# **Ray-Space-Based Multichannel Nonnegative Matrix Factorization for Audio Source Separation**



Nonnegative matrix factorization (NMF) has been traditionally considered a promising approach for single-channel mixtures, extensions to consider multi-channel data have been also proposed. Among the most popular alternatives, multichannel NMF (MNMF) and further derivations based on constrained spatial covariance models have been successfully employed to separate multi-microphone convolutive mixtures. This letter proposes a MNMF extension by considering a mixture model with Ray-Space-transformed signals, where magnitude data successfully encodes source locations as frequency-independent linear patterns. We show that the MNMF algorithm can be seamlessly adapted to consider Ray-Space-transformed data, providing competitive results with recent state-of-the-art MNMF algorithms in a number of configurations using real recordings.

#### Multichannel NMF model (MNMF)

- We consider a uniform linear array (ULA) of I channel acquiring the mixture of J acoustic sources.
- Under the local Gaussian model MNMF describes the mixture at the *ith* channel as

$$y_i(\omega, n) \sim \mathcal{N}_{\mathbb{C}}\left(0, \sum_{j=1}^J \boldsymbol{G}_j(\omega) \sum_k^K w_{j,k}(\omega) h_{j,k}(n)\right)$$

- $G_i \in \mathbb{C}^{I \times I}$  is the spatial covariance matrix of the *j*th source
- $w_{i,k}(\omega), h_{i,k}(n)$  are the basis functions and the activation modeling the source PSD  $p_i(\omega, n)$ .  $[\Psi]_{i,t} = e$

#### **Ray Space Transofrm (RST)**

RST [1] is a linear operator  $\Psi \in \mathbb{C}^{I \times LD}$  that maps the signals of a ULA onto the Ray Space  $\mathbf{Z}(\omega, n) = \mathbf{\Psi}^{\mathrm{H}}(\omega) \mathbf{y}(\omega, n).$ 

Array signals can be recovered using the inverse RST  $\widetilde{\Psi} = (\Psi \Psi^H)^{-1} \Psi$  $\mathbf{y}(\omega, n) \approx \widetilde{\mathbf{\Psi}}(\omega) \mathbf{Z}(\omega, n).$ 

#### **GOAL**: exploit RS representation of source's position as input domain for MNMF separation

#### **Setup and metrics**

- $5.5m \times 3.4m \times 3.3m$  Room with  $T60 \approx 0.4s$
- ULA of I = 32 microphones and 9 source locations

• Mixtures with  $J = \{2,3\}$  sources with 3s signals of male/female speech and music

- Results compared with BS-MNMF[2,] FastMNMF[3], DOA-MNMF[4], WN-MNMF[5] and ILRMA[6].
- Performance is evaluated in terms of :
- Signal-to-artifacts ratio (SAR),
- Signal-to-distortion ratio (SDR),
- Signal-to-interference ratio (SIR).

https://github.com/polimi-ispl/rs-mnmf

#### References

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### Abstract

### **Related Works**





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# 2. The Ray Space MNMF (RS-MNMF)

 $Z_t(\omega, n) = \sum_{j=1}^J r_{t,j} s_j(\omega, n) + b_t(\omega, n),$ 

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•  $\hat{y}_t(\omega, n) = \sum_j g_{t,j} \sum_{k \in K_j} w_k(\omega) h_k(n)$  is the square magnitude of the ray space modeled

Similarly to instantaneous algorithm in [2] the components are estimated using MU

 $\tilde{s}_{j}^{(t)\text{im}}(\omega,n) = \frac{g_{t,j}p_{j}(\omega,n)}{\hat{v}_{t}(\omega,n)} Z_{t}(\omega,n)$ 

**Estimate** of the *jth* **sources** at the **microphones** is obtained using the **inverse RST**:  $\hat{s}_{i}^{im}(\omega, n) = \widetilde{\Psi}(\omega, n) \widetilde{s}_{i}^{im}(\omega, n)$