

Knowledge Distilling for Object Detection in Remote Sensing Images

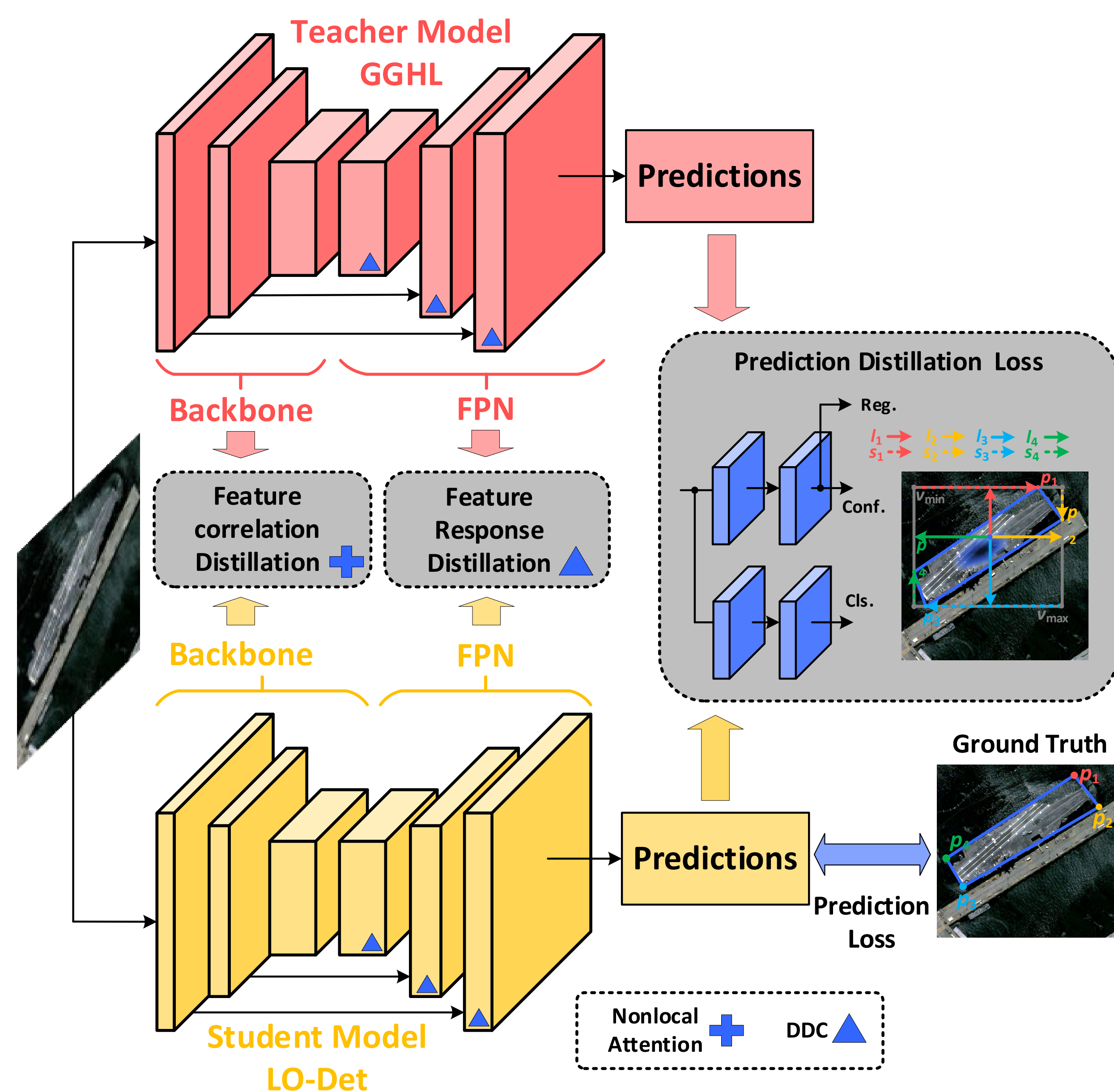
◆ For Spaceborne or Airborne Online Remote Sensing Object Detection (RSOD) Tasks:



- Limited Computing Resources → Lightweight CNN Models
- Lightweight CNN Models → Performance Drop
- Performance Compensation → Knowledge Distillation

◆ Our Contributions:

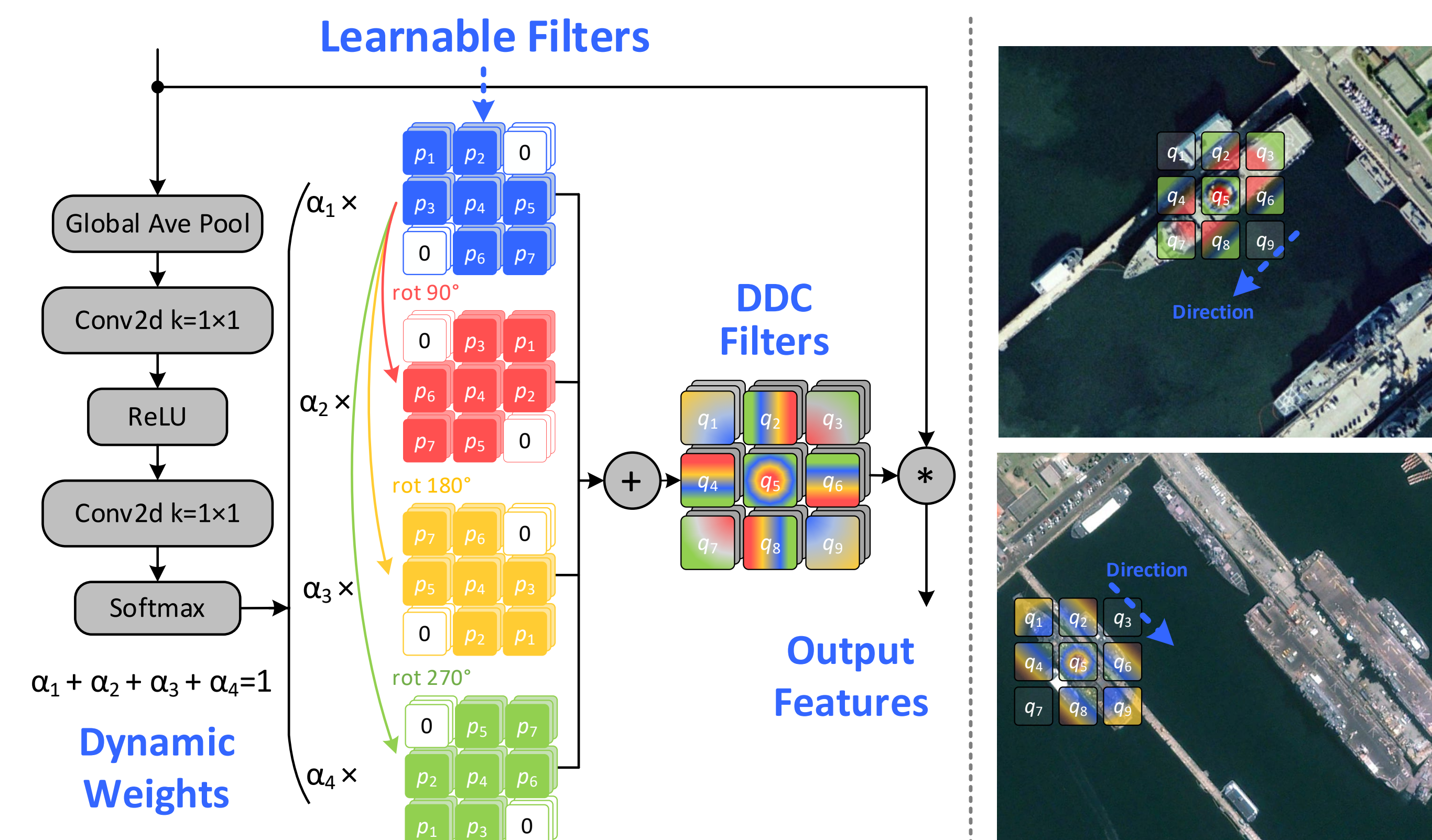
- Propose a direction-adaptive knowledge extraction and distillation (DKED) method that compensates for the performance penalty of lightweight RSOD models;
- The proposed DKED distills arbitrary-oriented feature responses & correlations & predictions of objects in remote sensing images.



Knowledge Distillation of DKED

◆ Dynamic Directional Convolution (DDC)

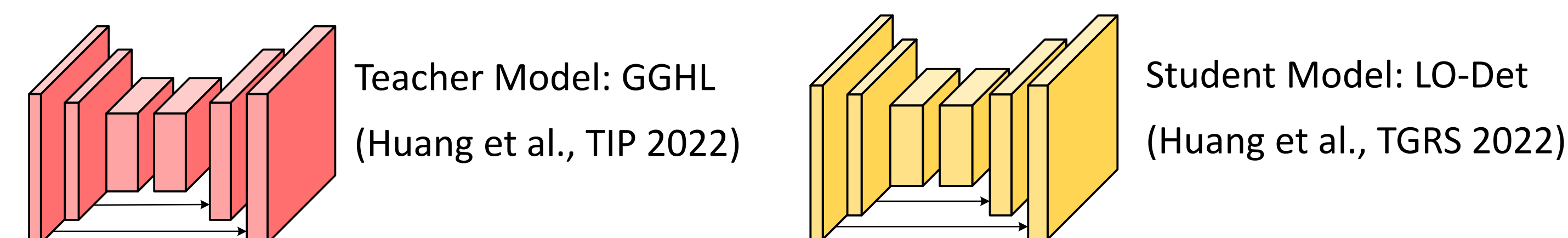
Because of the top-down perspective of remote sensing images, extracting arbitrary oriented features adaptively is important.



- DDC dynamically generates convolutional filters that match the optimal orientation based on the input.

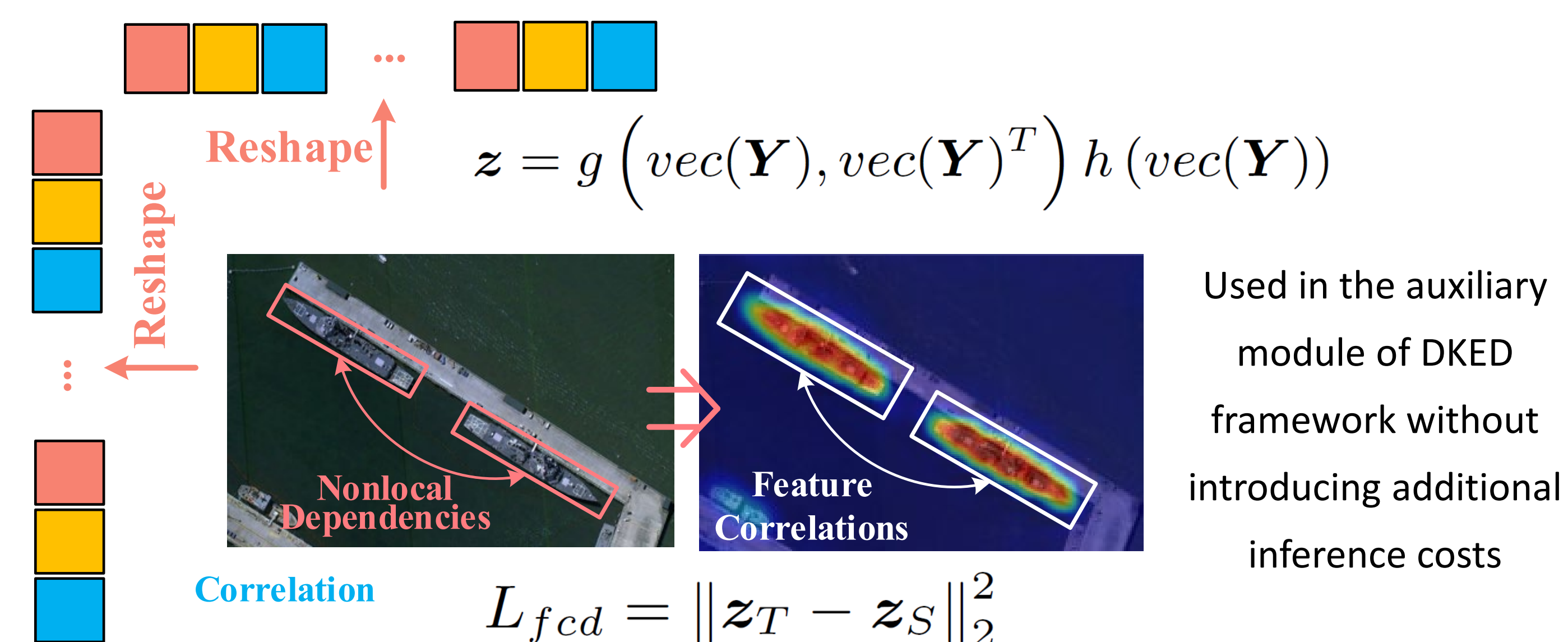
◆ Direction-Adaptive Knowledge Extraction and Distillation (DKED) Framework

1) Teacher & Student Models for Distilling

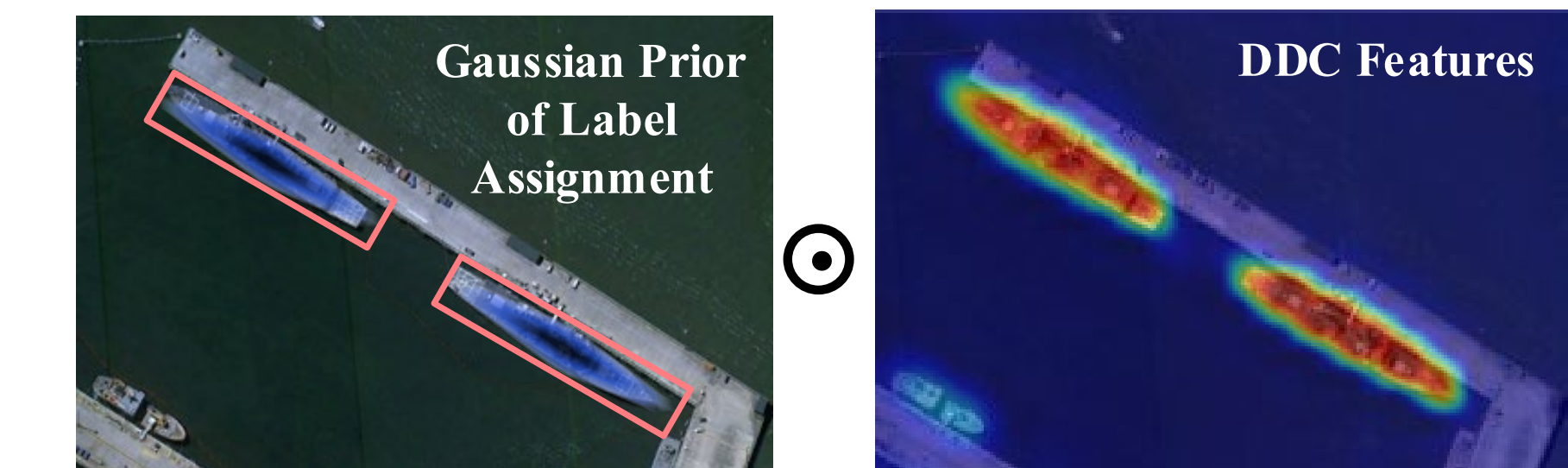


2) Feature Correlation Distillation

Distill the non-local correlation features extracted by the backbone CNNs.

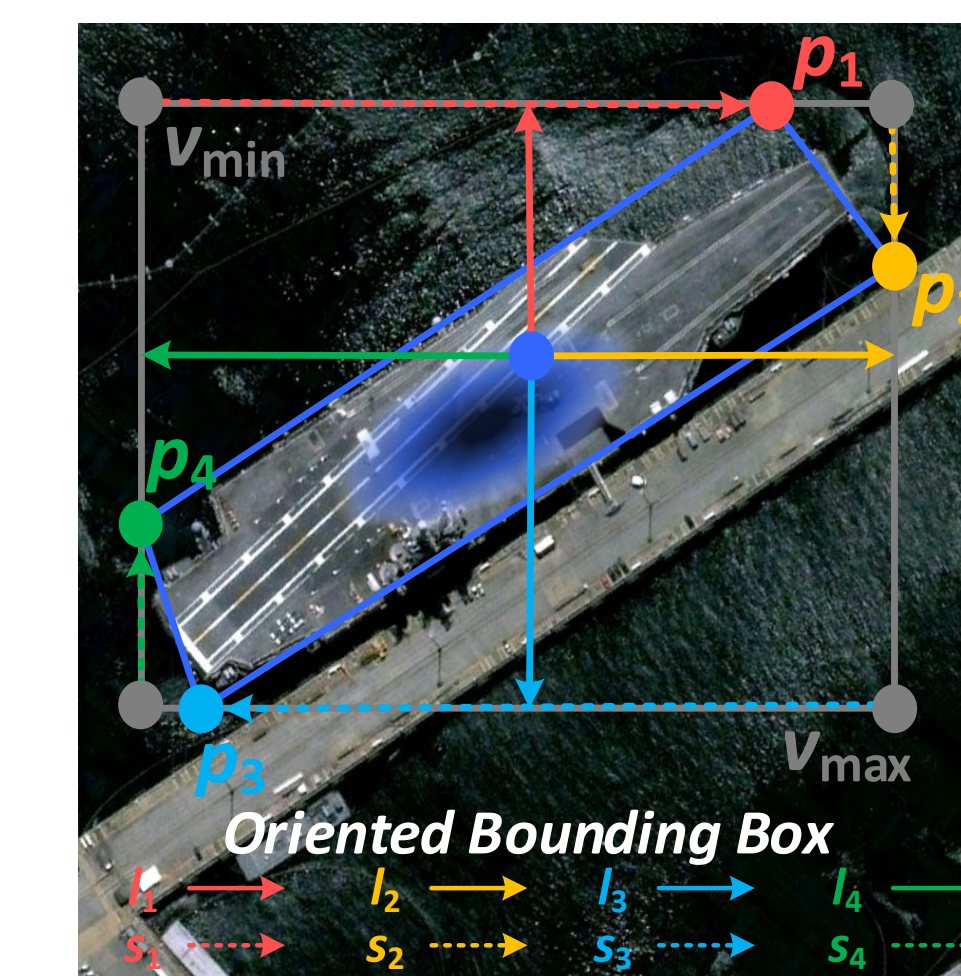


3) Feature Response Distillation $L_{drfd} = \|G \odot (Y'_T - Y'_S)\|_2^2$



Distill the direction-adaptive feature responses in the FPN of CNNs.

4) Prediction Distillation



Distill the predictions of detection heads in CNN models.

$$L_{obb}(r_T, r_S, r_{GT}) = \begin{cases} JOL_{obb}(r_S, r_{GT}), & \text{if } JOL_{obb}(r_S, r_{GT}) + \delta > JOL_{obb}(r_T, r_{GT}) \\ 0, & \text{otherwise} \end{cases}$$

$$L_{loc} = JOL_{obb}(r_S, r_{GT}) + \lambda \times L_{obb}(r_T, r_S, r_{GT})$$

$$L_{cls} = \lambda \times JOL_{cls}(c_S, c_{GT}) + (1 - \lambda) \times JOL_{cls}(c_T, c_S)$$

Use the predictions of teacher model as soft labels.

The Representation of Predictions: GGHL (Huang et al., TIP 2022)

Experimental Results

◆ Comparative Results w/wo Using DKED

Methods	mAP @HRSC	mAP @DOTA	Speed (fps) @RTX3090	Speed (fps) @TX2	Speed (fps) @AGX Xavier
LO-Det	80.05	66.17	62.12	7.34	23.51
DKED + LO-Det	85.17(+5.12)	71.39(+5.22)	62.16	7.38	23.51
GGHL	87.30	76.95	42.39	4.67	14.72
DKED + GGHL	93.45(+6.15)	77.43(+0.48)	42.39	4.69	14.73

● DKED improves the detection performance of lightweight model without introducing any inference costs;

● DKED can also be used for self-distillation of large models to further improve detection performance.

◆ Detection Results on HRSC & DOTA Datasets

