# Learning Expanding Graphs for Signal Interpolation

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#### Introduction

- Graph data processing, i.e., interpolation, classification usually done over fixed-size static and dynamic graphs.
- New nodes often emerge, increasing graph size, often without information (e.g. cold start recommendation).
- Existing works either assume known connectivity of new nodes, or independent attachment and data-processing.
- First term bias, second variance of prediction at  $v_+$ .
- Not always convex, solved using projected gradient descent

#### Results

• We propose a data-driven, task-aware stochastic attachment of new nodes, focusing on signal interpolation.

#### **Problem Formulation**

- Graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ , adjacency matrix  $\mathbf{A}$ , signal  $\mathbf{x}$ . Directed edge of weight  $w_i$  from  $v_i \in \mathcal{V}$ to  $v_+$  with prob  $p_i$ .
- Attachment vector a<sub>+</sub> with [a<sub>+</sub>]<sub>k</sub> = w<sub>k</sub> if v<sub>+</sub> connects to v<sub>k</sub>. a<sub>+</sub> has mean w ο p, covariance Σ<sub>+</sub>. p, w attachment
- New adjacency matrix  $\mathbf{A}_{+} = \begin{bmatrix} \mathbf{A} & \mathbf{0}_{+} \\ \mathbf{a}_{+}^{\top} & \mathbf{0} \end{bmatrix}$



• *Synthetic*: ER and BA graphs with 100 nodes, band-limited signals for order three filter.

	Erdős-Rényi			Barabasi-Albert		
	Prop.	Pref.	Rand.	Prop.	Pref.	Rand.
MSE	0.03	0.06	0.06	0.05	0.1	80.0
Std.	0.003	0.003	0.003	0.006	0.006	0.006
Table 1: Caption						

- Proposed outperforms topology-aware random attachments
- *Real*: Item cold start item collaborative filtering on Movielens 100K
- Trained on three sets of items-with low, medium and high number of interactions

2.5

parameters.

- Estimate  $(\mathbf{p}, \mathbf{w})$  over training set  $\mathcal{T} =$   $\{(v_{t+}, x_{t+}, \mathbf{a}_{t+})\}_t$  with  $x_{t+}, \mathbf{a}_{t+}$  observed signals and attachments.
- Figure 1: Incoming node attaching to an existing graph of five nodes.

### Signal Interpolation on Incoming Nodes

- Order L graph filter with coefficients  ${\bf h}$  and shift  ${\bf A}_+$  outputs at  $v_+$ 

$$y_{+} = \mathbf{a}_{+}^{\top} \sum_{l=1}^{L} h_{l} \mathbf{A}_{+}^{l} \mathbf{x} = \mathbf{a}_{+}^{\top} \mathbf{A}_{x} \mathbf{h}$$
(1)

We now solve  $(\mathbf{p}, \mathbf{w})$  via

$$\min_{\mathbf{p}, \mathbf{w}} \mathsf{MSE}_{\mathcal{T}}(\mathbf{p}, \mathbf{w}) + \sum_{t=1}^{|\mathcal{T}|} \left( \mu_p ||\mathbf{p} - \mathbf{b}_{t+}||_q^q + \mu_w ||\mathbf{w} - \mathbf{a}_{t+}||_q^q \right)$$
$$\mathbf{p} \in [0, 1]^N, \mathbf{w} \in \mathcal{W}$$



• Lowest error with low items (challenging scenario), robust for items with many interactions. Shows benefit of proposed model and problem formulation.

#### Conclusion

- We proposed learning a topology, data and task-aware attachment model for growing graphs.
- Solve for parameters via projected gradient descent.

$$\mathsf{MSE}_{\mathcal{T}}(\mathbf{p}, \mathbf{w}) = \|(\mathbf{w} \circ \mathbf{p})^{\top} \mathbf{A}_x \mathbf{h} - x_{+}^{\star}\|_2^2 + \mathbf{h}^{\top} \mathbf{A}_x^{\top} \mathbf{\Sigma}_{+} \mathbf{A}_x \mathbf{h} \quad (2)$$

- Outperform other attachment rules on real and synthetic data.
- Future work to address sequence of incoming nodes.



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