# Multitask Gaussian Process with Hierarchical Latent Interactions

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#### March 2022



## Overview

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- Multitask Gaussian process (MTGP) and kernel function
- Our motivation and contribution

### 2 Multitask Gaussian process with interactions

- Manner of latent interaction
- Function interaction between LFs
- Coefficient interaction between LMCs
- MTGP with hierarchical interactions

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• Performance of multitask learning

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# Multitask Gaussian process (MTGP)



Figure 1: Single task (a) and multitask (b) learnings

### Why multitask learning ?

- A complex system usually consists of multiple correlated tasks;
- Joint learning of these tasks can help us understand the system;
- To obtain higher accuracy and concurrent predictions by transferring knowledge;

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# Multitask Gaussian process (MTGP)



### Why multitask Gaussian process ?

- Interpretability, the correlation between tasks is quantifiable and explainable;
- Uncertainty representation and prediction;
- Less prone to overfitting;

# Multitask Gaussian process (MTGP)

### Definition of MTGP

A MTGP models *m* tasks as a joint Gaussian distribution,

$$\boldsymbol{f} \sim \mathcal{GP}(\boldsymbol{0}, \boldsymbol{k}_{\mathsf{M}}(\boldsymbol{X}, \boldsymbol{X}')), \tag{1}$$

where 
$$\mathbf{y} = \mathbf{f} + \mathbf{\epsilon}$$
,  $\mathbf{f} = [f^{(1)}(\mathbf{x}^{(1)}), ..., f^{(m)}(\mathbf{x}^{(m)})]^{\top}$ ,  $X = [\mathbf{x}^{(1)}, ..., \mathbf{x}^{(m)}]^{\top}$ ,  
 $\mathbf{y} = [y^{(1)}, ..., y^{(m)}]^{\top}$ , and  $k_{\mathsf{M}}(X, X')$  describes both the auto-covariance of each task and the cross covariance between tasks.

• *k*<sub>M</sub> determines the representation, smoothness, interpretability, and expressiveness of MTGP.

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## Multitask kernel function

The general formula of  $k_{\rm M}$  is,

$$K_{\mathsf{M}}(X, X') = \begin{bmatrix} K^{(1,1)}, & K^{(1,m)} \\ K^{(m,1)}, & K^{(m,m)} \end{bmatrix},$$
(2)

where  $K^{(m,1)}$  describes the cross covariance between  $f^{(m)}$  and  $f^{(1)}$ .

An expressive  $k_{M}$  using linear model of coregionalization (LMC) linearly combines a mixture of Q covariance components to ameliorate the representation of MTGP :

$$K_{\mathsf{M}} = \sum_{i=1}^{Q} B_i \otimes K_{s,i},\tag{3}$$

where  $B_i$  is a LMC matrix representing task correlation and  $K_{s,i}$  is a matrix constructed by arbitrary kernel of STGP.

## Multitask kernel function



Figure 3: Frameworks of MTGPs. In subplot (a), task correlation in MTGP is described by the convolution between latent functions (LFs). In subplot (b), all tasks share a LF space  $f_s$  adumbrating their common qualities.

- The LMC has a clearer hierarchical architecture for model explanation;
- The LMC has more compact hyperparameter space due to the shared LF;

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## Our motivation

### Limitation of existing MTGPs

- Considers linear combination of LFs as well as kernels;
- Ignores interactions between them;

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## Our contribution

We develop a novel LMC framework with hierarchical interactions for MTGP:

- By using convolution between LFs, we offer a kernel encoding function interactions (FIs) in MTGP for the first time;
- We derive free-form coupling coregionalization (CC) between Cholesky factors of LMCs for coefficient interactions;
- We demonstrate the rich representation, interpretability, and expressiveness of a kernel framework incorporating both the function and coefficient interactions for MTGP.

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## Manner of latent interaction

 $k_{s,i}$  ensures the generalization of  $f_{s,i}(\mathbf{x}^{(m)})$  and we therefore replace it with  $k_{\text{SM},i}$ 

$$f^{(m)}(\mathbf{x}^{(m)}) = \sum_{i=1}^{Q} \alpha_i^{(m)} f_{\mathsf{SM},i}(\mathbf{x}^{(m)}),$$
(4)

where  $f_{\text{SM},i} \sim \mathcal{GP}(0, k_{\text{SM},i})$  and  $k_{\text{SM},i}(\tau) = \mathcal{F}_{s \to \tau}^{-1} \Big[ w_i \mathcal{N}(\mathbf{s}; \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i) \Big](\tau)$ .

Due to  $f_{SM,i}(\mathbf{x}^{(m)}) \not\perp f_{SM,j}(\mathbf{x}^{(m)})$  and  $cov[f_{SM,i}(\mathbf{x}^{(m)}), f_{SM,j}(\mathbf{x}^{(m)})] \neq 0$  when  $i \neq j$ , we consider two hierarchical interactions in LMC:

• FI between LFs f<sub>SM,i</sub> and f<sub>SM,j</sub>;

• coefficient interaction between  $\alpha_i^{(m)}$  and  $\alpha_i^{(m)}$ ;

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## Function interaction between LFs

By following the so-called generalized convolution spectral mixture (GCSM) in<sup>1</sup> and view it as a general sense of FI between LFs.

$$k_{\text{GCSM}}^{i \times j}(\tau) = c_{ij} \exp\left(-\frac{1}{2}\tau_{\theta}^{\top}\Sigma_{ij}\tau_{\theta}\right) \cos\left(\tau_{\theta}^{\top}\boldsymbol{\mu}_{ij} - \boldsymbol{\phi}_{ij}\pi\right),$$
(5)

where  $c_{ij}$  is the cross constant,  $\tau_{\theta} = 2\pi(\tau - \frac{\theta_{ij}}{2})$  is the Euclidean distance with time delay,  $\mu_{ij}$  is cross inverse period,  $\Sigma_{ij}$  is cross inverse length scale,  $\theta_{ij}$  is cross time delay, and  $\phi_{ij}$  is cross phase delay between  $f_{\text{SM},i}$  and  $f_{\text{SM},j}$ , respectively. Note that  $k_{\text{GCSM}}^{i \times j}(\tau) = k_{\text{SM},i}$  for i = j

Chen et al. 2019.

## Function interaction between LFs



Figure 4: The illustrations of LFs (a), covariances (b), and SDs (c) of their interaction.

Includes more interaction terms without the increasing of hyperparameter space (if remove time and phase delays).

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## Coefficient interaction between LMCs

For the coefficient interaction between  $\alpha_i^{(m)}$  and  $\alpha_j^{(m)}$ , we reformulate  $\alpha_i^{(m)}$  in a free-form parameterized<sup>2</sup> matrix  $B_i$  as  $B_i(m, m') = \alpha_i^{(m)} \alpha_i^{(m')}$ .

We construct  $B_{ij} = B_{L,i}B_{L,j}^{\top}$  to encode the coefficient interaction and interpretate  $B_{i,j}$  as a free-form coupling coregionalization (CC).

<sup>2</sup>Bonilla, Chai and Williams 2008. (<sup>†</sup>CUHK, Shenzhen, <sup>‡</sup>RU, Nijmegen)

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## MTGP with hierarchical interactions

For MTGP with Q LFs constructed by using LMC and SM kernel, we have a kernel with hierarchical interactions as follows:

$$K_{\text{GCSM-CC}}(\tau) = \sum_{i=1}^{Q} \sum_{j=1}^{Q} B_{ij} \otimes k_{\text{GCSM}}^{i \times j}(\tau).$$
(6)

 MTGP with k<sub>GCSM-CC</sub> has richer representation capacity than existing LMC and convolution frameworks because there are Q<sup>2</sup> − Q cross interaction terms when i ≠ j.

## Experiment setting

Performance metric: MAE =  $\sum_{i=1}^{n} |y_i - \tilde{y}_i| / n$ .

We compare GCSM-CC with some advanced baselines:

- Traditional MTGP<sup>3</sup>
- GPRN<sup>4</sup>
- CSM<sup>5</sup>
- MOSM<sup>6</sup>

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<sup>3</sup>Bonilla, Chai and Williams 2008.
<sup>4</sup>Wilson, Knowles and Ghahramani 2012.
<sup>5</sup>Ulrich et al. 2015.
<sup>6</sup>Parra and Tobar 2017.
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# Performance on synthetic multitask



Figure 5: Performance of GCSM-CC (in blue dashed line) and MOSM (in plum dashed line) on synthetic MT.

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## Asymmetric extrapolations of primary tasks



Figure 6: Nitrogen oxides concentration extrapolations.

## Experiment performance

Table 1: Performance (MAE) of GCSM-CC and other MTGPs.

Task	SE-LMC	Matérn-LMC	GPRN	CSM	MOSM	GCSM-CC
Mixed signal	$0.16 \pm 0.01$	$0.11 \pm 0.01$	$0.12 \pm 0.01$	$0.12 \pm 0.01$	$0.13 \pm 0.01$	<b>0.10</b> ±0.003
Integral	$0.26 \pm 0.01$	$0.25 \pm 0.02$	$0.33 \pm 0.05$	$0.19 \pm 0.06$	$0.09 \pm 0.004$	<b>0.06</b> ±0.003
Derivative	$0.18 \pm 0.01$	$0.19 \pm 0.01$	$0.09 \pm 0.01$	$0.17 \pm 0.02$	$0.08 \pm 0.01$	$\textbf{0.04} \pm 0.01$
NO <sup>H</sup>	$130.96 \pm 0.41$	$132.89 \pm \! 0.37$	$58.16 \pm 1.17$	$52.02 \pm 4.28$	$53.95 \pm\! 1.04$	<b>41.16</b> ±0.95
NO <i>S</i>	$85.06 \pm 0.38$	$85.19 \pm 0.36$	$45.98 \pm 2.61$	$35.48 \pm 1.17$	$60.81 \pm 1.60$	$\textbf{33.39} \pm 1.54$

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### Summary

- GCSM-CC with hierarchical interactions includes FI modeled by convolution of SM kernels and coefficient interaction constructed by using free-form coupling coregionalization.
- GCSM-CC advances the learning capacity and interpretability of MTGPs beyond non-interactive frameworks.

#### Future work

• Interesting future research involves sparse and efficient inference methods for current MTGPs.

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Feedback welcome!

# The End

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