

Generalized autocorrelation analysis for multi-target detection

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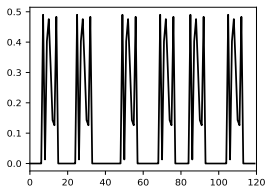


Multi-target detection (MTD)

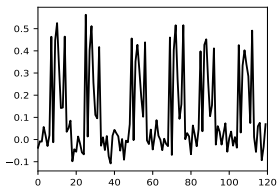
The problem of estimating a target signal $x \in \mathbb{R}^L$ from a noisy measurement $y \in \mathbb{R}^N$ that contains multiple copies of the signal, each randomly translated:

$$y[l] = \sum_{i=1}^P x[l - \ell_i] + \varepsilon[l], \quad (1)$$

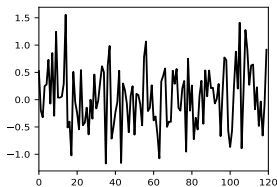
where $\{\ell_i\}_{i=1}^P \in \{L + 1, \dots, N - L\}$ and $\varepsilon[l] \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$.



(a) No noise.



(b) SNR = 50.



(c) SNR = 0.1.

Cryo-electron microscopy (cryo-EM)

Single-particle cryo-electron microscopy (cryo-EM) is an emerging technology for macromolecular structure determination.

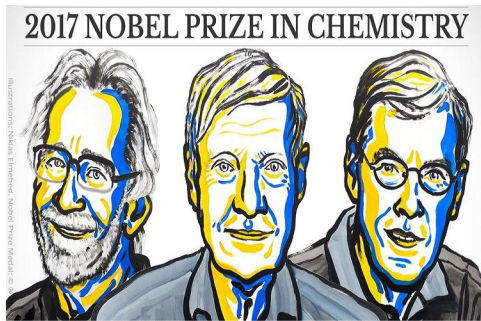


Figure: The Nobel Prize in Chemistry 2017 was awarded to Jacques Dubochet, Joachim Frank and Richard Henderson “for developing cryo-electron microscopy for the high-resolution structure determination of biomolecules in solution”.

Cryo-EM

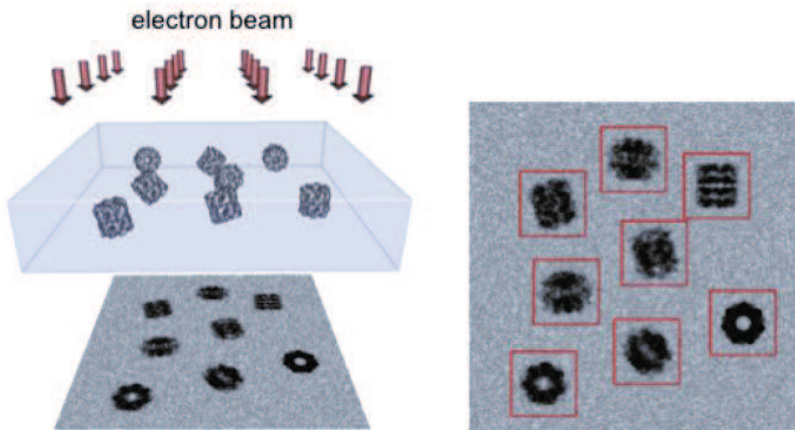


Figure: The cryo-EM process and particle picking.

Autocorrelation analysis

The idea: **finding a signal that best explains the empirical autocorrelations of the measurement:**

$$A_y^1 := \frac{1}{N} \sum_{i \in \mathbb{Z}} y[i], \quad (2)$$

$$A_y^2[\ell_1] := \frac{1}{N} \sum_{i \in \mathbb{Z}} y[i]y[i + \ell_1], \quad (3)$$

$$A_y^3[\ell_1, \ell_2] := \frac{1}{N} \sum_{i \in \mathbb{Z}} y[i]y[i + \ell_1]y[i + \ell_2]. \quad (4)$$

Autocorrelation analysis

For any fixed level of noise σ^2 , density γ and signal length L , in the limit $N \rightarrow \infty$, we have that:

$$A_y^1 \stackrel{\text{a.s.}}{=} \gamma A_x^1, \quad (5)$$

$$A_y^2[l_1] \stackrel{\text{a.s.}}{=} \gamma A_x^2[l_1] + \sigma^2 \delta[l_1], \quad (6)$$

$$A_y^3[l_1, l_2] \stackrel{\text{a.s.}}{=} \gamma A_x^3[l_1, l_2] + \gamma A_x^1 \sigma^2 (\delta[l_1] + \delta[l_2] + \delta[l_1 - l_2]), \quad (7)$$

for $l_1, l_2 \in \mathcal{L}$, where δ is the Kronecker delta function.

Here, γ is the density of the target signals in the measurement and is defined by

$$\gamma = p \frac{L}{N}. \quad (8)$$

The autocorrelations of x and y do not directly depend on the location of individual signal occurrences in the measurement, but only through the density parameter γ .

Autocorrelation analysis

In the **standard approach**, we find the signal that best matches the observable autocorrelations by minimizing a LS objective:

$$\begin{aligned} \arg \min_{x \in \mathbb{R}^L, \gamma > 0} & (A_y^1 - \gamma A_x^1)^2 + w_2 \sum_{\ell_1=0}^{L-1} \|A_y^2[\ell_1] - \gamma A_x^2[\ell_1] - \sigma^2 \delta[\ell_1]\|_2^2 \\ & + w_3 \sum_{\ell_1=0}^{L-1} \sum_{\ell_2=0}^{L-1} \|A_y^3[\ell_1, \ell_2] - \gamma A_x^3[\ell_1, \ell_2] - \gamma A_x^1 \sigma^2 (\delta[\ell_1] + \delta[\ell_2] + \delta[\ell_1 - \ell_2])\|_2^2, \end{aligned} \quad (9)$$

where the weights w_2 and w_3 were chosen such that each term is equally weighted.

Generalized autocorrelation analysis

Generalized autocorrelation analysis consists of replacing the LS objective function by weighted LS with optimal weights.

A specific choice of weights guarantees favorable asymptotic statistical properties, such as minimal asymptotic variance of the estimation error [Hansen 1982].

The **moment function** $f(\theta, y)$ for $\theta \in \Theta$ is chosen such that its expectation is zero only at a single point $\theta = \theta_0$, where θ_0 is the ground truth parameter (in our case, the target signal x and the density parameter γ). Namely,

$$\mathbb{E}[f(\theta, y)] = 0 \quad \text{if and only if} \quad \theta = \theta_0. \quad (10)$$

Generalized autocorrelation analysis

For MTD, we define the i -th observation from the measurement y

$$y_i := [y[i], \dots, y[i + L - 1]] \in \mathbb{R}^L, \quad (11)$$

and the moment function $f(\theta, y_i)$ simply as the discrepancy between the autocorrelations of y_i and the population autocorrelations.

The estimated sample moment function is the average of f over N observations:

$$g_N(\theta) = \frac{1}{N} \sum_{i=0}^{N-1} f(\theta, y_i). \quad (12)$$

The generalized autocorrelation estimator is defined as the minimizer of the weighted LS objective

$$\hat{\theta}_N = \arg \min_{\theta \in \Theta} g_N(\theta)^T W_N g_N(\theta). \quad (13)$$

Generalized autocorrelation analysis

Let

$$S := \lim_{N \rightarrow \infty} \text{Cov} \left[\sqrt{N} g_N(\theta_0) \right], \quad (14)$$

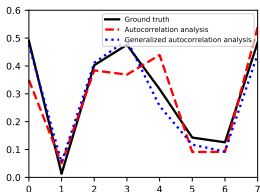
be the covariance matrix of the estimated sample moment function (12) at the ground truth θ_0 .

It can be shown that the optimal choice of a weighting matrix is given by

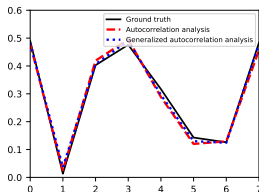
$$W = S^{-1}. \quad (15)$$

Numerical experiments¹

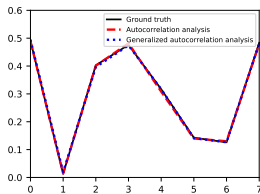
Recovery from a noisy measurement



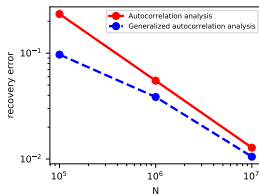
(a) $N = 10^5$



(b) $N = 10^6$



(c) $N = 10^7$



(d) Recovery error

¹The code to reproduce all experiments is publicly available at

<https://github.com/krshay/MTD-GMM>.

Numerical experiments

Recovery error as a function of the measurement length

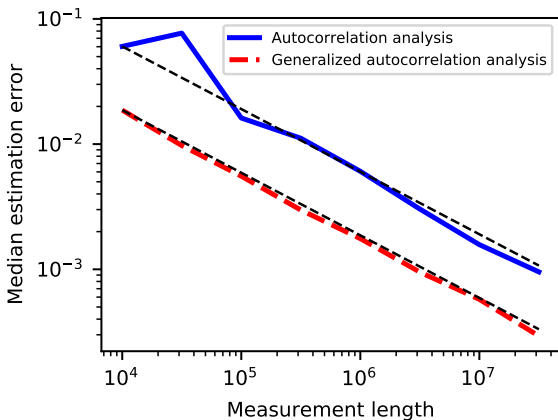


Figure: The median estimation error as a function of the measurement length N with SNR = 50, by: (a) autocorrelation analysis; (b) generalized autocorrelation analysis. The black dashed lines illustrates a slope of $-1/2$, as predicted by the law of large numbers.

Numerical experiments

Recovery error as a function of the SNR

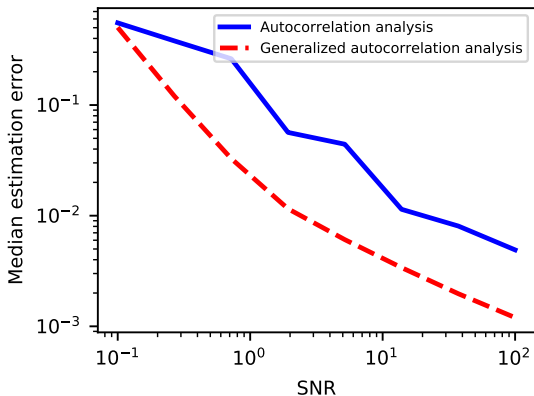


Figure: The median estimation error as a function of SNR, for measurements with length $N = 10^6$, by: (a) autocorrelation analysis; (b) generalized autocorrelation analysis estimator. Evidently, the generalized autocorrelation analysis estimator outperforms classical autocorrelation analysis for all SNR levels.

Conclusion

- The main contribution of this study is incorporating the generalized method of moments into the computational framework for the MTD problem.
- We demonstrate a successful signal reconstruction directly from noisy measurements.
- The generalized autocorrelation analysis framework outperforms autocorrelation analysis in a wide range of parameters.
- A step towards efficiently estimating a molecular structure directly from a noisy cryo-EM micrograph.

Thanks for your attention!