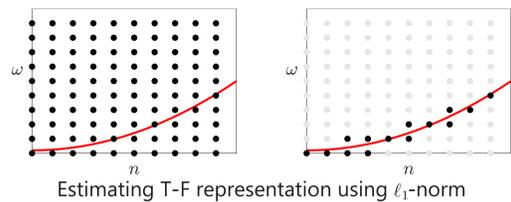


Introduction

Aim: Estimate a well-localized time-frequency representation

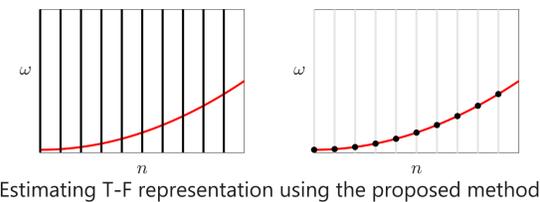
- Nonstationary signals are commonly analyzed and processed in the time-frequency (T-F) domain.
- A T-F representation obtained by the discrete Gabor transform (DGT) is **spread due to windowing of an analyzed signal**.
- Sparse estimation using the ℓ_1 -norm **needs to discretize a continuous parameter onto a grid** [1].
→ may **degrade the performance due to a model mismatch**.



Proposal:

Sparse T-F representation via atomic norm minimization

- Atomic norm [2]
 - Sparse optimization technique **without discretization of continuous parameters**
 - Corresponding to **an infinite-dimensional dictionary of ℓ_1 -norm**
- Introducing atomic norm into sparse T-F estimation **avoids the effect of the grid mismatch**.



Sparse T-F representation

Gabor system and discrete Gabor transform

- A Gabor system is defined as a collection of sinusoids modulated by \mathbf{g} .

$$\mathcal{G}(\mathbf{g}, a, M) = \{\mathbf{g}_{m,n}\}_{m=0,\dots,M-1, n=0,\dots,N-1}$$

$$\mathbf{g}_{m,n}[l] = e^{i\frac{2\pi m(l-an)}{M}} \mathbf{g}[l-an]$$

- DGT and the inverse DGT with respect to the Gabor system $\mathcal{G}(\mathbf{g}, a, M)$:

$$(\mathbf{G}_g^* \mathbf{f})[m+nM] = \langle \mathbf{f}, \mathbf{g}_{m,n} \rangle, \quad \mathbf{G}_g \mathbf{c} = \sum_{m,n} \mathbf{c}[m+nM] \mathbf{g}_{m,n}$$

- A T-F representation $\mathbf{c} \in \mathbb{C}^{MN}$ satisfying $\mathbf{f} = \mathbf{G}_g \mathbf{c}$ can be obtained by DGT with a dual window \mathbf{h} associated with \mathbf{g} .

Sparse T-F representation using ℓ_1 -norm [1]

- The T-F representation \mathbf{c} is a redundant representation of a signal \mathbf{f} .
→ The T-F representation \mathbf{c} satisfying $\mathbf{f} = \mathbf{G}_g \mathbf{c}$ is not unique.
- Find a sparse \mathbf{c} satisfying $\mathbf{f} = \mathbf{G}_g \mathbf{c}$ using ℓ_1 -norm.

$$\underset{\mathbf{c}}{\text{minimize}} \quad \|\mathbf{c}\|_1 \quad \text{subject to} \quad \mathbf{f} = \mathbf{G}_g \mathbf{c}$$

- This problem is convex
→ can be **efficiently solved by convex optimization algorithms**.
- This formulation may provide **a poor result when the signal \mathbf{f} has a component whose frequency is not included in the grid**.

Atomic norm

Line spectrum estimation using atomic norm

- A windowed signal at time index n is denoted as $\mathbf{f}_n = \mathbf{W}_n \mathbf{f}$.
- \mathbf{W}_n is a diagonal matrix whose diagonal elements are $\mathbf{g}[l-an]$.
- We assume that the n th windowed signal is superimposed by atoms in $\mathcal{A} = \{\mathbf{a} \in \mathbb{C}^L \mid \mathbf{a}[l] = e^{i2\pi\omega l}, \omega \in [0, 1)\}$.

$$\mathbf{f}_n = \mathbf{W}_n \sum_k c_{n,k} \mathbf{a}_{n,k}, \quad \mathbf{a}_{n,k} \in \mathcal{A}.$$

- The atomic norm of \mathbf{x}_n associated with a set of atoms \mathcal{A} is given by

$$\|\mathbf{x}_n\|_{\mathcal{A}} = \inf \left\{ \sum_k |c_{n,k}| \mid \mathbf{x}_n = \sum_k c_{n,k} \mathbf{a}_{n,k}, \mathbf{a}_{n,k} \in \mathcal{A} \right\}.$$

- Line spectrum estimation using the atomic norm is formulated as

$$\underset{\mathbf{x}_n}{\text{minimize}} \quad \|\mathbf{x}_n\|_{\mathcal{A}} \quad \text{subject to} \quad \mathbf{f}_n = \mathbf{W}_n \mathbf{x}_n.$$

Semidefinite programming formulation of atomic norm

- The atomic norm is characterized by a semidefinite programming.

$$\|\mathbf{x}_n\|_{\mathcal{A}} = \min_{\mathbf{u}_n, \nu_n} \frac{1}{2L} \text{Tr}(T(\mathbf{u}_n)) + \frac{1}{2} \nu_n$$

$$\text{subject to} \quad \begin{bmatrix} T(\mathbf{u}_n) & \mathbf{x}_n \\ \mathbf{x}_n^* & \nu_n \end{bmatrix} \succeq 0$$

- $T(\mathbf{u})$ is the Hermitian Toeplitz matrix whose first row is \mathbf{u} .
- $\mathbf{a}_{n,k}$ can be obtained by the Vandermonde decomposition of $T(\mathbf{u})$.
- Thus, the line spectrum estimation problem is reformulated as

$$\underset{\mathbf{x}_n, \mathbf{u}_n, \nu_n}{\text{minimize}} \quad \frac{1}{2L} \text{Tr}(T(\mathbf{u}_n)) + \frac{1}{2} \nu_n$$

$$\text{subject to} \quad \begin{bmatrix} T(\mathbf{u}_n) & \mathbf{x}_n \\ \mathbf{x}_n^* & \nu_n \end{bmatrix} \succeq 0, \quad \mathbf{f}_n = \mathbf{W}_n \mathbf{x}_n.$$

Proposed method

Sparse T-F representation using atomic norm

- Inducing sparsity by **a sum of atomic norms** under the constraint of **the reconstruction of the entire signal**

$$\underset{\mathbf{x}}{\text{minimize}} \quad \sum_{n=0}^{N-1} \|\mathbf{x}_n\|_{\mathcal{A}} \quad \text{subject to} \quad \mathbf{f} = \mathbf{A}_g \mathbf{x}.$$

$$-\mathbf{x} = [\mathbf{x}_0^T, \mathbf{x}_1^T, \dots, \mathbf{x}_{N-1}^T]^T$$

- A sum of atomic norms for time index n

$$\min_{\mathbf{x}} \sum_{n=0}^{N-1} \|\mathbf{x}_n\|_{\mathcal{A}} = \inf \left\{ \sum_{n,k} |c_{n,k}| \mid \mathbf{x}_n = \sum_k c_{n,k} \mathbf{a}_{n,k}, \mathbf{a}_{n,k} \in \mathcal{A} \right\}$$

- corresponding to the grid-less version of the ℓ_1 -norm-based method.

- Reconstructing the signal \mathbf{f} by windowing and summing \mathbf{x}_n

$$\mathbf{A}_g \mathbf{x} = \sum_{n=0}^{N-1} \mathbf{W}_n \mathbf{x}_n$$

Algorithm for solving this problem

- Semidefinite programming formulation of the proposed method

$$\underset{\mathbf{x}, \mathbf{u}, \nu}{\text{minimize}} \quad \sum_{n=0}^{N-1} \frac{1}{2L} \text{Tr}(T(\mathbf{u}_n)) + \frac{1}{2} \nu_n$$

$$\text{subject to} \quad \begin{bmatrix} T(\mathbf{u}_n) & \mathbf{x}_n \\ \mathbf{x}_n^* & \nu_n \end{bmatrix} \succeq 0, \quad \text{for } n = 0, \dots, N-1$$

$$\mathbf{f} = \mathbf{A}_g \mathbf{x}$$

- Alternating direction method of multipliers (ADMM) for solving this problem.

- $P_C(\cdot)$: The projection onto the set $C = \{\mathbf{x} \mid \mathbf{A}_g \mathbf{x} = \mathbf{f}\}$

$$P_C(\mathbf{v}) = \mathbf{v} - \mathbf{A}_g^* (\mathbf{A}_g \mathbf{A}_g^*)^{-1} (\mathbf{A}_g \mathbf{v} - \mathbf{f}).$$

- $T^\dagger(\cdot)$: The pseudo-inverse operator of T

$$T^\dagger(\mathbf{X})[n] = \frac{1}{2(L-n)} \sum_{k=0}^{L-n-1} (\mathbf{X}[k, k+n] + \overline{\mathbf{X}[k+n, k]}).$$

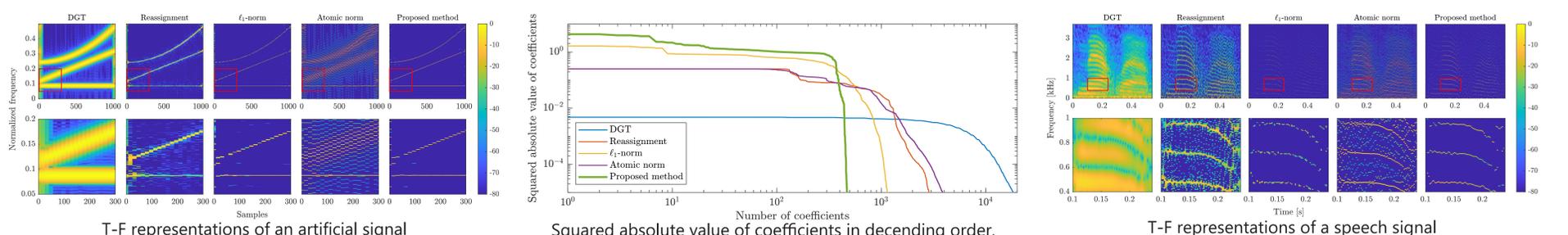
- $P_{\mathbb{S}_+}$: The projection onto the positive semidefinite cone

Algorithm 1 Proposed algorithm

Input: $\mathbf{A}, \mathbf{f}, \rho$
Output: $\mathbf{x}, \mathbf{u}, \nu$
Initialize \mathbf{Z}_n and Λ_n for $n = 0, \dots, N-1$
for $i = 0, 1, \dots$ do
for $n = 1, \dots, N$ do
 $\mathbf{x} \leftarrow P_C(\mathbf{z}_n - \frac{1}{\rho} \lambda_n)$
 for $n = 1, \dots, N$ do
 $\mathbf{u}_n \leftarrow T^\dagger(\mathbf{Z}_{Tn} - \frac{1}{\rho} (\Lambda_{Tn} - \frac{1}{2} \mathbf{I}_L))$
 $\nu_n \leftarrow z_{\nu n} - \frac{1}{\rho} (\lambda_{\nu n} - \frac{1}{2})$
 $\mathbf{Z}_n \leftarrow P_{\mathbb{S}_+} \left(\begin{bmatrix} T(\mathbf{u}_n) & \mathbf{x}_n \\ \mathbf{x}_n^* & \nu_n \end{bmatrix} + \frac{1}{\rho} \Lambda_n \right)$
 $\Lambda_n \leftarrow \Lambda_n + \rho \left(\begin{bmatrix} T(\mathbf{u}_n) & \mathbf{x}_n \\ \mathbf{x}_n^* & \nu_n \end{bmatrix} - \mathbf{Z}_n \right)$
 end for
end for

Numerical experiment

- The T-F representations obtained by the proposed method were **the most-localized among these T-F representations**.
→ The proposed method provides **a sparser T-F representation via atomic norm minimization as a result of avoiding the grid mismatch**.



[1] E. Sejdić, I. Orović, and S. Stanković, "Compressive sensing meets time-frequency: An overview of recent advances in time-frequency processing of sparse signals," Digital Signal Process., vol. 77, pp. 22–35, 2018.
[2] Y. Chi and M. Ferreira Da Costa, "Harnessing sparsity over the continuum: Atomic norm minimization for superresolution," IEEE Signal Process. Mag., vol. 37, no. 2, pp. 39–57, 2020.