

Large-scale ASR Domain Adaptation using Self- and Semi-supervised Learning

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Background

Introduction

Self- and semi-supervised learning methods have been actively investigated to reduce labeled training data or enhance model performance. However, these approaches mostly focus on in-domain performance for public datasets. In this study, we utilize the combination of self- and semi-supervised learning methods to solve unseen domain adaptation problems in a large-scale production setting for online ASR model. This approach demonstrates that using the source domain data with a small fraction of the target domain data (3%) can recover the performance gap compared to a full data baseline: 13.5% relative WER improvement for target domain data.

Problem

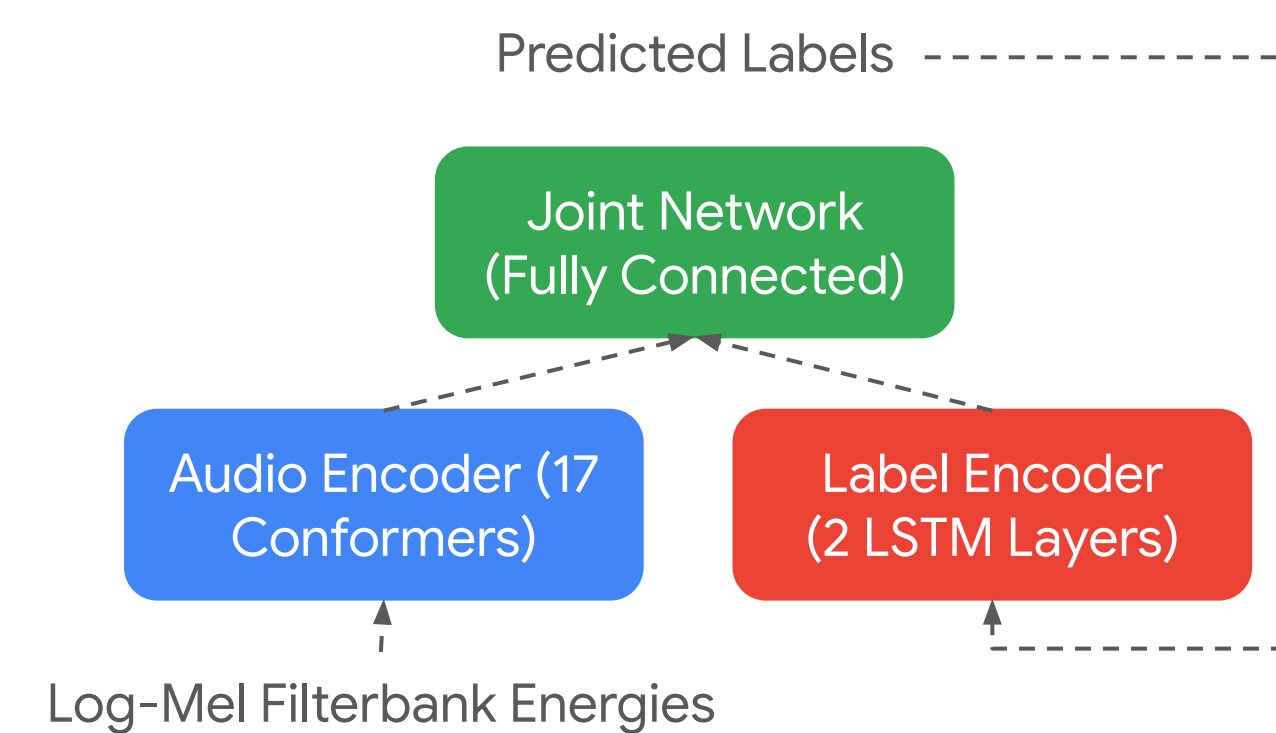
There are 2 datasets:

- source domain: short-form and YouTube (374k hrs)
- target domain: long-form (26k hrs)

The ASR model trained with source domain data has poor WER on target domain data. This study minimizes domain mismatch gap by self and semi-supervised learning.

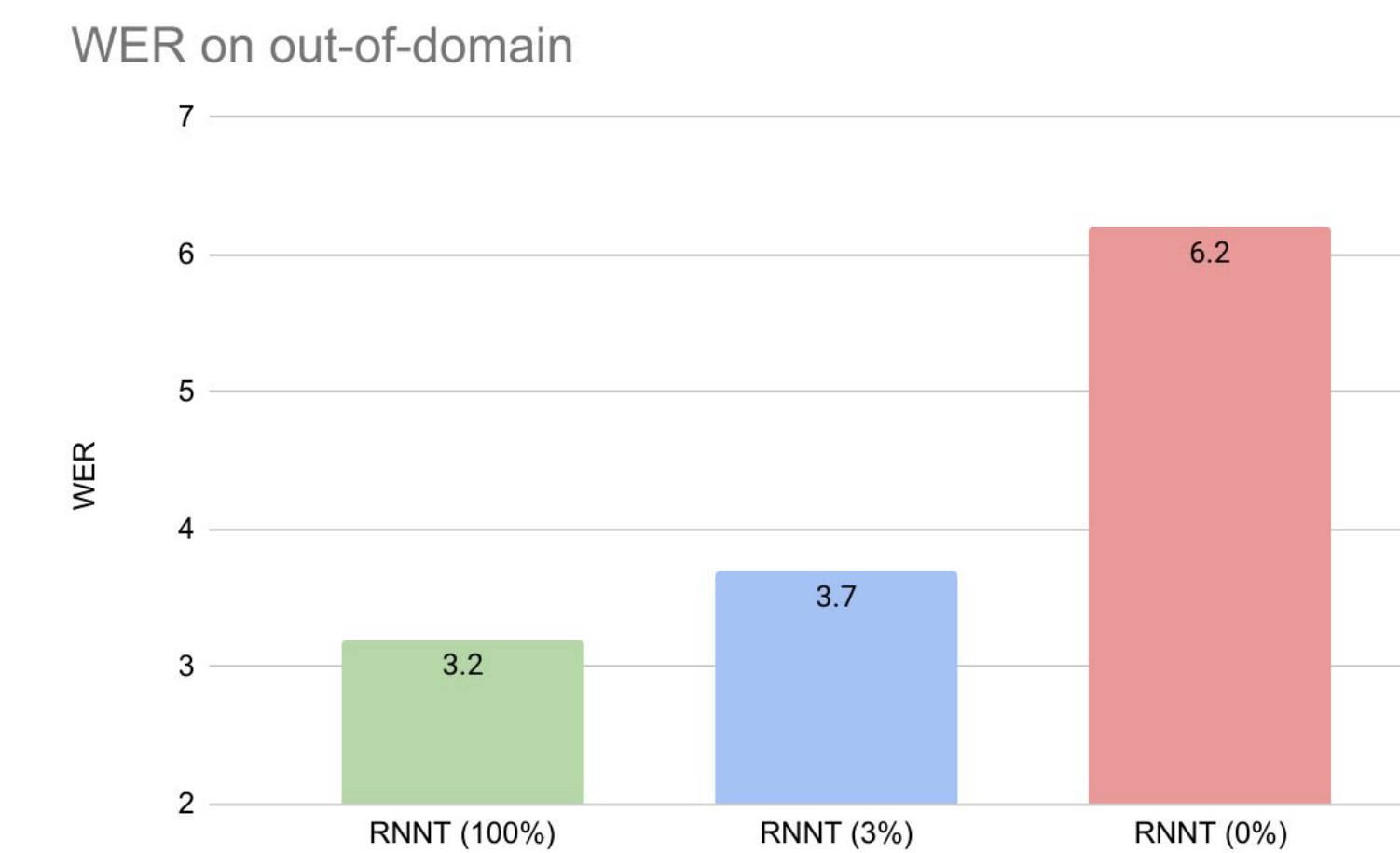
Model & Dataset

We use the RNN-T architecture, which is a 137 million parameter end-to-end neural ASR model predicting target labels based on acoustic input. The audio encoder has 17 Conformer blocks with model dimension 512. As the model is online ASR, we restrict the model from using any future information. We use large multi-domain (MD) datasets in English. MD utterances include multi domain data such as search, farfield, telephony and YouTube. Total size is 400k hours.



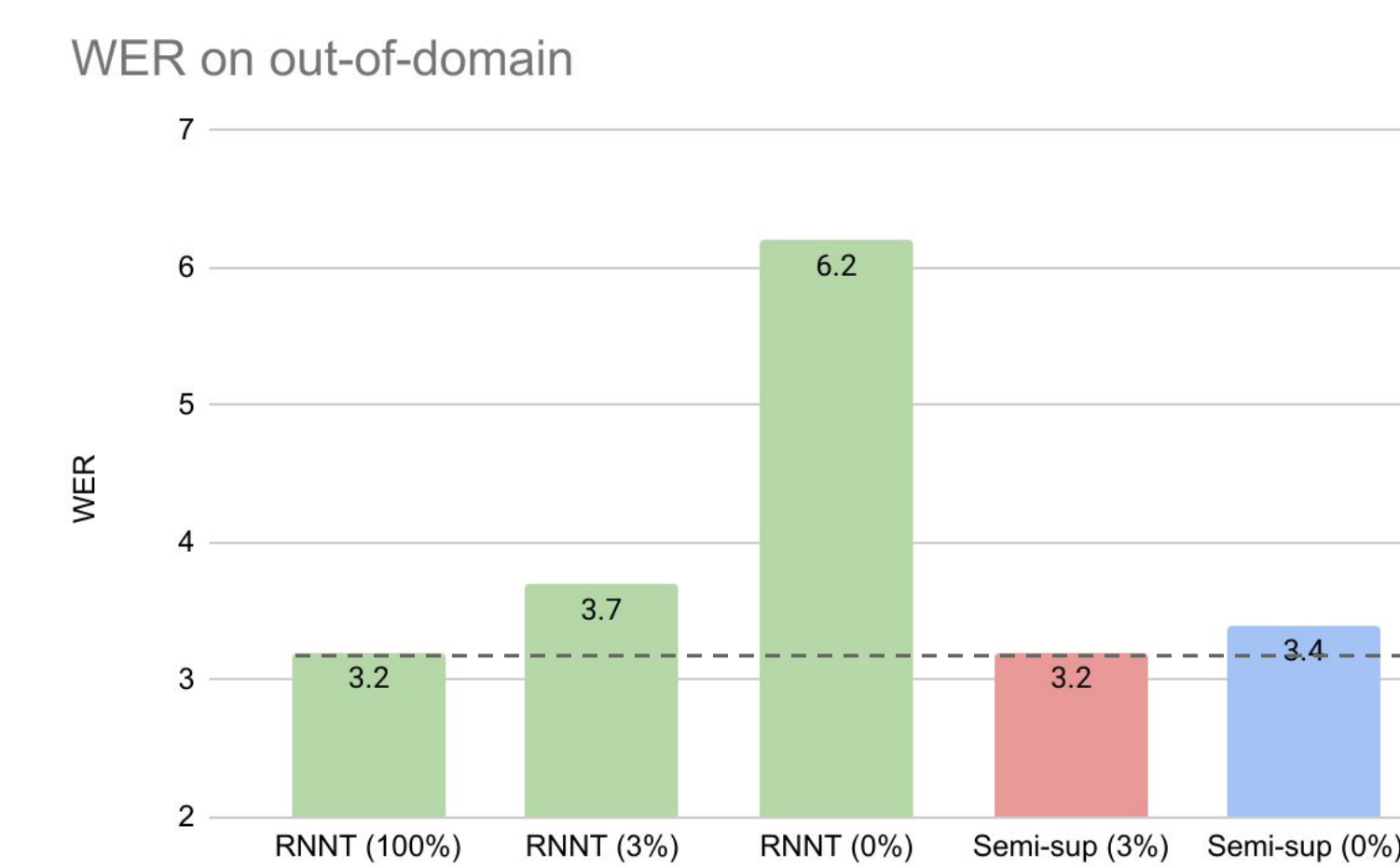
Baseline

The model trained with both source domain and target domain data has 3.2 WER on target domain. The model with only source domain has 6.2 WER. When we mix full source domain data and 3% target domain data, the model has 3.7 WER. We want to minimize the gap between 3.2 and 3.7 with 3% of target data.

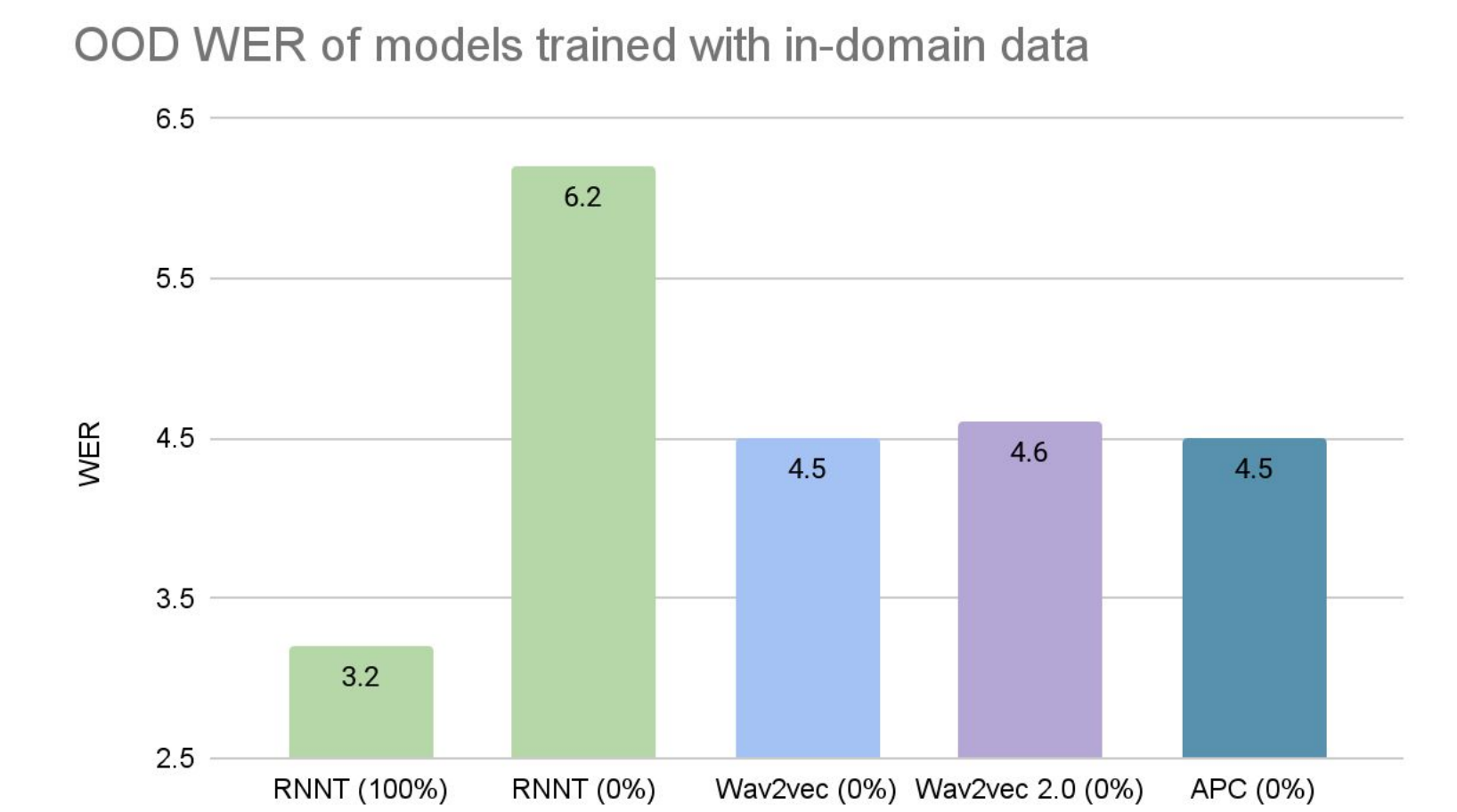


Semi-supervised Learning

We use Noisy student training (NST). NST is very effective to close OOD gap. We use both source domain and target domain to train models by RNN-T loss. Bi-directional teacher model produces pseudo label for target domain data. When we use 100% pseudo label for target domain, the model has 3.4 WER on target domain. When we mix 3% human label with 97% pseudo label, the model has 3.2 WER, which is same to 100% baseline. Semi-sup can close all the OOD gap by 3% of target domain data.

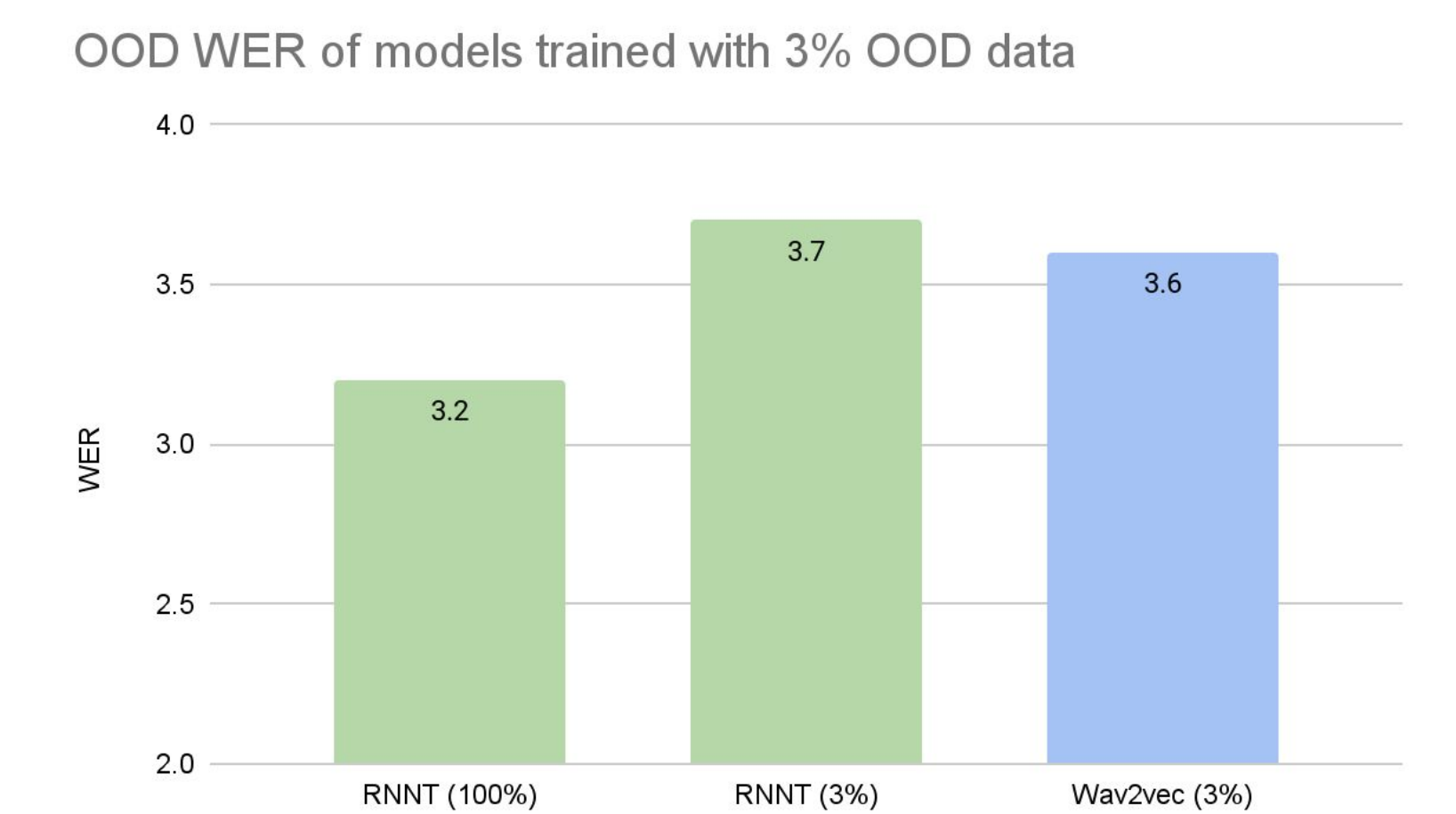


Wav2vec for rest of experiments. In our experience, APC is more sensitive to checkpoint fluctuations. When we choose a pre-trained checkpoint, Wav2vec works between 50k and 1.2M steps, but APC works only near 100k steps. In addition, APC requires total variation auxiliary loss to stabilize it [20].



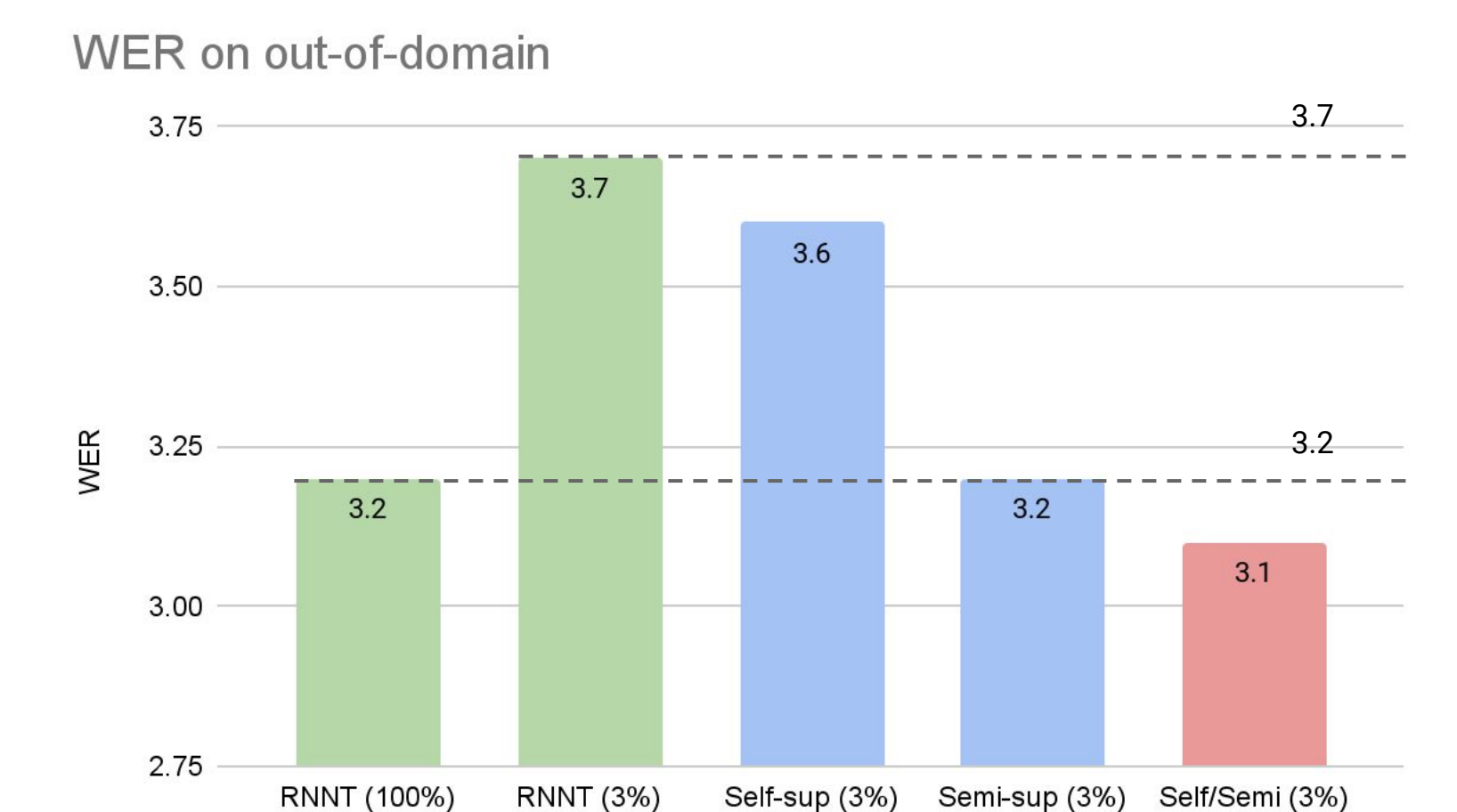
Self-sup contribution is minimal

We pretrain the audio encoder with both source and target domain data and finetune the RNN-T model with 3% target domain data and 100% source domain data. It improves target domain WER by 0.1%. Self-sup enhances overall model generalization, but cannot reduce gap of out-of-domain (OOD) generalization.



Combined Self/Semi-sup

Combined both self- and semi-sup are complementary. Self + Semi-sup show even better WER. We are actually surprised that that Self + Semi-sup with 3% target domain has better WERs than supervised learning with 100% target domain. Semi-sup plays a much more critical role to close the OOD gap, and self-sup enhances WER last mile.



Method

Self-Supervised learning

All of the self-supervised methods are used to pre-train the audio encoder of the RNN-T model [12] using all the source and target domain data. This is followed by supervised training of the entire model using only the labeled source domain data. We use the three popular self-supervised learning methods in this work: Wav2vec [1, 2], and Wav2vec2.0 [3], APC [4].

Semi-supervised learning

After self-supervised pre-training, we train the ASR model using RNN-T loss with both source domain data (labeled data) and target domain data (unlabeled data) [13]. NST produces pseudo labels for target domain data. The teacher model is trained with source domain data (same for the student model). As a result, the pseudo labels generated for the target domain data is error-prone, which is harmful for domain adaptation.

When pseudo labels are generated, the teacher model filters out low confidence utterances by Confidence Estimation Module (CEM) [14]. When the teacher model is trained by RNN-T loss, we add CEM whose inputs are the audio encoding and the beam search labels from the RNN-T model. The CEM is trained to minimise the binary cross entropy between the estimated confidence p and the binary target sequence c . The target sequence c contains a 1 when the prediction word is correct and 0 otherwise. The average word-level confidence is used to filter utterances.

Domain adaptation approach

Figure 1 visualizes the proposed domain adaptation method. First of all, self-sup trains the audio encoder with source and target domain data. Then, RNN-T model is trained by RNN-T loss with source and target domain data. NST produces pseudo label for target domain data.

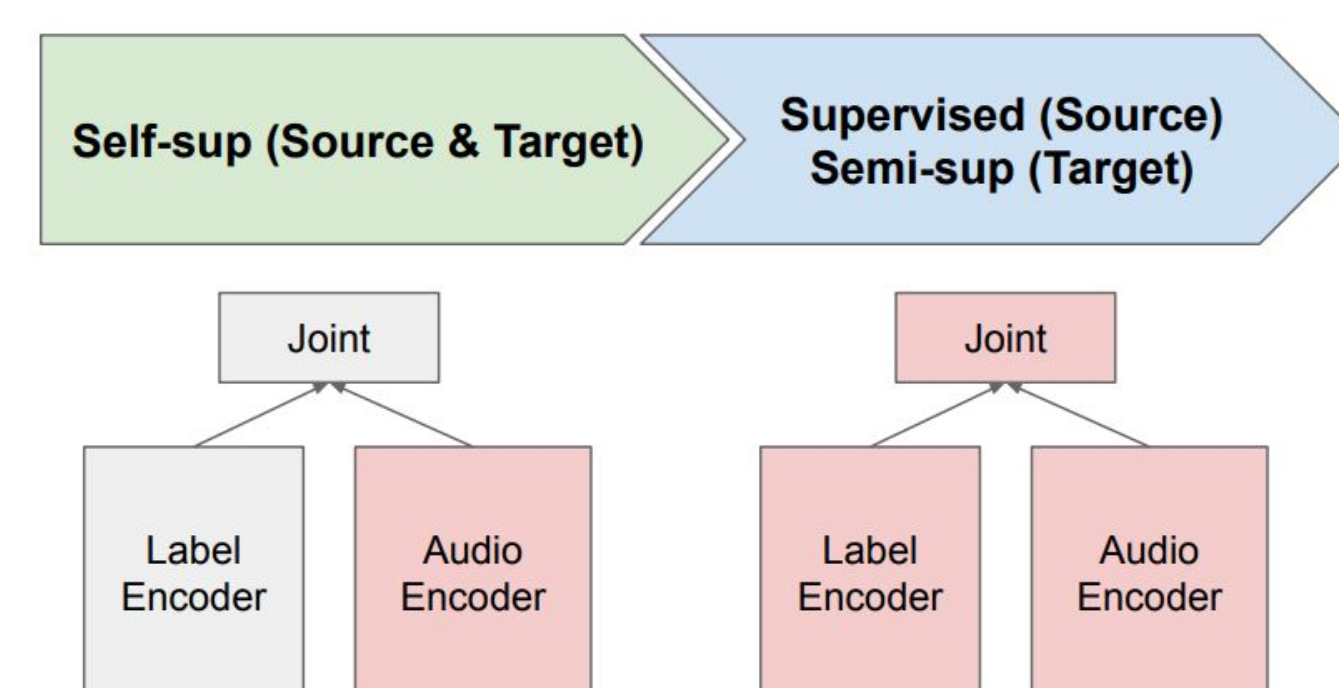
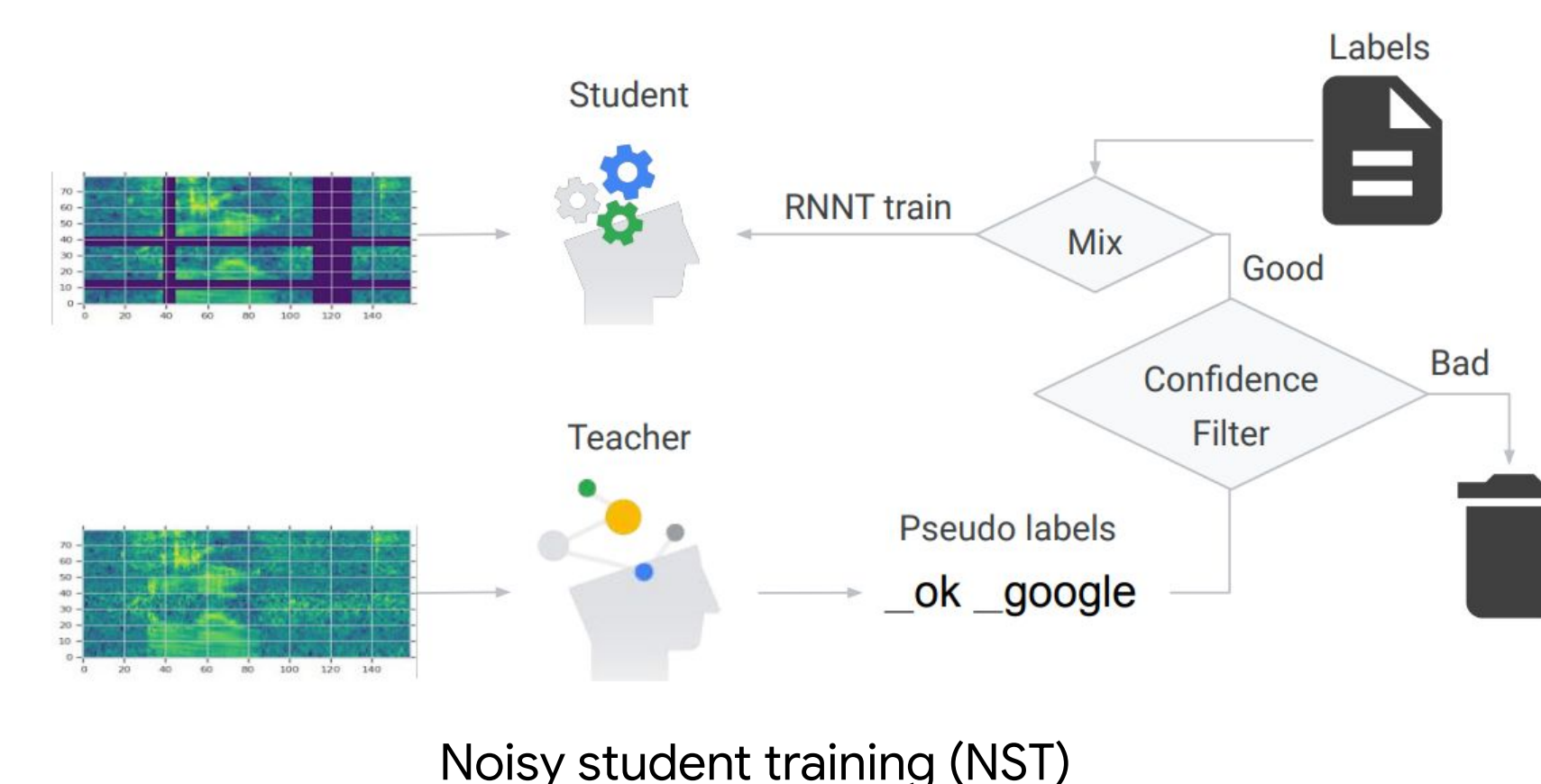


Fig. 1: Domain adaptation: Self-sup pre-trains the audio encoder. Supervised and semi-sup train all the modules.



Experiments

Self-supervised Learning

Compare W2V, W2V2 and APC

First, we compare the three popular self-supervised learning methods: Wav2vec [1, 2], and Wav2vec2.0 [3], APC [4].

Wav2vec and APC have better WER than Wav2vec2.0, unlike what Wav2vec2.0 paper reported [3]. The downstream ASR model is online RNN-T, which is a causal model. Wav2vec and APC are causal models like GPT-3, but Wav2vec2.0 is full context (non-causal) model like BERT. It shows causal self-sup has better performance for causal downstream task. Even though Wav2vec and APC have the same WERs, we use