A Linearly-Constrained Quadratic Program, cvx:

$$\min_{\mathbf{w}_i} \frac{\|\mathbf{h}^i\|_2^2}{2} \|\mathbf{w}_i\|_2^2 - \langle \mathbf{M}_i {\mathbf{h}^i}^\top, \mathbf{w}_i \rangle \quad \text{s.t.} \quad \underbrace{\mathbf{U}_{p_i} \mathbf{w}_i \ge \mathbf{0}}_{\mathbf{w}_i \in \mathcal{U}_+^{m, p_i}}, \quad \mathbf{w}_i^\top \mathbf{1} = 1, \quad (*)$$

Involves integer variables, ncvx:

$$\min_{\mathbf{w}_i, \mathbf{p}_i} \frac{\|\mathbf{h}^i\|_2^2}{2} \|\mathbf{w}_i\|_2^2 - \langle \mathbf{M}_i \mathbf{h}^i^\top, \mathbf{w}_i \rangle \quad \text{s.t. } \mathbf{w}_i \in \mathcal{U}_+^m, \ \mathbf{w}_i^\top \mathbf{1} = 1, \quad (**)$$

- Brute-force: solve (\*) on all p, pick the best one as  $p_i$  to solve (\*\*).
- Directly solving (\*\*) by proximal gradient is not scalable (\$\$\$).
   Proximal gradient on (\*\*) = a 2-branch isotonic projection.
   Isotonic projection: x ≤ y ⇒ P<sub>K</sub>x ≤ P<sub>K</sub>y.

## Speed up the brute-force algorithm for large m

$$\min_{\mathbf{w}_{i}} \frac{\|\mathbf{h}^{i}\|_{2}^{2}}{2} \|\mathbf{w}_{i}\|_{2}^{2} - \langle \mathbf{M}_{i} \mathbf{h}^{i^{\top}}, \mathbf{w}_{i} \rangle \quad \text{s.t.} \quad \mathbf{U}_{p_{i}} \mathbf{w}_{i} \ge \mathbf{0}, \ \mathbf{w}_{i}^{\top} \mathbf{1} = 1, \qquad (*)$$

$$\min_{\mathbf{w}_{i}, \mathbf{p}_{i}} \frac{\|\mathbf{h}^{i}\|_{2}^{2}}{2} \|\mathbf{w}_{i}\|_{2}^{2} - \langle \mathbf{M}_{i} \mathbf{h}^{i^{\top}}, \mathbf{w}_{i} \rangle \quad \text{s.t.} \quad \mathbf{U}_{p_{i}} \mathbf{w}_{i} \ge \mathbf{0}, \ \mathbf{w}_{i}^{\top} \mathbf{1} = 1, \qquad (**)$$

- Brute-force on p in [m] ok if m small.
- Speed up:
  - 1. solve (\*) by accelerated projected gradient.
  - 2. reduce search space for  $p_i$  in (\*\*) by dimension reduction: multi-grid
    - Multi-grid preserves Nu: a theorem with proof in 3 sentences!
    - Other techniques such as PCA or Gaussian sampling do not work here as they destroy the Nu.

Speed up 1 : Accelerated Projected Gradient solving (\*)

$$\min_{\mathbf{w}_{i}} \frac{\|\mathbf{h}^{i}\|_{2}^{2}}{2} \|\mathbf{w}_{i}\|_{2}^{2} - \langle \mathbf{M}_{i} \mathbf{h}^{i^{\top}}, \mathbf{w}_{i} \rangle \quad \text{s.t.} \underbrace{\mathbf{U}_{p_{i}} \mathbf{w}_{i} \geq \mathbf{0}, \ \mathbf{w}_{i}^{\top} \mathbf{1} = 1}_{\text{hard to project}}. \quad (*)$$

• Transform (\*) via  $\mathbf{y} = \mathbf{U}\mathbf{w}$ :

$$\min_{\mathbf{y}} \frac{1}{2} \left\langle \|\mathbf{h}^{i}\|_{2}^{2} \mathbf{U}_{p_{i}}^{-\top} \mathbf{y}, \mathbf{y} \right\rangle - \left\langle \mathbf{U}_{p_{i}}^{-\top} \mathbf{M}_{i} \mathbf{h}^{i^{\top}}, \mathbf{y} \right\rangle \text{ s.t. } \mathbf{y} \geq \mathbf{0}, \mathbf{y}^{\top} \mathbf{U}_{p_{i}}^{-\top} \mathbf{1} = 1$$

equivalently

$$\min_{\mathbf{y}} \frac{1}{2} \langle \mathbf{Q} \mathbf{y}, \mathbf{y} \rangle - \langle \mathbf{p}, \mathbf{y} \rangle \quad \text{s.t. } \mathbf{y} \ge \mathbf{0}, \ \mathbf{y}^{\top} \mathbf{b} = 1.$$
 (\*')

• 
$$\mathbf{y}^*$$
 of  $(*')$  gives  $\mathbf{w}_i^*$  of  $(*)$  by  $\mathbf{y} = \mathbf{U}\mathbf{w}$ .

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Speed up 1: APG on solving v

$$\min_{\mathbf{y}} \frac{1}{2} \langle \mathbf{Q} \mathbf{y}, \mathbf{y} \rangle - \langle \mathbf{p}, \mathbf{y} \rangle \quad \text{s.t. } \mathbf{y} \ge \mathbf{0}, \ \mathbf{y}^{\top} \mathbf{b} = 1.$$
 (\*')

- ► Projection:  $P(\mathbf{z}) = \underset{\mathbf{v}}{\operatorname{argmin}} \frac{1}{2} \|\mathbf{y} \mathbf{z}\|_{2}^{2} \text{ s.t. } \mathbf{y} \ge \mathbf{0}, \ \mathbf{y}^{\top} \mathbf{b} = 1.$
- Optimal sol. by partial Lagrangian

$$\mathbf{y}^* \stackrel{(*)}{=} \min_{\mathbf{y} \ge \mathbf{0}} \max_{\nu} \underbrace{\frac{1}{2} \|\mathbf{y} - \mathbf{z}\|_2^2 + \nu(\mathbf{y}^\top \mathbf{b} - 1)}_{L(\mathbf{y},\nu)} = \underbrace{[\mathbf{z} - \nu^* \mathbf{b}]_+}_{\text{soft-thresholding}},$$

Lagrangian multiplier  $\nu^*$  is the root of a piece-wise linear eqn.

$$\sum_{i=1}^{m} \max\left\{0, z_i - \nu b_i\right\} b_i = 1,$$

which costs  $\mathcal{O}(m)$  to  $\mathcal{O}(m \log m)$  to solve by sorting the break points  $\frac{z_i}{b}$ . After sorting, the magical-one-line-code that no one can read is nu = max((cumsum(z.\*b)-1)./(cumsum(b.\*b)));11 / 18

The problem satisfies the Slater's condition which guarantees strong duality. (\*):

Speed up 2: Multi-level / multi-grid

- ► Idea: instead of working on w, work on R<sub>N</sub>...R<sub>1</sub>w with smaller search space of p.
- Restriction  $\mathbf{R} \in \mathbb{R}^{m_1 \times m}_+$  changes  $\mathbf{x} \in \mathbb{R}^m_+$  to  $\mathbf{R}\mathbf{x} \in \mathbb{R}^{m_1}_+$ ,  $m_1 < m$ .

$$\mathbf{R}(a,b) = \begin{bmatrix} a & b & & & \\ & b & a & b & & \\ & & \ddots & \ddots & \ddots & \\ & & b & a & b \\ & & & & b & a \end{bmatrix}, \begin{array}{l} a > 0, b > 0, \\ a + 2b = 1. \end{array}$$

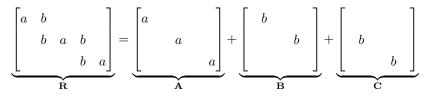
▶ Theorem (if x is NU, then Rx is Nu) Let  $\mathbf{x} \in \mathcal{U}_{+}^{m,p}$  with p is even<sup>2</sup> and  $\mathbf{R} \in \mathbb{R}^{m_1 \times m}$ . Then  $\mathbf{y} = \mathbf{R}\mathbf{x} \in \mathcal{N}_{+}^{m_1,p_y}$  with  $\mathcal{N}_{+}^{m,p} = \mathcal{U}_{+}^{m,p} \cup \mathcal{U}_{+}^{m,p+1}$  and  $p_y \in \{\lfloor \frac{p}{2} + 1 \rfloor, \lfloor \frac{p}{2} \rfloor\}$ .

 $^2{\rm lf}\ p$  is odd, by considering the vector  $[0,{\bf x}]$  does not change the unimodality and increases p by one.

The three-sentence proof

Goal: show  $\mathbf{R}\mathbf{x}$  is Nu if  $\mathbf{x}$  is Nu.

1. Decomposition of  ${\bf R}$ 



So  $\mathbf{R}\mathbf{x} = \mathbf{A}\mathbf{x} + \mathbf{B}\mathbf{x} + \mathbf{C}\mathbf{x}$ 

2.  $\mathbf{Ax}$ ,  $\mathbf{Bx}$  and  $\mathbf{Cx}$  are Nu

: subvector of Nu vector is Nu.

3. The sum Ax + Bx + Cx is Nu

 $\therefore$  their p differ at most 1.

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The whole algorithm (in words) for  $\mathsf{NuMF}(\mathbf{M},r)$ 

Steps:

- 1. Restrict:  $\mathbf{M}^{[N]} = \mathbf{R}_N \dots \mathbf{R}_1 \mathbf{M}$  and  $\mathbf{W}_0^{[N]} = \mathbf{R}_N \dots \mathbf{R}_1 \mathbf{W}_0$ .
- 2. Solve coarse problem: brute-force and APG on

$$[\mathbf{W}_*^{[N]}, \mathbf{H}_*, \mathbf{p}_*^{[N]}] \leftarrow \mathrm{NuMF}(\mathbf{M}^{[N]}, \mathbf{W}_0^{[N]}, \mathbf{H}_0).$$

- 3. Interpolate:  $[\mathbf{W}_0, \mathbf{p}_0] \leftarrow \operatorname{Interpolate}(\mathbf{W}_*^{[N]}, \mathbf{p}_*^{[N]}).$
- 4. Solve the original fine problem:

$$[\mathbf{W}_*, \mathbf{H}_*, \mathbf{p}_*] \leftarrow \mathrm{NuMF}(\mathbf{M}, \mathbf{W}_0, \mathbf{H}_0, \mathbf{p}_0).$$

no brute-forcing!

### Convergence

- Optimization: sequence converge to a local minima.
- Linear Algebra: sequence converge to a global minima. Identifiability – when does solving NuMF give a unique sol? Three identifiability results for three special cases.

See paper for details.

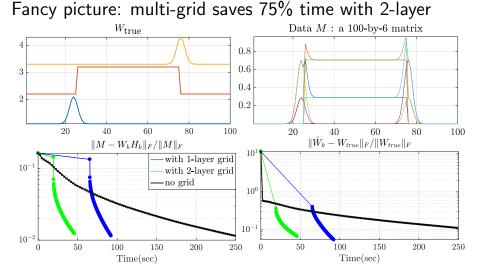
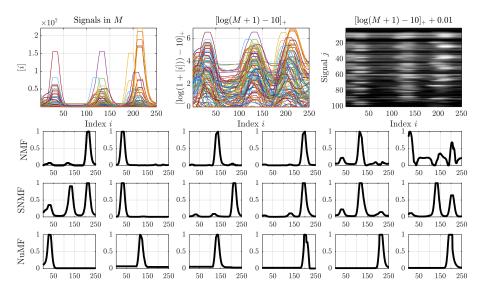


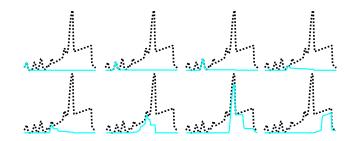
Figure: Experiment on a toy example. All algo. run 100 iterations with same initialization. For algo. with MG, the computational time taken on the coarse grid are also taken into account, as reflected by the time gap between time 0 and the first dot in the curves. 15 / 18

## Fancy picture: on Belgian beers



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#### Fancy picture: on r > n



- On a data vector in  $\mathbb{R}^{947}_+$  (black curve) with r = 8 > 1 = n.
- Cyan curves are the components  $\mathbf{w}_i h_i$ .
- Relative error  $\|\mathbf{M} \mathbf{W}\mathbf{H}\|_F / \|\mathbf{M}\|_F = 10^{-8}$ .
- The first two peaks in the data satisfy an identifiability Theorem, NuNMF identifies them perfectly.
- ▶ For the other peaks: supports overlap, decomposition not unique.

#### Last page - summary

- ► NuMF problem: nonconvex and block-nonconvex.
- Nu characterization and brute-force
- Acceleration by APG and MG
- Identifiability of NuMF (Not discussed in-depth)
- Applications
- References
  - ► A, Gillis, Vandaele and De Sterck, "Nonnegative Unimodal Matrix Factorization".
  - Chapter 5 of my thesis "Nonnegative Matrix and Tensor Factorizations: Models, Algorithms and Applications".
- Slide, paper, code at angms.science