

# Node-screening tests for the $\ell_0$ -penalized least-squares problem

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ICASSP 2022

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# The $\ell_0$ -penalized least-squares problem

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# Sparse-linear problem

## Ingredients of the problem :

- An **observation**  $y \in \mathbb{R}^m$
- A **dictionary**  $A = [a_i]_{i=1}^n \in \mathbb{R}^{m \times n}$  (columns  $\equiv$  **atoms**)

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### Problem

Find  $x$  *sparse* such that  $y \simeq Ax$

The vector  $x$  weights each atom in the approximation.

# $\ell_0$ -penalized problem

**Idea :** Solve the problem

$\ell_0$ -penalized least-squares

$$p^* = \begin{cases} \min & \frac{1}{2} \|y - Ax\|_2^2 + \lambda \|x\|_0 \\ \text{s.t.} & \|x\|_\infty \leq M \end{cases} \quad (P)$$

where  $\lambda > 0$  is a tuning parameter and  $M$  is a big-enough constant.

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**Properties :**

- Quadratic objective
- Linear constraints
- Continuous and integer variables
- Combinatorial problem
- Can be addressed with **Branch-and-Bound (BnB)** algorithms

# Branch-and-bound algorithms

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# Branch-and-bound principle

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## Node $\nu = (\mathcal{S}_0, \mathcal{S}_1, \bar{\mathcal{S}})$ where :

- $\mathcal{S}_0$  : indices of  $x$  fixed to zero
- $\mathcal{S}_1$  : indices of  $x$  fixed to non-zero
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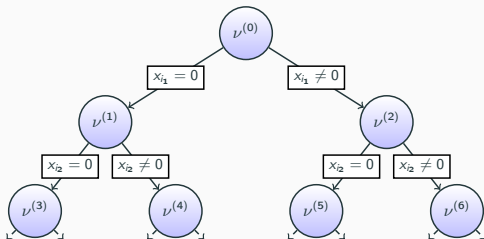
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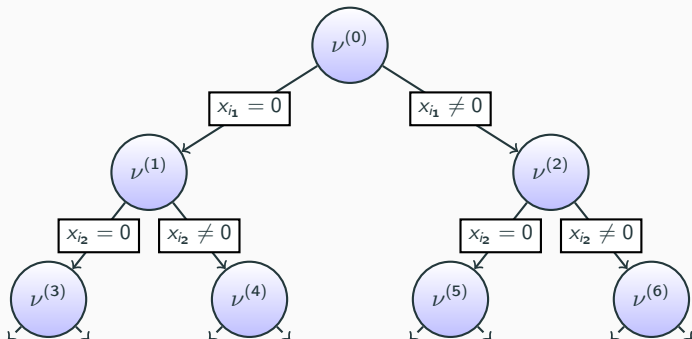
**Question :** Does any global solution matches the current constraints ?

**Relaxed problem at node  $\nu$**

$$p_l^\nu = \begin{cases} \min & \frac{1}{2} \|y - Ax\|_2^2 + \frac{\lambda}{M} \|x_{\bar{\mathcal{S}}}\|_1 + \lambda |\mathcal{S}_1| \\ \text{s.t.} & \|x\|_\infty \leq M, x_{\mathcal{S}_0} = 0 \end{cases} \quad (P_l^\nu)$$

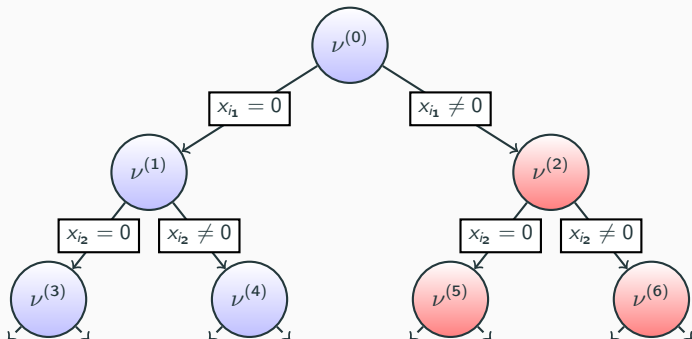
Let  $p_u$  be an upper bound on  $p^*$ . If  $p_u < p_l^\nu$ , then no optimizers of  $(P)$  can match the constraints of node  $\nu$ .

# Exploration and pruning process





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## Node-screening tests

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**Dual** problem at node  $\nu$

$$\max_{\mathbf{u} \in \mathbb{R}^m} \left\{ D^\nu(\mathbf{u}) \triangleq \frac{1}{2} \|\mathbf{y}\|_2^2 - \frac{1}{2} \|\mathbf{y} - \mathbf{u}\|_2^2 - \sum_{i \in \mathcal{S}} [\gamma(\mathbf{a}_i^T \mathbf{u})]_+ - \sum_{i \in \mathcal{S}_1} \gamma(\mathbf{a}_i^T \mathbf{u}) \right\} \quad (D^\nu)$$

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- One common term
- Terms corresponding to the current constraints
- The “pivot” function is defined as  $\gamma(t) = M|t| - \lambda$

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At node  $\nu$ , let  $i$  be an unfixed index. Then  $\forall \mathbf{u} \in \mathbb{R}^m$ ,

$$D^{\nu \cup \{x_i=0\}}(\mathbf{u}) = D^\nu(\mathbf{u}) + [\gamma(\mathbf{a}_i^T \mathbf{u})]_+$$

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- $\forall \mathbf{u}, D^\nu(\mathbf{u}) \leq p_i^\nu$  : the dual objective can also be used to prune nodes.
- At a given node, we may be able to **prune subnodes without processing them**.



## Node-screening test

Given an upper bound  $p_u$  on  $p^*$  and a dual point  $u \in \mathbb{R}^m$ ,

$$D^\nu(u) + [\gamma(a_i^T u)]_+ > p_u \implies \text{Fix } x_i \neq 0 \text{ at node } \nu$$

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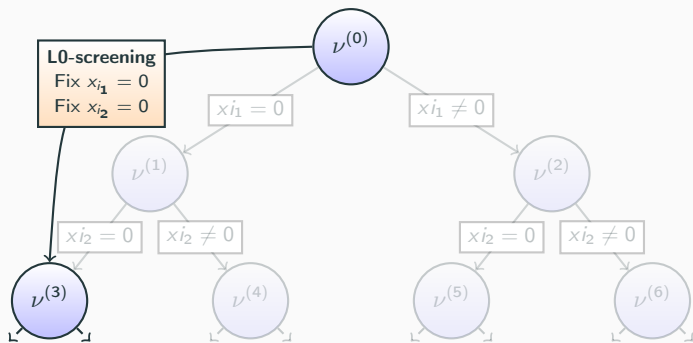
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**Practical use :** If a node-screening test is passed at node  $\nu$ , one can immediately **fix a new variable** at this node.

**Nesting property :** If **multiple** node-screening tests are passed, the corresponding variables can be fixed **simultaneously**.

## Consequence of passing a node-screening test



**Consequence :** Less nodes are explored by the BnB algorithm.

## Some numerical results

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### Synthetic setups :

1. Generate the dictionary randomly (low or high correlation)
2. Generate a  $k$ -sparse vector  $x^*$
3. Set  $y = Ax^* + \text{noise}$
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Corr.	Sparsity	CPLEX		BnB		BnB+scr	
		Nodes	Time	Nodes	Time	Nodes	Time
Low	$k = 3$	16	13.13	19	0.29	15	0.18
	$k = 5$	96	25.89	70	1.5	56	0.75
	$k = 7$	292	60.84	180	5.14	152	3.02
High	$k = 3$	76	1.73	79	0.38	60	0.26
	$k = 5$	1,424	10.18	965	6.39	725	4.18
	$k = 7$	17,647	106.45	10,461	79.29	7,881	52.16