# Accelerated Spectral Clustering Using Graph Filtering of Random Signals

Nicolas Tremblay<sup>(1,2,3)</sup>, Gilles  $Puy^{(1)}$ , Pierre Borgnat<sup>(2)</sup>, Rémi Gribonval<sup>(1)</sup>, Pierre Vandergheynst<sup>(1,3)</sup>

PANAMA Team, INRIA Rennes, France
 Physics Laboratory, Ens de Lyon, CNRS, France
 Signal Processing Laboratory 2, EPFL, Switzerland







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"Compressive spectral embedding : sidestepping the SVD", NIPS '15 D. Ramasamy and U. Madhow, UC Santa Barbara







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# What's clustering?

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Given a series of N objects :

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Given a series of N objects :

 $\begin{array}{c} 0 & 0 & 1 & 1 & 1 & 2 & 2 & 3 & 3 & 3 & 4 & 4 & 4 \\ 1 & \text{Find adapted} \\ \text{descriptors} & \downarrow \\ 2 & 2 \\ 1 & 2 \\ 1 & 2 \\ 1 & 2 \\ 1 & 3 \\ 4 & 0 & 3 \\ 4 & 0 & 3 \\ 4 & 4 & 3 \end{array}$ 

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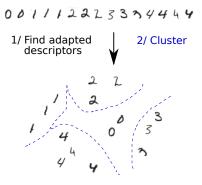
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#### After step 1, one has :

• *N* vectors in *d* dimensions (descriptor dimension) :

$$\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_N \in \mathbb{R}^d$$

• and their distance matrix  $\Delta \in \mathbb{R}^{N \times N}$ .

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<u>Goal of clustering</u> : assign a label  $c(i) = 1, \dots, k$  to each object i in order to organize / simplify / analyze the data.

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<u>Goal of clustering</u> : assign a label  $c(i) = 1, \dots, k$  to each object i in order to organize / simplify / analyze the data.

There exists two different general types of methods :

- methods directly based on the *x<sub>i</sub>* and/or Δ like *k*-means or hierarchical clustering.
- graph-based methods.

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### Graph construction from the distance matrix $oldsymbol{\Delta}$

Create a graph  $\mathcal{G} = (V, E)$  :

- each node in V is one of the N objects
- each pair of nodes (i, j) is connected if the associated distance  $\Delta(i, j)$  is small enough.

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### Graph construction from the distance matrix $oldsymbol{\Delta}$

Create a graph  $\mathcal{G} = (V, E)$  :

- each node in V is one of the N objects
- each pair of nodes (i, j) is connected if the associated distance  $\Delta(i, j)$  is small enough.
- For example, two connectivity possibilities :
  - Gaussian kernel :
    - 1. all pairs of nodes are connected with links of weights  $\exp(-\Delta(i,j)/\sigma)$
    - 2. remove all links of weight inferior to  $\boldsymbol{\epsilon}$
  - k nearest neighbors : connect each node to its k nearest neighbors.

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#### The problem now states :

Given the graph G representing the similarity between the N objects, find a partition of all nodes in k clusters.

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#### The problem now states :

Given the graph G representing the similarity between the N objects, find a partition of all nodes in k clusters.

Many methods exist [Fortunato '10] :

- Modularity (or other cost-function) optimisation methods [Newman '06]
- Random walk methods [Schaub '12]
- Methods inspired from statistical physics [Krzakala '13], information theory [Rosvall '08]...
- spectral methods
- ...

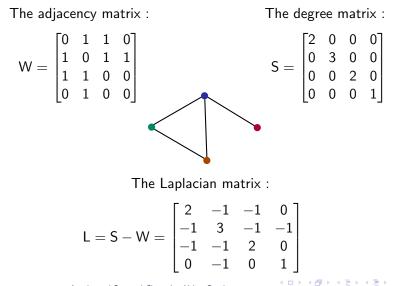
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#### Three useful matrices



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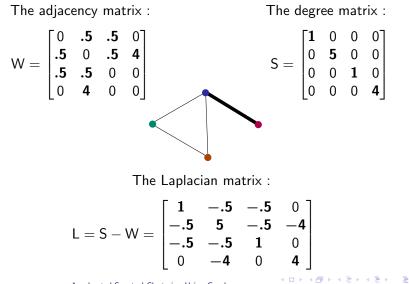
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#### Three useful matrices



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The classical spectral clustering algorithm [Von Luxburg '06] :

Given the N-node graph  $\mathcal G$  of laplacian matrix L :

1. Compute L's first k eigenvectors :

$$U_k = (\boldsymbol{u}_1 | \boldsymbol{u}_2 | \cdots | \boldsymbol{u}_k).$$

2. Consider each node *i* as a point in  $\mathbb{R}^k$ :

$$f_i = U_k^{\top} \delta_i.$$

3. Run *k*-means with the Euclidean distance :  $D_{ij} = ||\mathbf{f}_i - \mathbf{f}_j||$  and obtain *k* clusters.

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3. Run *k*-means with the Euclidean distance :  $D_{ij} = ||\mathbf{f}_i - \mathbf{f}_j||$  and obtain *k* clusters.

Definition : Let us call  $D_{ij}$  the spectral clustering distance.

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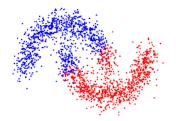
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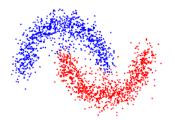
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#### What's the point of using a graph?

N points in d = 2 dims. Result with k-means (k=2) on  $\Delta$ :



After creating a graph, partial daigonalisation of L and running k-means (k=2) on **D** :



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#### Overview

Problem : When N and/or k become too large, there are two main bottlenecks in the algorithm :

- 1. The partial eigendecomposition of the (sparse) Laplacian with restarted Arnoldi method  $[O(k^3 + Nk^2 + N\#Ek)]$  [Chen '11a]
- 2. high-dimensional k-means.

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- 2. high-dimensional k-means.
- Goal : Circumvent bottleneck #1. Scheme of existing lines of work :
  - approximate U<sub>k</sub> : Ũ<sub>k</sub> via power methods [O(pk#E)] [Lin '10, Boutsidis '15] or Nystrom-type methods [O(n<sup>3</sup> + nN)] [Fowlkes '04, Wang '09, Chen '11b, ...].
  - 2. compute approximate feature vectors  $\tilde{\mathbf{f}}_i = \tilde{U}_k^{\top} \boldsymbol{\delta}_i \simeq \mathbf{f}_i$ .
  - 3. compute approximate spectral distance  $\tilde{D}_{ij} = \|\tilde{f}_i \tilde{f}_j\| \simeq D_{ij}$ .

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- 3. compute approximate spectral distance  $\tilde{D}_{ij} = \|\tilde{f}_i \tilde{f}_j\| \simeq D_{ij}$ . Contribution : directly estimate  $D_{ij}$  without approximating  $U_k$  in  $O(m \# E \log N)$ .

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# Filtering random graph signals for clustering

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What's graph signal filtering? [Shuman '13]

• U is the Fourier basis of the graph

 $\mathsf{L} = \mathsf{S} - \mathsf{W} = \mathbf{U} \mathsf{\Lambda} \mathbf{U}^\top$ 

• the Fourier transform of a signal f

reads : 
$$\hat{f} = \mathbf{U}^{\top} f$$

•  $\Lambda = Diag(\lambda_1, \lambda_2, \cdots, \lambda_N)$  the spectrum

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What's graph signal filtering? [Shuman '13]

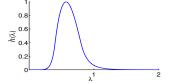
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Given a filter function *h* defined in the Fourier space.



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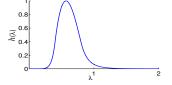
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Given a filter function *h* defined in the Fourier space.



In the node space, the signal f filtered by h reads :

$$f^h = \bigcup h(\Lambda) \bigcup^\top f = \mathsf{H}f$$

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# So where's the link with clustering?

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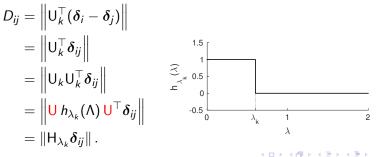
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#### Remember : the classical spectral clustering algorithm

Given the N-node graph  ${\mathcal G}$  of adjacency matrix W :

- 1. Compute L's first k eigenvectors :  $U_k = (\boldsymbol{u}_1 | \boldsymbol{u}_2 | \cdots | \boldsymbol{u}_k)$ .
- 2. Consider each node *i* as a point in  $\mathbb{R}^k$ :  $\mathbf{f}_i = \bigcup_k^\top \boldsymbol{\delta}_i$ .
- 3. Run k-means with  $D_{ij} = ||\mathbf{f}_i \mathbf{f}_j||$  and obtain k clusters.

Our goal : Estimate  $D_{ij}$  without computing exactly  $U_k$ .



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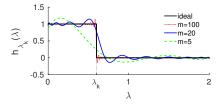
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#### Fast filtering [Hammond, ACHA '11]

In practice, we use a poly approx of order *m* of  $h_{\lambda_{\mu}}$ :

$$\tilde{h}_{\lambda_k} = \sum_{l=1}^m \alpha_l \lambda^l \simeq h_{\lambda_k}.$$



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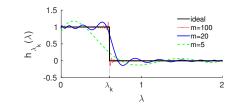
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Indeed, in this case, filtering a signal  $\boldsymbol{f}$  reads :

$$\mathsf{H}_{\lambda_k}\boldsymbol{f}\simeq \tilde{\mathsf{H}}_{\lambda_k}\boldsymbol{f}=\boldsymbol{\mathsf{U}}\tilde{h}_{\lambda_k}(\Lambda)\boldsymbol{\mathsf{U}}^{\top}\boldsymbol{f}=\boldsymbol{\mathsf{U}}\sum_{l=1}^m\alpha_l\Lambda^l\boldsymbol{\mathsf{U}}^{\top}\boldsymbol{f}=\sum_{l=1}^m\alpha_l\mathsf{L}^l\boldsymbol{f}$$

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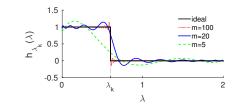
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- Does not require to compute U<sub>k</sub> : no partial diagonalisation.
- Only involves matrix-vector multiplications [costs O(m#E)].

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#### Main idea

The spectral distance reads : 
$$\left| D_{ij} = \| \mathsf{H}_{\lambda_k} \delta_{ij} \| = \lim_{m \to \infty} \left\| \widetilde{\mathsf{H}}_{\lambda_k} \delta_{ij} \right\|$$

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Let  $R = (\mathbf{r}_1 | \mathbf{r}_2 | \cdots | \mathbf{r}_\eta) \in \mathbb{R}^{N \times \eta}$  be a random Gaussian matrix, i.e. a collection of  $\eta$  random graph signals, with 0 mean and var.  $1/\eta$ .

We define 
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Norm conservation theorem (case of infinite m)

Let  $\epsilon > 0$ , if  $\eta > \eta_0 \sim \frac{\log N}{\epsilon^2}$ , then, with proba > 1 - 1/N, we have :  $\forall (i,j) \in [1,N]^2 \qquad (1-\epsilon)D_{ij} \leq \tilde{D}_{ij} \leq (1+\epsilon)D_{ij}.$ 

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 $\frac{\text{Consequence :}}{\text{fast filter only } \eta \sim \log N \text{ random signals !}}$ 

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## How to quickly estimate $\lambda_k$ , the sole unknown of the fast filtering operation?

Goal : given a SDP L, estimate its *k*-th eigenvalue as fast as possible.

We use eigencount techniques [Napoli '13] (also based on polynomial filtering of random vectors !) :

- given the interval [0, *b*], get an approximation of the number of enclosed eigenvalues.
- And find  $\lambda_k$  by dichotomy on *b*.

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#### Accelerated spectral algorithm

Given the N-node graph  ${\mathcal G}$  of adjacency matrix W :

Inputs : k, polynomial order m, # random signals  $\eta \sim \log N$ .

- 1. Estimate  $\lambda_k$ , the *k*-th eigenvalue of L.
- 2. Generate  $\eta$  random graph signals in matrix  $\mathsf{R} \in \mathbb{R}^{N \times \eta}$ .
- 3. Filter them with  $\tilde{H}_{\lambda_k}$  and treat each node *i* as a point in  $\mathbb{R}^{\eta}$  :

$$\widetilde{\mathbf{f}}_i^{ op} = \mathbf{\delta}_i^{ op} \widetilde{\mathsf{H}}_{\lambda_k} \mathsf{R}.$$

4. Run *k*-means with the Euclidean distance :  $\tilde{D}_{ij} = ||\tilde{f}_i - \tilde{f}_j||$ and obtain *k* clusters.

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4. Run *k*-means with the Euclidean distance :  $\tilde{D}_{ij} = ||\tilde{f}_i - \tilde{f}_j||$ and obtain *k* clusters.

Computing the features (steps 1 to 3) costs  $O(m\#E \log N) \simeq O(mN \log N)$ .

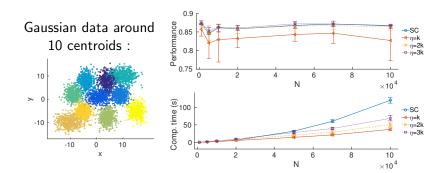
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#### Toy experiment



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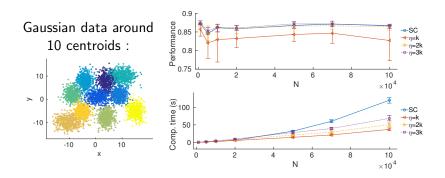
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#### Toy experiment



**Example** :  $N = 10^5$ , k = 10 : filtering only  $\eta = 20$  random signals gives same performance... 3x faster.

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#### Main idea of this paper

# **Low-pass graph fast filtering of random signals** : a way to by-pass the Laplacian's diagonalisation for learning tasks.

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## Ideas surrounding this paper : compressive spectral clustering [arXiv : Tremblay '16, Puy '15]

- Cluster indicator functions are k-bandlimited signals on the graph : they can be recovered after appropriate sampling schemes! 1/ Compute features, 2/ Sample a few nodes, 3/ Run low-dimensional k-means, 4/ Interpolate
- 2. Norm conservation theorem for  $\underline{finite}$  polynomial order m
- 3. Generalisation to the use of the normalized Laplacian (but not the random walk Laplacian yet)

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#### Perspectives and difficult questions

Two difficult questions (among others) :

- 1. Given a SDP matrix, how to estimate as fast as possible its *k*-th eigenvalue, and only that one?
- How to choose automatically the appropriate polynomial order m?

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#### Perspectives

- 1. Rational filters instead of polynomial filters? [Shi '15b]
- 2. How about if nodes are added one by one?

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Filtering random graph signals for clustering

Conclusion

#### References

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