

Adversarially-Trained Nonnegative Matrix Factorization

Ting Cai¹, Vincent Y. F. Tan², Cédric Févotte³

¹ University of Wisconsin-Madison, ² National University of Singapore, ³ IRT Université de Toulouse

Poster ID: 9296

Nonnegative Matrix Factorization

- Given a **nonnegative** data matrix $\mathbf{V} \in \mathbb{R}_+^{F \times N}$, approximate $\mathbf{V} \approx \mathbf{WH}$ where $\mathbf{W} \in \mathbb{R}_+^{F \times K}$ (basis) and $\mathbf{H} \in \mathbb{R}_+^{K \times N}$ (coefficients). To find such a decomposition, one solves

$$\min_{\mathbf{W}, \mathbf{H} \geq \mathbf{0}} \|\mathbf{V} - \mathbf{WH}\|_F^2$$

where $\mathbf{A} \geq \mathbf{0}$ means \mathbf{A} 's entries are nonnegative.

- Motivation:** Improve the **predictive** performance of NMF using adversarial training for matrix completion tasks.
- Main Contribution:** Derive efficient algorithms for updating the adversary and (\mathbf{W}, \mathbf{H}) . Demonstrate the superior performance of adversarially-trained NMF or AT-NMF over other methods on matrix completion tasks for three benchmark datasets.

Formulation of AT-NMF

- Consider an **adversary** adds an **arbitrary** matrix $\mathbf{R} \in \mathbb{R}^{F \times N}$ to \mathbf{V} to maximize the divergence between \mathbf{V} and \mathbf{WH} , AT-NMF is formulated as

$$\min_{\mathbf{W}, \mathbf{H} \geq \mathbf{0}} \max_{\mathbf{R} \in \mathcal{R}} \|\mathbf{V} + \mathbf{R} - \mathbf{WH}\|_F^2$$

where the constraint set $\mathcal{R} := \{\mathbf{R} : \|\mathbf{R}\|_F^2 \leq \epsilon, \mathbf{V} + \mathbf{R} \geq \mathbf{0}\}$.

- $\epsilon > 0$ is a constant indicating the adversary's power.
- To relax the problem, dualize $\|\mathbf{R}\|_F^2 \leq \epsilon$ with a *Lagrange multiplier* $\lambda > 0$, AT-NMF becomes

$$\min_{\mathbf{W}, \mathbf{H} \geq \mathbf{0}} \max_{\mathbf{R}: \mathbf{V} + \mathbf{R} \geq \mathbf{0}} \|\mathbf{V} + \mathbf{R} - \mathbf{WH}\|_F^2 - \lambda \|\mathbf{R}\|_F^2.$$

AT-NMF Algorithm

Update of \mathbf{R}

- Let $\hat{\mathbf{V}} = \mathbf{WH}$, the inner maximization problem can be rewritten as a minimization problem as

$$\mathbf{R}^* = \arg \min_{\mathbf{R}: \mathbf{V} + \mathbf{R} \geq \mathbf{0}} -\|\mathbf{V} + \mathbf{R} - \hat{\mathbf{V}}\|_F^2 + \lambda \|\mathbf{R}\|_F^2$$

- The objective decomposes into the sum of FN independent terms

$$g(\mathbf{R}) = \sum_{f,n}^{F,N} [-(v_{fn} + r_{fn} - \hat{v}_{fn})^2 + \lambda r_{fn}^2].$$

- It suffices to minimize each term inside over r_{fn} . By re-arranging:

$$\min_{r_{fn}: v_{fn} + r_{fn} \geq 0} (\lambda - 1)r_{fn}^2 - 2r_{fn}(v_{fn} - \hat{v}_{fn})$$

AT-NMF Algorithm (cont)

- $-\lambda \in [0, 1]$ leads r_{fn}^* to ∞ . Choose $\lambda > 1$, the update of \mathbf{R} is

$$\mathbf{R} = \max \left\{ \frac{\mathbf{V} - \hat{\mathbf{V}}}{\lambda - 1}, -\mathbf{V} \right\}$$

Update of (\mathbf{W}, \mathbf{H})

- Regard $\mathbf{U} := \mathbf{V} + \mathbf{R}^*$, by **Majorization-Minimization** (MM) algorithm,

$$\mathbf{H} \leftarrow \mathbf{H} \cdot \frac{\mathbf{W}^\top \mathbf{U}}{\mathbf{W}^\top \mathbf{W} \mathbf{H}} \quad \text{and} \quad \mathbf{W} \leftarrow \mathbf{W} \cdot \frac{\mathbf{U} \mathbf{H}^\top}{\mathbf{W} \mathbf{H} \mathbf{H}^\top}$$

Initialization of (\mathbf{W}, \mathbf{H})

- Sample each entries independently from Half-Normal distribution ($\gamma = 1$),
- Run 5 standard MM steps on \mathbf{V} to obtain \mathbf{W}_{init} and \mathbf{H}_{init} .

Stopping Criteria of AT-NMF

- $(\mathbf{W}^{(o,i)}, \mathbf{H}^{(o,i)})$ denotes the iterate of (\mathbf{W}, \mathbf{H}) at the o^{th} outer iteration and i^{th} inner iteration and $\hat{\mathbf{V}}^{(o,i)} := \mathbf{W}^{(o,i)} \mathbf{H}^{(o,i)}$. ϵ_{in} and ϵ_{out} are positive constants.
- Terminate the inner optimization once the inner iteration i satisfies

$$\left\| \frac{\hat{\mathbf{V}}^{(o,i+1)} - \hat{\mathbf{V}}^{(o,i)}}{\hat{\mathbf{V}}^{(o,i)}} \right\|_F < \epsilon_{\text{in}}$$

- Terminate the entire optimization once the outer iteration o satisfies

$$\left\| \frac{\hat{\mathbf{V}}^{(o+1,i)} - \hat{\mathbf{V}}^{(o,i)}}{\hat{\mathbf{V}}^{(o,i)}} \right\|_F < \epsilon_{\text{out}}$$

Synthetic Dataset

- $\alpha \in \{0.1, 0.2, \dots, 0.8, 0.9\}$ denotes the fraction of held-out entries. $\Gamma \subset \{1, \dots, F\} \times \{1, \dots, N\}$ is the set of held-out entries of \mathbf{V} . \hat{v}_{fn} is the prediction of v_{fn} . Our performance metric is the root mean-squared error (RMSE)

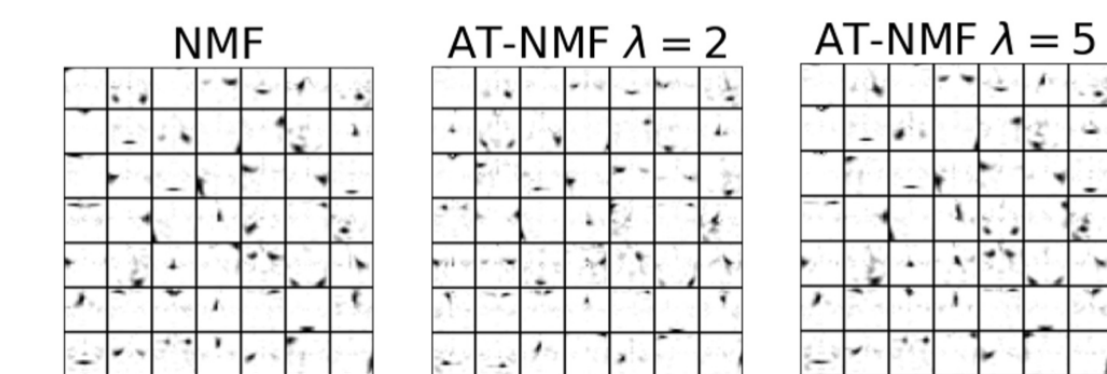
$$\text{RMSE} := \sqrt{\frac{1}{|\Gamma|} \sum_{(f,n) \in \Gamma} (v_{fn} - \hat{v}_{fn})^2}$$

- Synthetic dataset of $F = 100$, $N = 50$, and $K = 5$.
- RMSE of Synthetic dataset

α	NMF	ANMF	AT-NMF (2)	AT-NMF (3)	AT-NMF (5)
0.3	5.37 \pm 0.02	6.78 \pm 0.17	5.41 \pm 0.12	5.11 \pm 0.03	5.20 \pm 0.02
0.4	5.62 \pm 0.03	6.92 \pm 0.17	5.54 \pm 0.08	5.32 \pm 0.09	5.42 \pm 0.04
0.5	6.41 \pm 0.01	7.44 \pm 0.09	6.27 \pm 0.11	6.05 \pm 0.03	6.18 \pm 0.02
0.6	6.74 \pm 0.02	7.61 \pm 0.09	6.47 \pm 0.07	6.39 \pm 0.03	6.53 \pm 0.02
0.7	7.30 \pm 0.01	7.99 \pm 0.06	7.02 \pm 0.04	6.94 \pm 0.01	7.10 \pm 0.02
0.8	7.87 \pm 0.01	8.30 \pm 0.06	7.69 \pm 0.04	7.61 \pm 0.03	7.71 \pm 0.00
0.9	8.45 \pm 0.01	8.58 \pm 0.06	8.44 \pm 0.02	8.34 \pm 0.02	8.35 \pm 0.02

CBCL Dataset

- $N = 2429$ facial images with $F = 361$ pixels.
- Parts learnt** when $\alpha = 0.1$



- Image Restoration** by AT-NMF

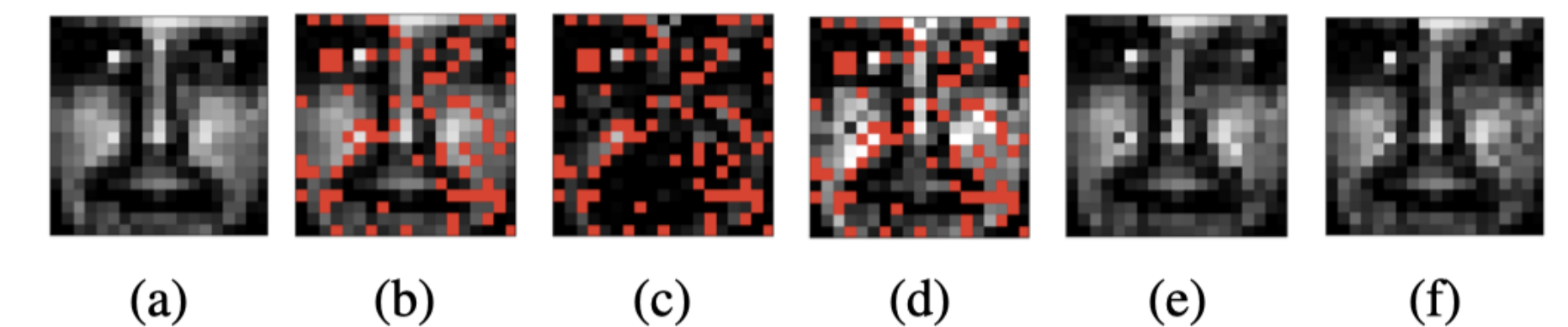
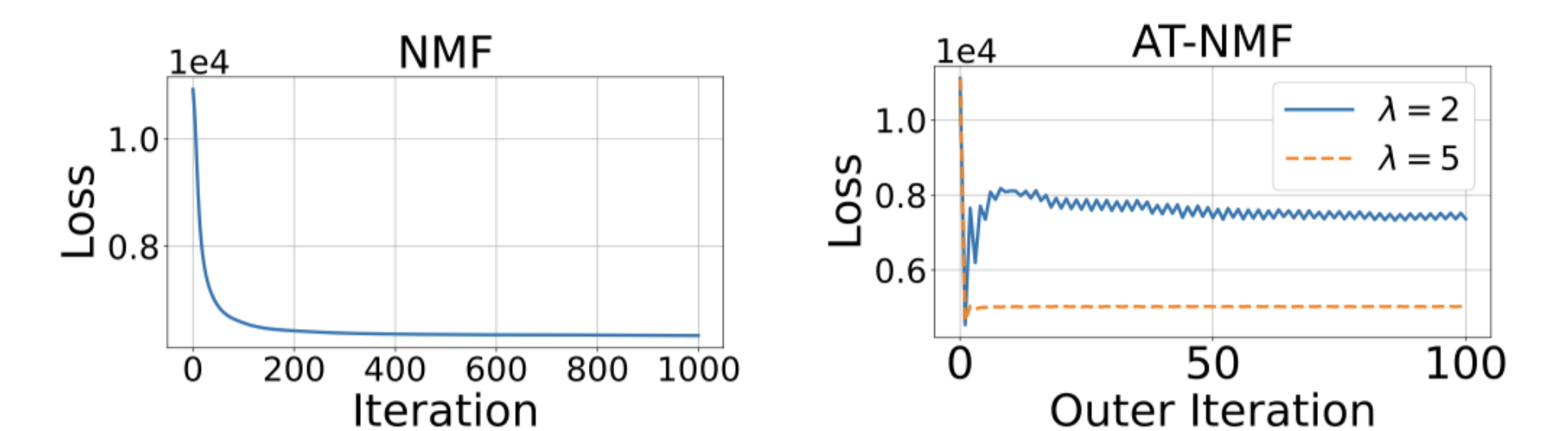


Fig. 3: (a) Original Image \mathbf{V} ; (b) Masked training image (missing pixels in red) \mathbf{V} ; (c) Adversary's added-on masked image \mathbf{R}^* ; (d) Adversarially trained masked image $\mathbf{V} + \mathbf{R}^*$; (e) Restored image using AT-NMF; (f) Restored image using NMF when $\alpha = 0.2$ and $\lambda = 2$.

- Training losses when $\alpha = 0.5$



Hyperspectral Dataset

- It includes the Moffet and Madonna datasets with $F = 165$ and $F = 160$ respectively and $N = 2500$.
- Effect of λ on the RMSE

