



# Sub-band Adaptive Low Light Image Enhancement Using Wavelet-Based Convolutional Neural Networks

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# Low light image enhancement



Low light image

**Gamma correction** 

#### **Proposed method**

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Low light image

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**Proposed method** 

Low light images: Low contrast, much noise and weak color.

### **Motivation**

### Sub-band adaptive processing

In wavelet analysis, signal is often decomposed to low- and high-frequency subbands, which low-frequency sub-band provides approximate information and highfrequency sub-bands provide image details. Most noise is contained in the high frequency sub-bands.

#### Wavelet transform's advantages

1) Perfect reconstruction ability to ensure that there is no information loss and redundant information;

2) Can effectively extract significant information such as textures and edges.

# **Contributions**

- Subband adaptive low light image enhancement based on discrete wavelet transform (DWT)
  - Decompose an image into LL band and HL, LH, HH bands to separately solve different low image problems: low lightness and noise.
- Well-designed CNN for low light image enhancement
  - Add the new luminance reinforcement layers into U-net framework to realize global brightness enhancement.
  - Design a new Feature Fusion network to achieve denoising and enhancement on the LH, HL, HH bands.
  - Introduce a chain of residual blocks as Refinement network to complete image details.

### **Proposed Method**



# **Proposed Method: Contrast enhancement for LL band**



Adopt **U-Net** as the basic enhancement framework to increase local receptive fields for connecting more pixels.

Only using U-Net leads to the image background to be darker, we introduce **luminance reinforcement layers** for extending contrast dynamic range.

### **Proposed Method: Loss function for LL band**

$$L_{CE} = w_1 L_{re} + w_2 L_{col}$$

• Use the SSIM loss to define  $L_{re} = \frac{1}{N} \sum_{p} 1 - SSIM(F(I(p)), gt)(gt \text{ means LL})$ band of ground truth), which can take brightness, contrast and structure into consideration.

• Only use SSIM loss results in brightness change and color deviation, so introduce L1 Loss to define  $L_{col} = ||F(I) - gt||_1$  for keeping brightness and color constancy.

# **Proposed Method: Noise reduction for HL, LH, HH bands**



Based on that shallow network extracts the detail information and deep network extracts the high level semantic information and most of noise exists in the detail information,

Thus, we set low parameters(<0.5) on the shallow layers and high parameters(>1) on the deep layers for noise reduction, then fuse adjusted features for reconstruction.

### **Proposed Method: Loss function for HL, LH, HH bands**

 $L_{NR} = L_{re} + \beta L_{intensity}$ 

• Also use the SSIM loss to define  $L_{re} = \frac{1}{N} \sum_{p} 1 - SSIM(F(I(p)), gt)(gt)$  means high bands of ground truth).

• SSIM loss results in weaker constrains on the difference of the intensity distribution, so introduce L2 Loss to define  $L_{intensity} = ||F(I) - gt||_2$  for keeping intensity distribution.

# **Proposed Method: Refinement for Inverse transform result**



As a result of the IDWT results occur edge blur and color shifts, so using **a series of residual blocks** as the finetune network to extract useful information for recovering lost textural details in the component network.

$$L_{refin} = \frac{1}{N} \sum_{p} 1 - SSIM(F(I(p)), gt)$$

Use SSIM loss to reduce the difference between the final result and ground truth in brightness, contrast and structure.

# **Experimental Details**

HW: GTX 2080 TI

**SW:** Python + PyTorch

#### Training details:

- 1) Contrast enhancement network: batch\_size=64 epoch=500 lr=1e-4 optimizer=Adam
- 2) Noise redution network: batch\_size=64 epoch=500 lr=1e-4 optimizer=Adam C=[0.2, 0.3, 2, 3]
- 3) Refinement network: batch\_size=16, epoch=50, lr=1e-4 optimizer=Adam

**Evaluation metrics:** PSNR, SSIM, No-Reference IQA(NIQE)

#### **Compared methods:**

- RetinexNet: Deep Retinex Decomposition for Low-Light Enhancement, Retinex Net.
- Zero-DCE: Zero-Reference Deep Curve Estimation for Low-Light Image Enhancement.
- Self-supervised: Self-supervised Image Enhancement Network: Training with Low Light Images Only.
- LIME: Low-light Image Enhancement via Illumination Map Estimation.
- DLN: Lighting Network for Low-Light Image Enhancement.

# **Experimental results**



Zero-DCE

Self-Supervised

Proposed





Zero-DCE

DLN

Self-Supervised

Proposed

Visual comparison on LOL dataset





Zero-DCE

DLN

Self-Supervised





Input



LIME





Zero-DCE



Self-Supervised

Proposed

#### Visual comparison on NPE dataset



The images on the right turn represents the results on LIME, RetinexNet, Zero-DCE, DLN, Self-Supervised, Proposed Method.

Visual comparison on ExDark dataset

# **Ablation study**



Without noise reduction

Without refinement

Final results

Ground Truths

# **Quantitative measurements**

Dataset	LOL			NPE			ExDark
Methods	PSNR	SSIM	NIQE	PSNR	SSIM	NIQE	NIQE
LIME	12.65	0.5469	9.127	12.11	0.6142	13.61	11.40
RetinexNet	18.40	0.7320	9.730	17.14	0.7014	12.95	12.16
Zero-DCE	13.14	0.5728	11.304	10.32	0.4554	15.26	17.51
DLN	23.82	0.8543	4.915	14.79	0.6777	13.34	15.04
Self-supervised	22.06	0.7201	4.793	17.12	0.7280	15.36	18.84
Proposed	24.93	0.8759	4.332	18.32	0.7473	15.45	16.61

### **Conclusions**

- DWT is a useful method on low light image enhancement by adaptively processing low frequency component (LL band) and high frequency components (HL, LH, HH bands).
- Experimental results show that the proposed method can effectively eliminate noise while achieving image enhancement and its performance is better than the state-of-the-art methods.

**Thank You!**