Robustness of raw waveform speaker embeddings under mismatched conditions

Abstract

We investigate the cross-dataset speaker verification performance using raw-waveform based speaker embeddings and observe a more significant performance degradation compared to spectral based systems. To improve raw-waveform models' cross-dataset performance, we replace the real-valued filters into analytic filters to ensure shift invariance; we also apply variational **dropout** to non-parametric filters to prevent them from overfitting irrelevant nuance features. By combining these strategies, we achieve results comparable to spectral based systems on both the VoxCeleb and VOiCEs datasets.

Time-domain Speaker Embedding

Potential problems for spectral based features:

- Hand-crafted features are not necessarily optimal;
- Mel-spectral transform is lossy.



Two strategies to learn from raw waveforms:

- Non-parametric filterbank with regularization;
- Pre-defined parametric filterbanks.



Recent self-supervised speech representation pretraining frameworks, such as wav2vec and WavLM, use waveform as input.

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Channel Mismatch Problem

Comparison of raw-waveform based and melspectrum based speaker embeddings under both matched and mismatched conditions.

- Dataset: train on noise augmented Vox2, test on in-domain full Vox1 and out-of-domain VOiCEs;
- Audio frontend: Mel-fbank, MFCC, Sinc, TDF; • Learnable blocks:



• We use equal error rate (EER) to evaluate verification performance scoring with cosine similarity:



• Visualization of learned filters:





Filter Index (b) SincNet



Filter Index (c) TDFBank

Proposed Strategies

Down-sampled convolutions or pooling layers are not shift-invariant, and they compromise performance on robust classification tasks.

 The modulus of convolution between real-valued input signals s(t) and analytic filters $z_a(t)$ are shiftinvariant with respect to time:

$$y(t) = |s(t) * z_a(t)|$$

• To obtain analytic filter on any given real-valued filter s(t), we can apply *Hilbert transform*:

$$z(t) = s(t) + j\mathcal{H}\{(s(t))\}$$
$$\mathcal{H}\{(s(t))\} = s(t) * \frac{1}{\pi t}$$

Observing learned filter responses trained with noisy datasets, the non-parametric filters tend to overfit the noisy training data, learning task-irrelevant aspects of the recordings.

Variational dropout is a Bayesian regularization technique to help avoid overfitting:

• Dropout can be seen as masking neural network (NN) weights, $w_{ij} = m_{ij}\theta_{ij}$:

① Standard dropout is binary mask $m_{ij} \sim Bern(p)$; **Q** Gaussian dropout is a ratio mask:

 $m_{ij} \sim \mathcal{N}(1, \alpha = p(1-p)).$

 Equivalently, variational dropout can be seen as applying an independent Gaussian mask parameterized with α_{ij} to every weight w_{ij} instead of a fixed parameter α in Gaussian dropout.

• During training, α_{ij} is learned through stochastic optimization using an approximated KL-divergence. • During inference, a threshold is set for α_{ij} : if it is larger than the threshold, i.e., the corresponding w_{ij} is stochastic enough, w_{ij} is then discarded.

The proposed strategies above do not bring extra parameters at inference. In fact, variational dropout can sparsify learned filterbank weights.

We repeat the experiments in both matched and mismatched conditions and use PLDA scoring as the backend.

 $T\Gamma$ MF

 Analyticity constraint helps non-parametric filters to learn robust representations, but this is not the case for parametric filters. • Variational dropout improves the performance of

non-parametric filterbanks on VOiCEs.

Visualization of learned filters trained on noise augmented VoxCeleb after applying variational dropout: Top row: 'TDF+H' filters. Bottom row: 'TDF+H+VD' filters.

345Hz 🔒

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Results

rontend	Vox1-0	Vox1-E	Vox1-H	VOiCEs
Sinc	2.37	2.32	4.02	8.55
SINC-H	2.15	2.28	3.91	8.90
TDF	1.98	2.19	3.85	8.38
ГDF-Н	2.01	2.27	3.98	7.46
DF-VD	1.98	2.30	4.05	7.68
PF-H-VD	1.99	2.26	3.93	7.40
lel-Fbank	2.04	2.17	3.79	7.10
CC (Kaldi)	2.26	2.37	4.14	6.79



