

Graph Filter Banks with M -Channels, Maximal Decimation, and Perfect Reconstruction

Oguzhan Teke P. P. Vaidyanathan

Department of Electrical Engineering
California Institute of Technology

ICASSP - 2016

Caltech

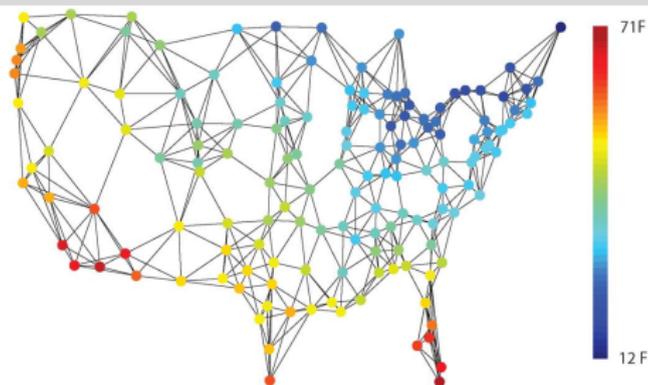
Outline

- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks
 - Extending Classical Tools to Graph Case
- 3 Multirate Processing of Graph Signals
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 Some Examples

Outline

- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks
 - Extending Classical Tools to Graph Case
- 3 Multirate Processing of Graph Signals
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 Some Examples

What is a Graph Signal ?



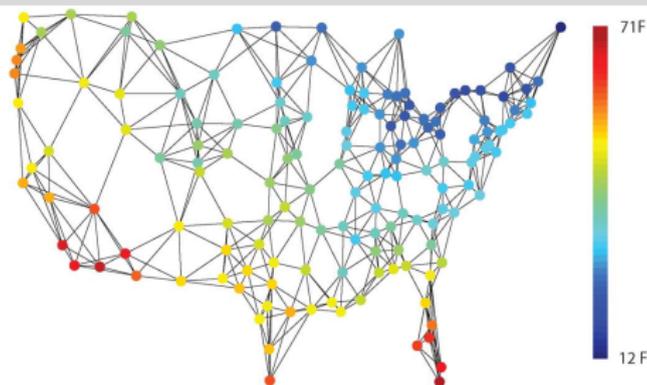
$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_N \end{bmatrix} \in \mathcal{C}^N$$

¹ A. Sandryhaila and J. M. F. Moura. "Discrete Signal Processing on Graphs: Frequency Analysis". In: *IEEE Trans. Signal Process.* 62.12 (2014), pp. 3042–3054.

² A. Sandryhaila and J. M. F. Moura. "Big Data Analysis with Signal Processing on Graphs: Representation and processing of massive data sets with irregular structure". In: *IEEE Signal Processing Magazine* 31.5 (2014), pp. 80–90.

³ D.I. Shuman et al. "The emerging field of signal processing on graphs: Extending high-dimensional data analysis to networks and other irregular domains". In: *IEEE Signal Processing Magazine* 30.3 (2013), pp. 83–98.

What is a Graph Signal ?



$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_N \end{bmatrix} \in \mathcal{C}^N$$

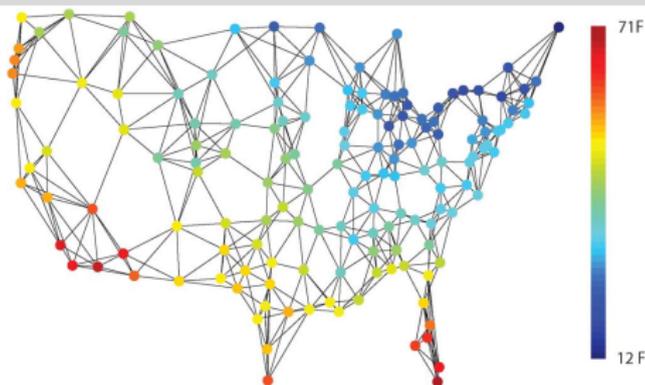
\mathbf{A} is the adjacency matrix^{1,2,3}, $\mathbf{A} \in \mathcal{M}^N$

¹ A. Sandryhaila and J. M. F. Moura. "Discrete Signal Processing on Graphs: Frequency Analysis". In: *IEEE Trans. Signal Process.* 62.12 (2014), pp. 3042–3054.

² A. Sandryhaila and J. M. F. Moura. "Big Data Analysis with Signal Processing on Graphs: Representation and processing of massive data sets with irregular structure". In: *IEEE Signal Processing Magazine* 31.5 (2014), pp. 80–90.

³ D.I. Shuman et al. "The emerging field of signal processing on graphs: Extending high-dimensional data analysis to networks and other irregular domains". In: *IEEE Signal Processing Magazine* 30.3 (2013), pp. 83–98.

What is a Graph Signal ?



$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_N \end{bmatrix} \in \mathcal{C}^N$$

\mathbf{A} is the adjacency matrix^{1,2,3}, $\mathbf{A} \in \mathcal{M}^N$

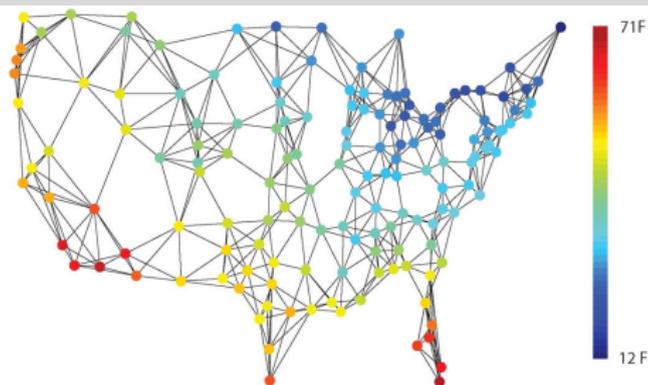
\mathbf{A} is considered as the *graph operator*, with $\mathbf{A} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^{-1}$

¹ A. Sandryhaila and J. M. F. Moura. "Discrete Signal Processing on Graphs: Frequency Analysis". In: *IEEE Trans. Signal Process.* 62.12 (2014), pp. 3042–3054.

² A. Sandryhaila and J. M. F. Moura. "Big Data Analysis with Signal Processing on Graphs: Representation and processing of massive data sets with irregular structure". In: *IEEE Signal Processing Magazine* 31.5 (2014), pp. 80–90.

³ D.I. Shuman et al. "The emerging field of signal processing on graphs: Extending high-dimensional data analysis to networks and other irregular domains". In: *IEEE Signal Processing Magazine* 30.3 (2013), pp. 83–98.

What is a Graph Signal ?



$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_N \end{bmatrix} \in \mathcal{C}^N$$

\mathbf{A} is the adjacency matrix^{1,2,3}, $\mathbf{A} \in \mathcal{M}^N$

\mathbf{A} is considered as the *graph operator*, with $\mathbf{A} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^{-1}$

\mathbf{V} = graph Fourier Basis, \mathbf{V}^{-1} = graph Fourier Transform

¹A. Sandryhaila and J. M. F. Moura. "Discrete Signal Processing on Graphs: Frequency Analysis". In: *IEEE Trans. Signal Process.* 62.12 (2014), pp. 3042–3054.

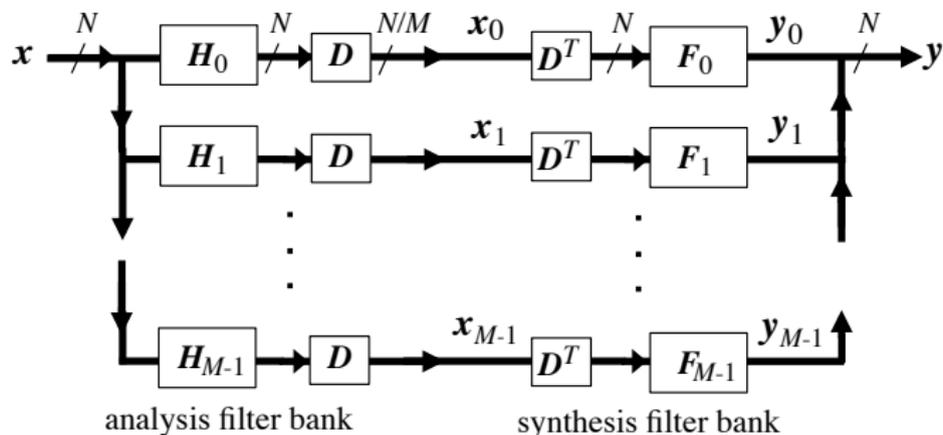
²A. Sandryhaila and J. M. F. Moura. "Big Data Analysis with Signal Processing on Graphs: Representation and processing of massive data sets with irregular structure". In: *IEEE Signal Processing Magazine* 31.5 (2014), pp. 80–90.

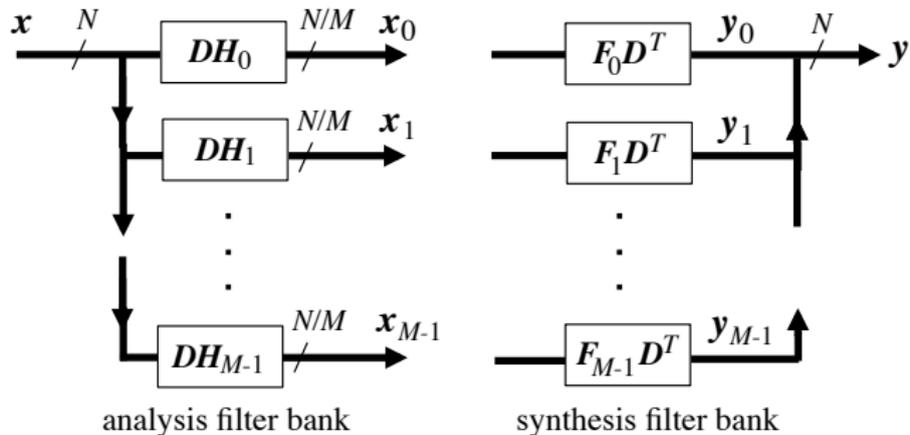
³D.I. Shuman et al. "The emerging field of signal processing on graphs: Extending high-dimensional data analysis to networks and other irregular domains". In: *IEEE Signal Processing Magazine* 30.3 (2013), pp. 83–98.

Outline

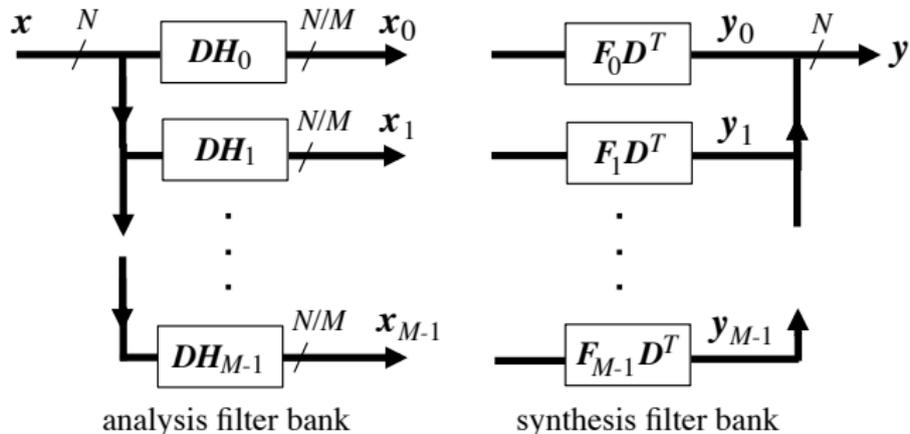
- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks**
 - Extending Classical Tools to Graph Case**
- 3 Multirate Processing of Graph Signals
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 Some Examples

Maximally Decimated M -Channel Filter Banks



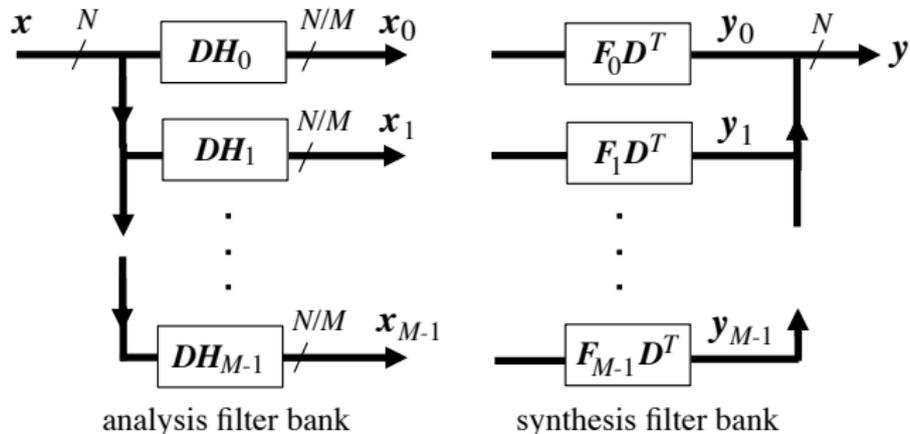
M -Channel Filter Banks (Brute-Force)

M -Channel Filter Banks (Brute-Force)



$$\mathbf{H}_{anal} = \begin{bmatrix} DH_0 \\ \vdots \\ DH_{M-1} \end{bmatrix}, \quad \mathbf{F}_{syn} = [F_0 D^T \quad \cdots \quad F_{M-1} D^T]$$

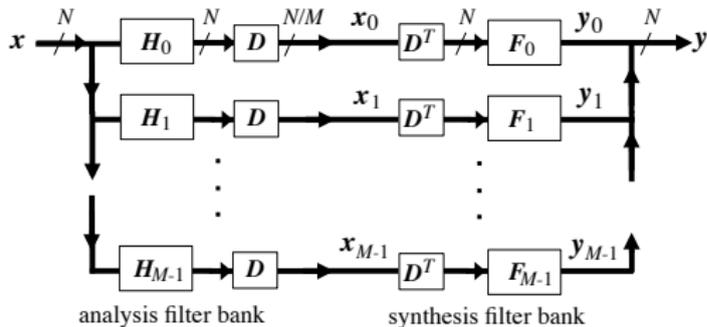
M -Channel Filter Banks (Brute-Force)



$$\mathbf{H}_{anal} = \begin{bmatrix} DH_0 \\ \vdots \\ DH_{M-1} \end{bmatrix}, \quad \mathbf{F}_{syn} = [F_0 D^T \quad \cdots \quad F_{M-1} D^T]$$

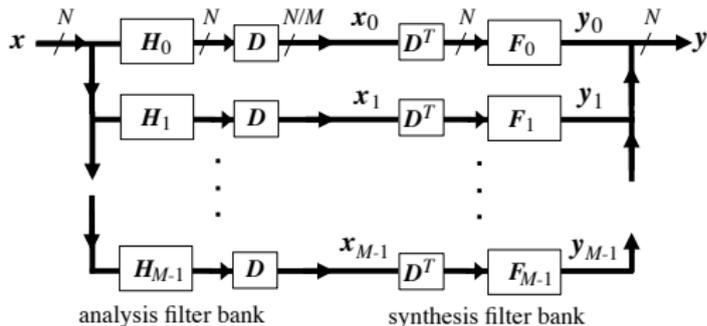
$$\mathbf{F}_{syn} \mathbf{H}_{anal} = \mathbf{I}$$

Problems with Brute-Force



$$\mathbf{F}_{syn} \mathbf{H}_{anal} = \mathbf{I}$$

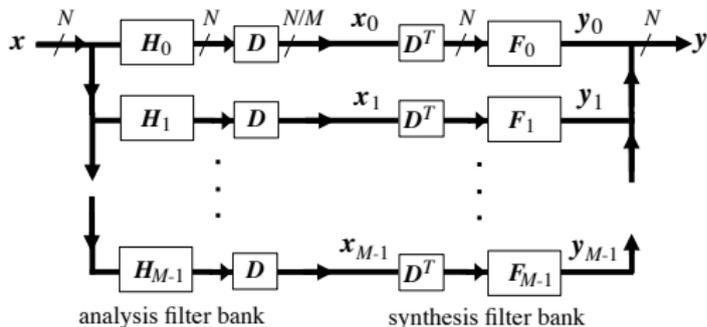
Problems with Brute-Force



$$\mathbf{F}_{syn} \mathbf{H}_{anal} = \mathbf{I}$$

$$\mathbf{F}_{syn} = \mathbf{H}_{anal}^{-1}$$

Problems with Brute-Force



$$\mathbf{F}_{syn} \mathbf{H}_{anal} = \mathbf{I}$$

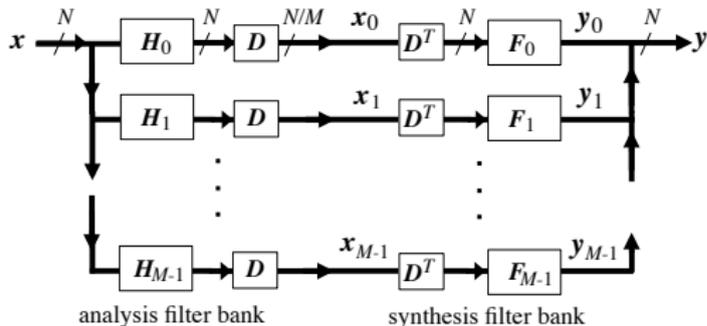
$$\mathbf{F}_{syn} = \mathbf{H}_{anal}^{-1}$$

Filter Design



Matrix Inversion Problem

Problems with Brute-Force



Relation with A ?

$$F_{syn} H_{anal} = I$$

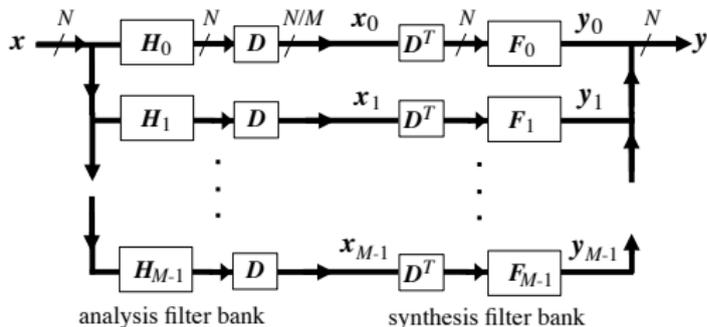
$$F_{syn} = H_{anal}^{-1}$$

Filter Design



Matrix Inversion Problem

Problems with Brute-Force



Relation with A ?

$$F_{syn} H_{anal} = I$$

$$F_{syn} = H_{anal}^{-1}$$

Computational Complexity = $O(N^2)$

Filter Design



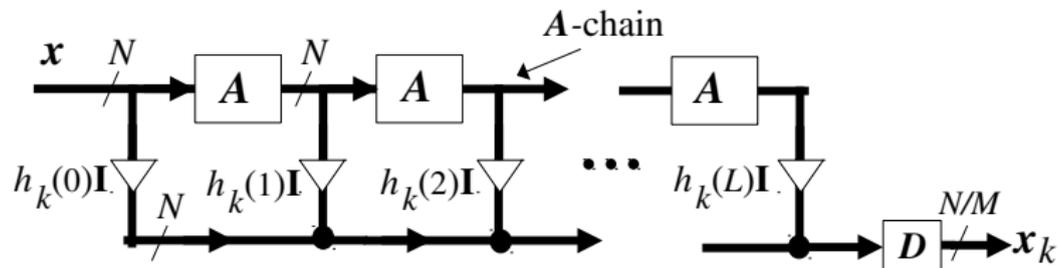
Matrix Inversion Problem

Polynomials

$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$

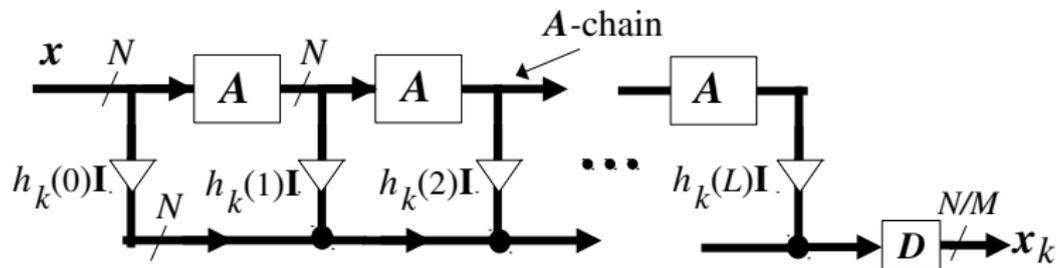
Polynomials

$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$



Polynomials

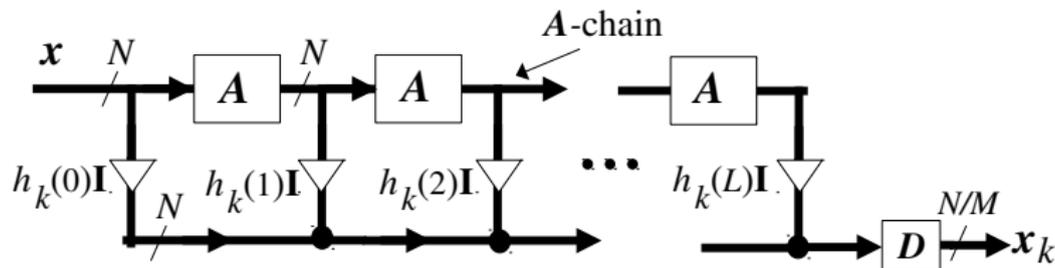
$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$



Cost: $LN^2 + LN$

Polynomials

$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$

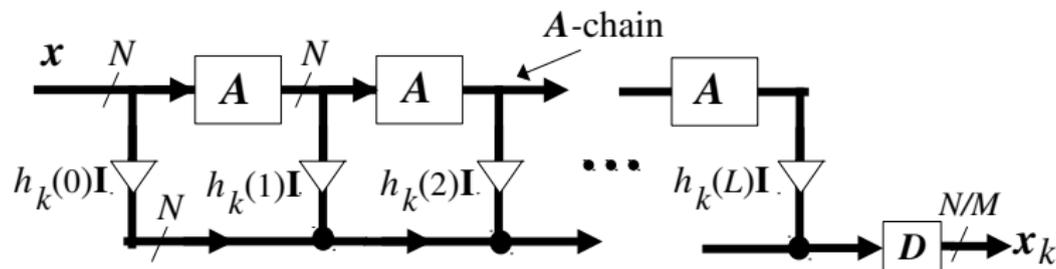


$$\text{Cost: } LN^2 + LN$$

\mathbf{A} has simple entries, e.g. $\{0, 1, -1\}$, $\Rightarrow \mathbf{A}\mathbf{x}$ has negligible complexity

Polynomials

$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$



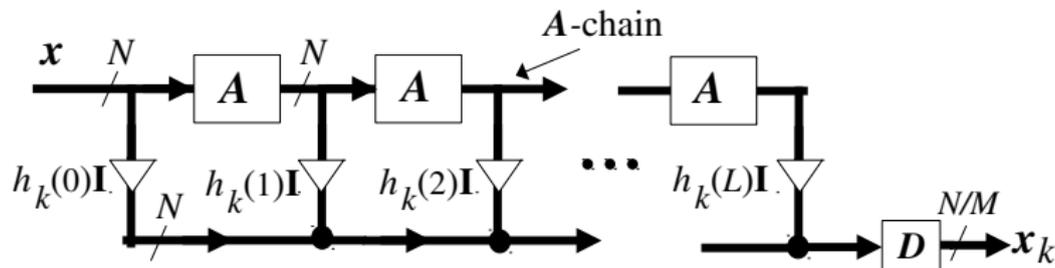
$$\text{Cost: } \cancel{LN^2} + LN$$

\mathbf{A} has simple entries, e.g. $\{0, 1, -1\}$, $\Rightarrow \mathbf{A} \mathbf{x}$ has negligible complexity

Cost of $\mathbf{H}_k(\mathbf{A})$ is $O(LN)$ v.s. $O(N^2)$ in brute-force

Polynomials

$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$



$$\text{Cost: } LN^2 + LN$$

\mathbf{A} has simple entries, e.g. $\{0, 1, -1\}$, $\Rightarrow \mathbf{A}\mathbf{x}$ has negligible complexity

Cost of $\mathbf{H}_k(\mathbf{A})$ is $O(LN)$ v.s. $O(N^2)$ in brute-force

$$L \ll N$$

Outline

- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks
 - Extending Classical Tools to Graph Case
- 3 Multirate Processing of Graph Signals**
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 Some Examples

M -Fold Decimation

$$\mathbf{D} : \mathbb{C}^N \rightarrow \mathbb{C}^{N/M}$$

M -Fold Decimation

$$\mathbf{D} : \mathbb{C}^N \rightarrow \mathbb{C}^{N/M}$$

$$\mathbf{D} \mathbf{x}$$

M -Fold Decimation

$$D : C^N \rightarrow C^{N/M}$$

$$D x$$

Which samples to keep?

M -Fold Decimation

$$D : C^N \rightarrow C^{N/M}$$

$$D x$$

Which samples to keep?

Assume an appropriate permutation (labeling) of the nodes

Keep the first N/M samples

M -Fold Decimation

$$D : C^N \rightarrow C^{N/M}$$

$$D x$$

Which samples to keep?

Assume an appropriate permutation (labeling) of the nodes

Keep the first N/M samples

Why? Labelling of the nodes is arbitrary!

M -Fold Decimation

$$\mathbf{D} : \mathbb{C}^N \rightarrow \mathbb{C}^{N/M}$$

$$\mathbf{D} \mathbf{x}$$

Which samples to keep?

Assume an appropriate permutation (labeling) of the nodes

Keep the first N/M samples

Why? Labelling of the nodes is arbitrary!

Definition (Canonical Decimator)

$$\mathbf{D} = \left[\mathbf{I}_{N/M} \quad \mathbf{0}_{N/M} \quad \cdots \quad \mathbf{0}_{N/M} \right] \in \mathbb{C}^{(N/M) \times N},$$

which retains the first N/M samples of the given graph signal.

M -fold Expansion

$$U : C^{N/M} \rightarrow C^N$$

M -fold Expansion

$$U : \mathcal{C}^{N/M} \rightarrow \mathcal{C}^N$$

Given the decimator $D = [\mathbf{I}_{N/M} \quad \mathbf{0}_{N/M} \quad \cdots \quad \mathbf{0}_{N/M}]$

$$U = D^T = \begin{bmatrix} \mathbf{I}_{N/M} \\ \mathbf{0}_{N/M} \\ \vdots \\ \mathbf{0}_{N/M} \end{bmatrix} \in \mathcal{C}^{N \times (N/M)}$$

M -fold Expansion

$$U : \mathcal{C}^{N/M} \rightarrow \mathcal{C}^N$$

Given the decimator $D = [\mathbf{I}_{N/M} \quad \mathbf{0}_{N/M} \quad \cdots \quad \mathbf{0}_{N/M}]$

$$U = D^T = \begin{bmatrix} \mathbf{I}_{N/M} \\ \mathbf{0}_{N/M} \\ \vdots \\ \mathbf{0}_{N/M} \end{bmatrix} \in \mathcal{C}^{N \times (N/M)}$$

Upsample-then-downsample, DU , is unity

$$DU = I$$

M -fold Expansion

$$U : \mathbb{C}^{N/M} \rightarrow \mathbb{C}^N$$

Given the decimator $D = [\mathbf{I}_{N/M} \quad \mathbf{0}_{N/M} \quad \cdots \quad \mathbf{0}_{N/M}]$

$$U = D^T = \begin{bmatrix} \mathbf{I}_{N/M} \\ \mathbf{0}_{N/M} \\ \vdots \\ \mathbf{0}_{N/M} \end{bmatrix} \in \mathbb{C}^{N \times (N/M)}$$

Upsample-then-downsample, DU , is unity

$$DU = I$$

$$D^T = \arg \min_U \|U\|_F \quad \text{s.t.} \quad DU = I$$

M -block cyclic graphs

^a[O. Teke and P. P. Vaidyanathan](#). "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$$\mathbf{A}_j \in \mathcal{M}^{N/M}$$

(Under suitable permutation)

^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

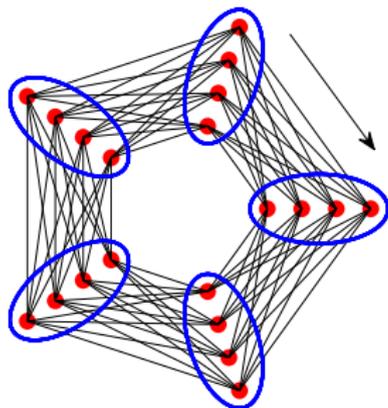
^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$$\mathbf{A}_j \in \mathcal{M}^{N/M}$$

(Under suitable permutation)



^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

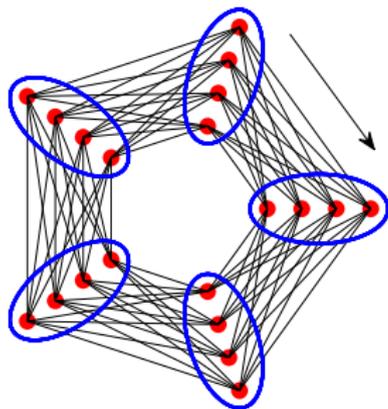
^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$$\mathbf{A}_j \in \mathcal{M}^{N/M}$$

(Under suitable permutation)



- 1** If a graph is M -block cyclic, then it is M -partite, but not vice-versa.

^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

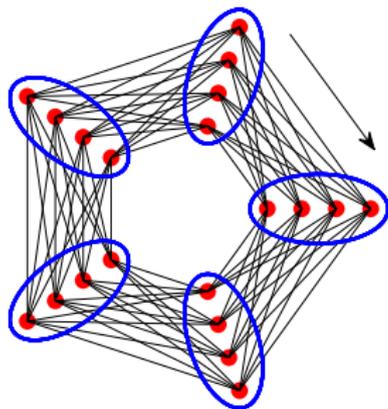
^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$$\mathbf{A}_j \in \mathcal{M}^{N/M}$$

(Under suitable permutation)



- 1 If a graph is M -block cyclic, then it is M -partite, but not vice-versa.
- 2 A graph is 2-block cyclic if and only if it is bi-partite.

^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

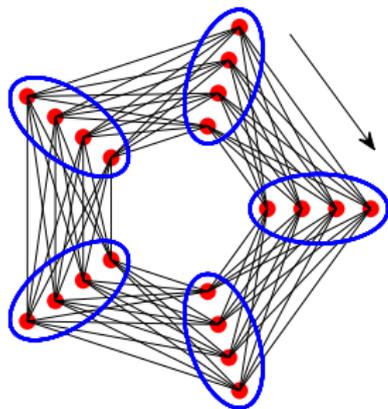
^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$$\mathbf{A}_j \in \mathcal{M}^{N/M}$$

(Under suitable permutation)



- 1 If a graph is M -block cyclic, then it is M -partite, but not vice-versa.
- 2 A graph is 2-block cyclic if and only if it is bi-partite.
- 3 An M -block cyclic graph is necessarily a directed graph for $M > 2$.

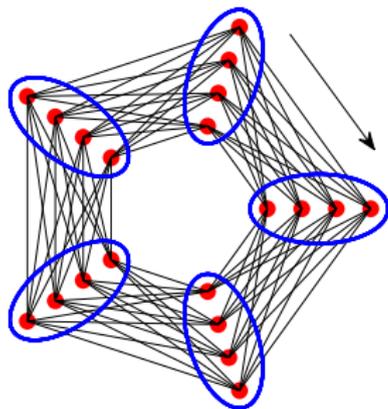
^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$\mathbf{A}_j \in \mathcal{M}^{N/M}$
(Under suitable permutation)



- 1 If a graph is M -block cyclic, then it is M -partite, but not vice-versa.
- 2 A graph is 2-block cyclic if and only if it is bi-partite.
- 3 An M -block cyclic graph is necessarily a directed graph for $M > 2$.
- 4 A cyclic graph of size N , \mathcal{C}_N , is an M -block cyclic graph for all M that divides N .

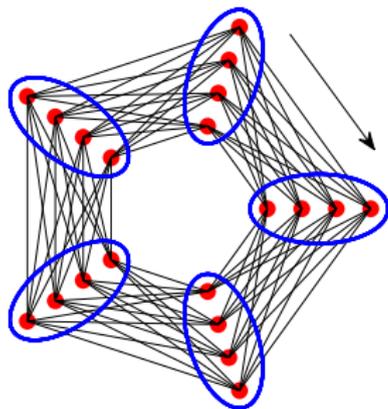
^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

^b

M -block cyclic graphs

$$\mathbf{A} = \begin{bmatrix} \mathbf{0} & \cdots & \mathbf{0} & \mathbf{A}_M \\ \mathbf{A}_1 & \cdots & \mathbf{0} & \mathbf{0} \\ \vdots & \ddots & \mathbf{0} & \vdots \\ \mathbf{0} & \cdots & \mathbf{A}_{M-1} & \mathbf{0} \end{bmatrix} \in \mathcal{M}^N$$

$\mathbf{A}_j \in \mathcal{M}^{N/M}$
(Under suitable permutation)



- 1 If a graph is M -block cyclic, then it is M -partite, but not vice-versa.
- 2 A graph is 2-block cyclic if and only if it is bi-partite.
- 3 An M -block cyclic graph is necessarily a directed graph for $M > 2$.
- 4 A cyclic graph of size N , \mathcal{C}_N , is an M -block cyclic graph for all M that divides N .
- 5 **Unique eigenvalue & eigenvector structure** ^{a b}

^aO. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

^bD. S. Watkins. "Product eigenvalue problems" *SIAM Review*, 2005

Spectrum Folding - Aliasing

Let x be a graph signal

$$y = D^T D x$$

Spectrum Folding - Aliasing

Let x be a graph signal

$$y = D^T D x$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ x_{\frac{N}{M}+1} \\ \vdots \\ \vdots \\ \vdots \\ x_N \end{bmatrix}$$

Spectrum Folding - Aliasing

Let x be a graph signal

$$y = D^T D x$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ x_{\frac{N}{M}+1} \\ \vdots \\ \vdots \\ \vdots \\ x_N \end{bmatrix} \xrightarrow{D} \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \end{bmatrix}$$

Spectrum Folding - Aliasing

Let x be a graph signal

$$y = D^T D x$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ x_{\frac{N}{M}+1} \\ \vdots \\ \vdots \\ \vdots \\ x_N \end{bmatrix} \xrightarrow{D} \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \end{bmatrix} \xrightarrow{D^T} \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ 0 \\ \vdots \\ \vdots \\ \vdots \\ 0 \end{bmatrix} = \mathbf{y}$$

Spectrum Folding - Aliasing

Let x be a graph signal

$$y = D^T D x$$

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ x_{\frac{N}{M}+1} \\ \vdots \\ \vdots \\ \vdots \\ x_N \end{bmatrix} \xrightarrow{D} \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \end{bmatrix} \xrightarrow{D^T} \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ 0 \\ \vdots \\ \vdots \\ \vdots \\ 0 \end{bmatrix} = \mathbf{y}$$

What is the relation between \hat{x} and \hat{y} ?

What is the relation between $\hat{\mathbf{x}}$ and $\hat{\mathbf{y}}$?

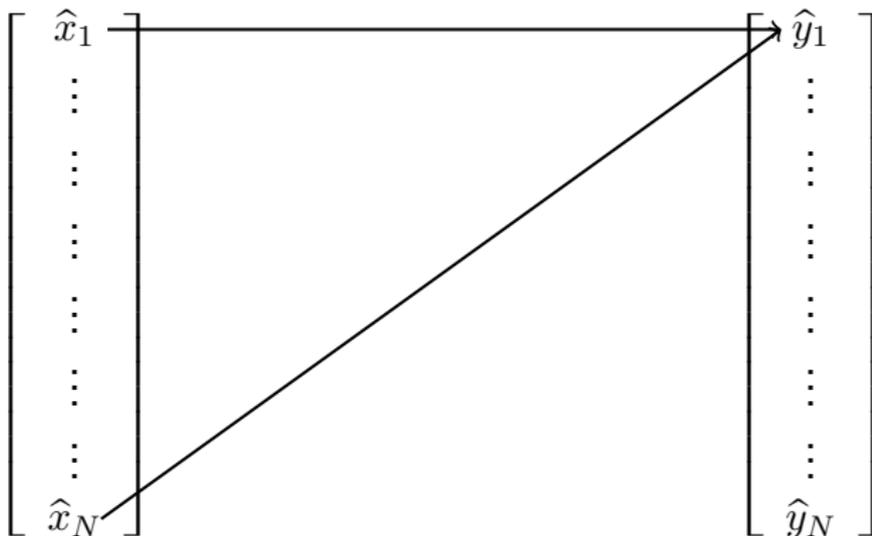
$$\hat{\mathbf{y}} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{\mathbf{x}}$$

$$\begin{bmatrix} \hat{x}_1 \\ \vdots \\ \hat{x}_N \end{bmatrix}$$

$$\begin{bmatrix} \hat{y}_1 \\ \vdots \\ \hat{y}_N \end{bmatrix}$$

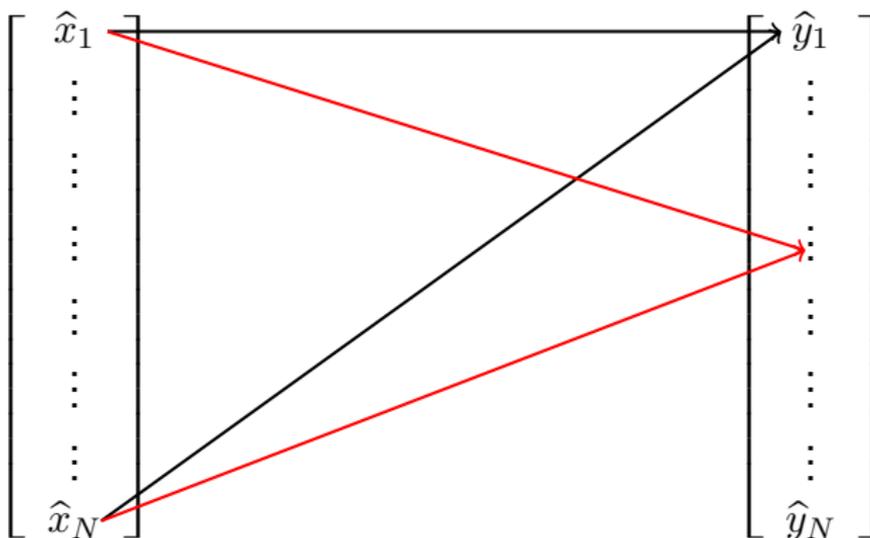
What is the relation between $\hat{\mathbf{x}}$ and $\hat{\mathbf{y}}$?

$$\hat{\mathbf{y}} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{\mathbf{x}}$$



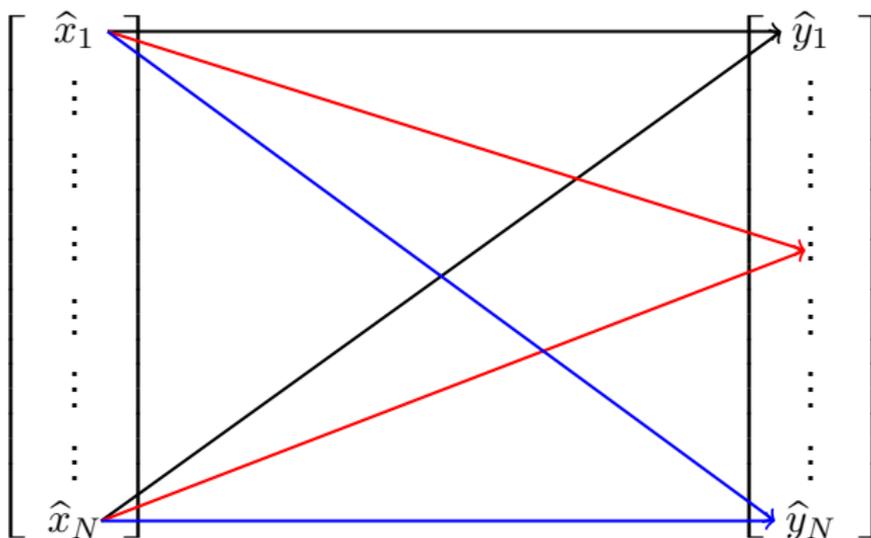
What is the relation between $\hat{\mathbf{x}}$ and $\hat{\mathbf{y}}$?

$$\hat{\mathbf{y}} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{\mathbf{x}}$$



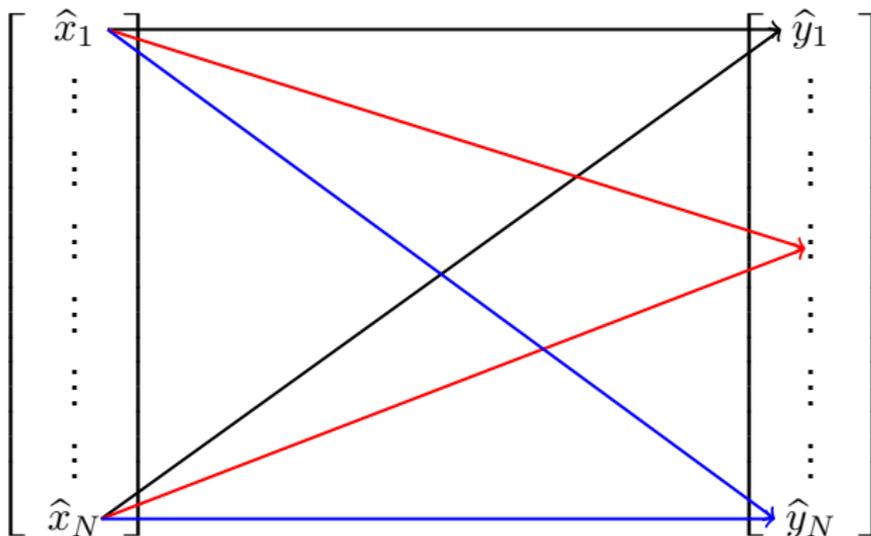
What is the relation between $\hat{\mathbf{x}}$ and $\hat{\mathbf{y}}$?

$$\hat{\mathbf{y}} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{\mathbf{x}}$$



What is the relation between \hat{x} and \hat{y} ?

$$\hat{y} = V^{-1} D^T D V \hat{x}$$



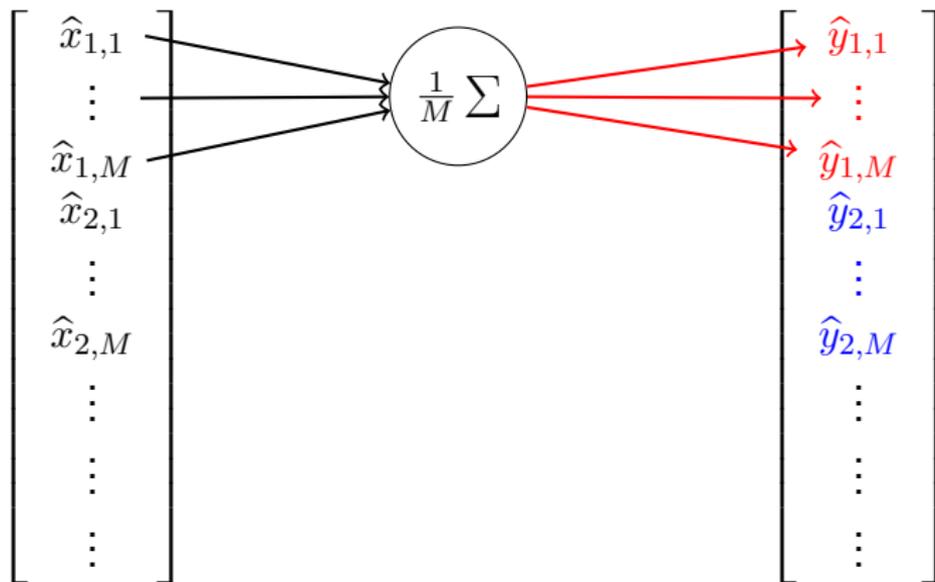
No "simple" relation in general!

Spectrum Folding on M -Block Cyclic Graphs

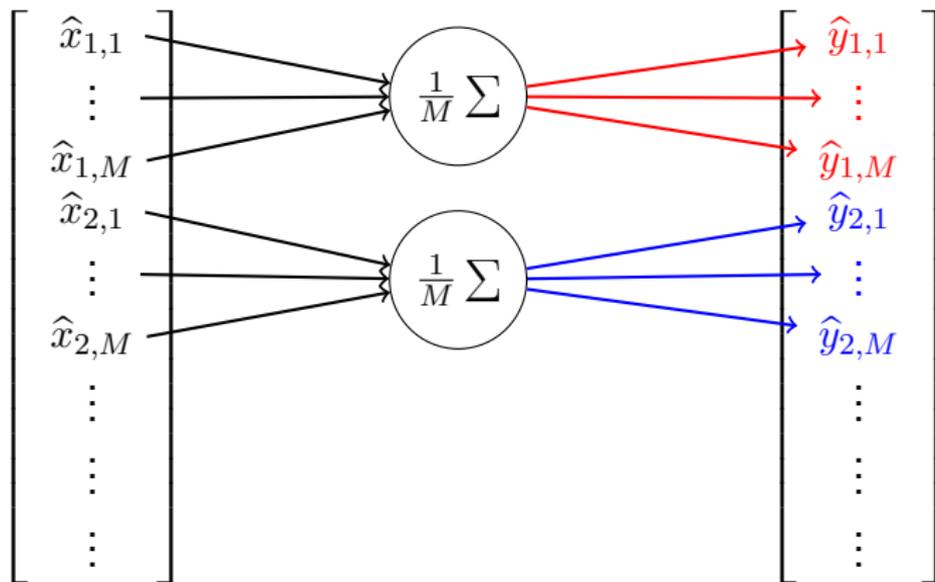
$$\begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

$$\begin{bmatrix} \hat{y}_{1,1} \\ \vdots \\ \hat{y}_{1,M} \\ \hat{y}_{2,1} \\ \vdots \\ \hat{y}_{2,M} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

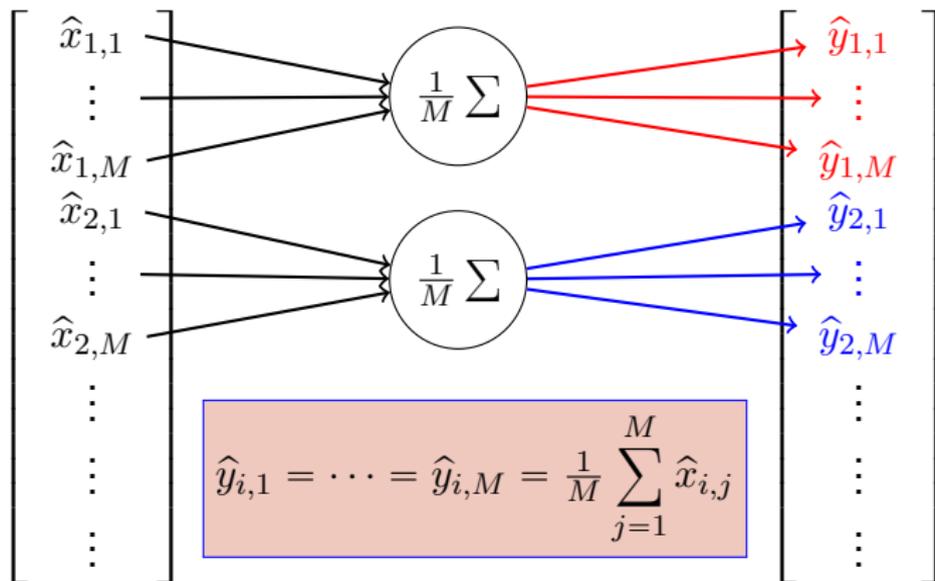
Spectrum Folding on M -Block Cyclic Graphs



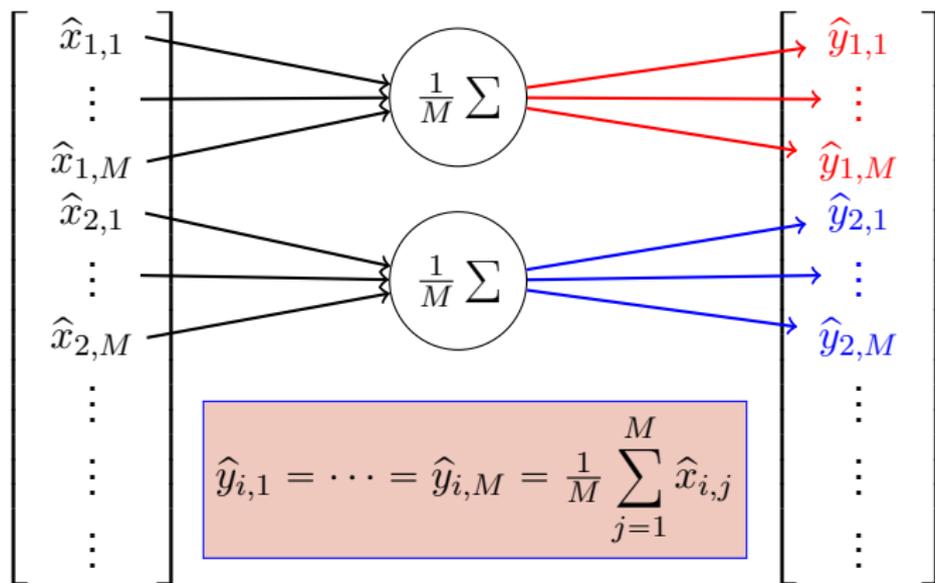
Spectrum Folding on M -Block Cyclic Graphs



Spectrum Folding on M -Block Cyclic Graphs



Spectrum Folding on M -Block Cyclic Graphs



$M = 2 \Leftrightarrow$ Bi-partite ⁴

⁴S.K. Narang and A. Ortega. "Perfect Reconstruction Two-Channel Wavelet Filter Banks for Graph Structured Data". *IEEE Trans. Signal Process.* 60.6 (2012), pp. 2786–2799.

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{\substack{k^{th} \\ \text{band} \\ \text{limited}}} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{\substack{k^{th} \\ \text{band} \\ \text{limited}}} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{D^T D}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{\substack{k^{th} \\ \text{band} \\ \text{limited}}} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{D^T D} \hat{\mathbf{y}} = \begin{bmatrix} \hat{y}_{1,1} \\ \vdots \\ \hat{y}_{1,M} \\ \hat{y}_{2,1} \\ \vdots \\ \hat{y}_{2,M} \\ \hat{y}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{\text{\textit{k}^{th} band limited}} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{D^T D} \hat{\mathbf{y}} = \begin{bmatrix} \hat{y}_{1,1} \\ \vdots \\ \hat{y}_{1,M} \\ \hat{y}_{2,1} \\ \vdots \\ \hat{y}_{2,M} \\ \hat{y}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[\text{(interpolation)}]{\mathbf{z} = \mathbf{F}\mathbf{y}}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[\text{(interpolation)}]{\mathbf{z} = \mathbf{F}\mathbf{y}} \hat{\mathbf{z}} = \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ 0 \\ 0 \\ \vdots \\ \vdots \end{bmatrix} = \hat{\mathbf{x}}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[\text{(interpolation)}]{\mathbf{z} = \mathbf{F}\mathbf{y}} \hat{\mathbf{z}} = \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ 0 \\ 0 \\ \vdots \\ \vdots \end{bmatrix} = \hat{\mathbf{x}}$$

Not true for an arbitrary \mathbf{x} !

For k^{th} -band-limited signals, \mathbf{x} can be recovered from $D\mathbf{x}$

M -Channel Filter-Banks on M -Block Cyclic Graphs

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

M -Channel Filter-Banks on M -Block Cyclic Graphs

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} = \underbrace{\begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{3,1} \\ 0 \\ \vdots \\ 0 \\ \vdots \end{bmatrix}}_{\hat{\mathbf{x}}_1 = 1^{st}} + \underbrace{\begin{bmatrix} 0 \\ \hat{x}_{1,2} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,2} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,2} \\ \vdots \\ 0 \\ \vdots \end{bmatrix}}_{\hat{\mathbf{x}}_2 = 2^{nd}} + \dots + \underbrace{\begin{bmatrix} 0 \\ \vdots \\ 0 \\ \hat{x}_{1,M} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{2,M} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix}}_{\hat{\mathbf{x}}_M = M^{th}}$$

M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix}$$

M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{x}}_k =]{\mathbf{H}_k} \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix}$$

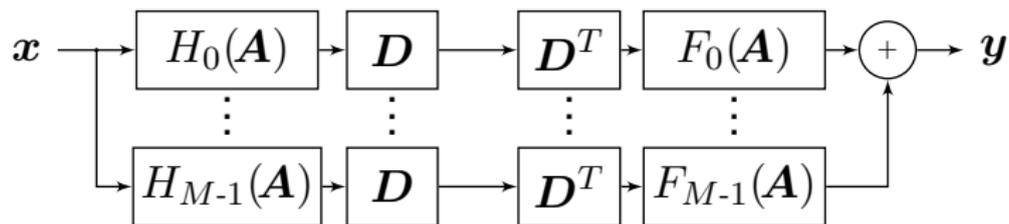
M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{x}}_k =]{\mathbf{H}_k} \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{y}}_k =]{\mathbf{D}^T \mathbf{D}} \frac{1}{M} \begin{bmatrix} \hat{x}_{1,k} \\ \hat{x}_{1,k} \\ \vdots \\ \hat{x}_{1,k} \\ \hat{x}_{2,k} \\ \hat{x}_{2,k} \\ \vdots \\ \hat{x}_{2,k} \\ \hat{x}_{3,k} \\ \hat{x}_{3,k} \\ \vdots \\ \hat{x}_{3,k} \\ \vdots \end{bmatrix}$$

M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix} \xrightarrow{\mathbf{H}_k} \hat{\mathbf{x}}_k = \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \xrightarrow{\mathbf{D}^T \mathbf{D}} \frac{1}{M} \begin{bmatrix} \hat{x}_{1,k} \\ \hat{x}_{1,k} \\ \vdots \\ \hat{x}_{1,k} \\ \hat{x}_{2,k} \\ \hat{x}_{2,k} \\ \vdots \\ \hat{x}_{2,k} \\ \hat{x}_{3,k} \\ \hat{x}_{3,k} \\ \vdots \\ \hat{x}_{3,k} \\ \vdots \end{bmatrix} \xrightarrow{\mathbf{F}_k} \hat{\mathbf{z}}_k = \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix}$$

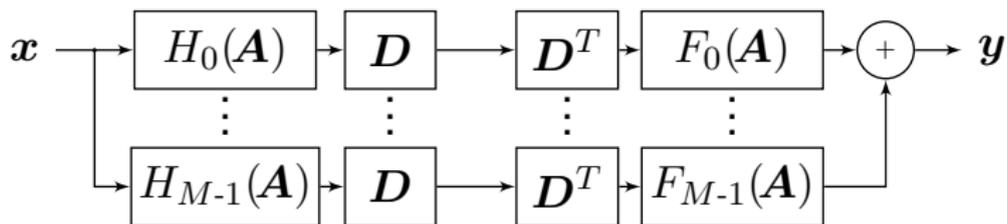
M -Channel FB on M -Block Cyclic Graphs (Details)



5

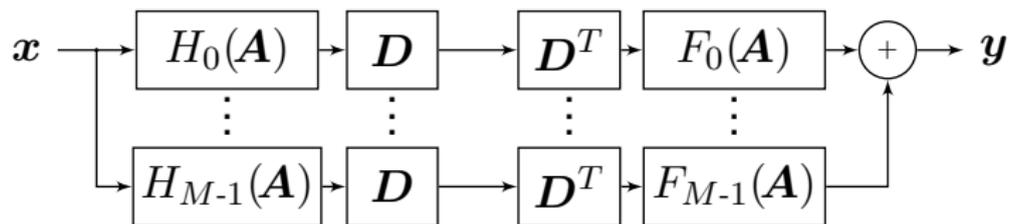
6

M -Channel FB on M -Block Cyclic Graphs (Details)



$$\mathbf{F}_k = M \mathbf{H}_k$$

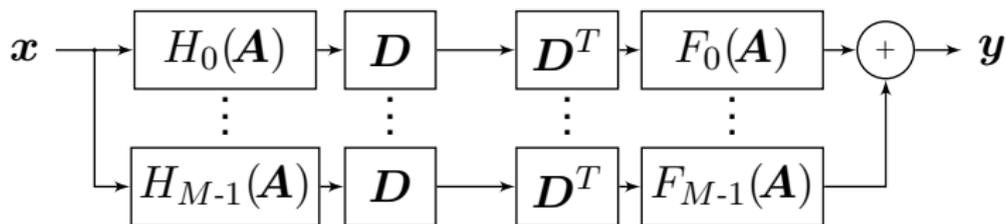
M -Channel FB on M -Block Cyclic Graphs (Details)



$$F_k = M H_k$$

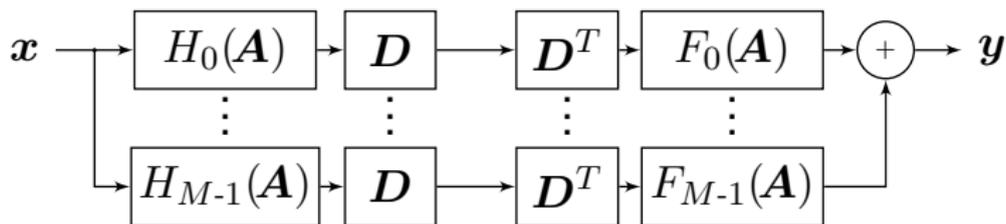
$$H_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1}$$

M -Channel FB on M -Block Cyclic Graphs (Details)



$$\mathbf{F}_k = M \mathbf{H}_k$$

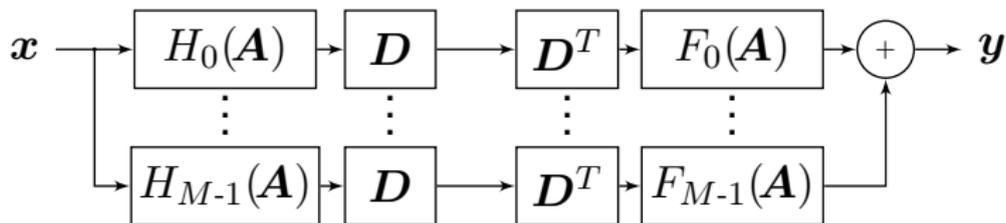
$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1} \quad H_k(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi k}{M} \leq \omega \leq \frac{2\pi(k+1)}{M}, \\ 0, & \text{otherwise,} \end{cases}$$

M -Channel FB on M -Block Cyclic Graphs (Details)

$$\mathbf{F}_k = M \mathbf{H}_k$$

$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1} \quad H_k(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi k}{M} \leq \omega \leq \frac{2\pi(k+1)}{M}, \\ 0, & \text{otherwise,} \end{cases}$$

$$\mathbf{H}_k \stackrel{?}{=} H_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + \dots + h_k(L) \mathbf{A}^L$$

M -Channel FB on M -Block Cyclic Graphs (Details)

$$\mathbf{F}_k = M \mathbf{H}_k$$

$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1} \quad H_k(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi k}{M} \leq \omega \leq \frac{2\pi(k+1)}{M}, \\ 0, & \text{otherwise,} \end{cases}$$

$$\mathbf{H}_k \stackrel{?}{=} H_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + \dots + h_k(L) \mathbf{A}^L$$

\mathbf{A} needs to have **distinct eigenvalues**.^{5 6}

⁵O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

⁶A. Sandryhaila and J. M. F. Moura. "Discrete Signal Processing on Graphs". *IEEE Trans. Signal Process.* 61.7 (2013)

Is M -Block Cyclic Property Necessary?

$$M\text{-Block Cyclic}^7 \Leftrightarrow \begin{cases} \text{Eigenvector Property : } \mathbf{v}_{i,j+k} = \mathbf{\Omega}^k \mathbf{v}_{i,j} \\ \text{Eigenvalue Property : } \lambda_{i,j+k} = w^k \lambda_{i,j} \end{cases}$$

⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Is M -Block Cyclic Property Necessary?

$$M\text{-Block Cyclic}^7 \Leftrightarrow \begin{cases} \text{Eigenvector Property : } \mathbf{v}_{i,j+k} = \mathbf{\Omega}^k \mathbf{v}_{i,j} \\ \text{Eigenvalue Property : } \lambda_{i,j+k} = w^k \lambda_{i,j} \end{cases}$$

⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Is M -Block Cyclic Property Necessary?

$$M\text{-Block Cyclic}^7 \Leftrightarrow \begin{cases} \text{Eigenvector Property : } \mathbf{v}_{i,j+k} = \mathbf{\Omega}^k \mathbf{v}_{i,j} \\ \text{Eigenvalue Property : } \lambda_{i,j+k} = w^k \lambda_{i,j} \end{cases}$$

For any polynomial $H(\mathbf{A})$

$$H(\mathbf{Q}\mathbf{A}\mathbf{Q}^{-1}) = \mathbf{Q} H(\mathbf{A}) \mathbf{Q}^{-1} \text{ for any invertible } \mathbf{Q}$$

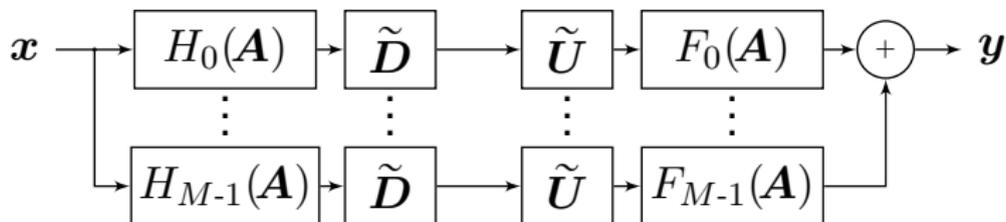
⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Is M -Block Cyclic Property Necessary?

$$M\text{-Block Cyclic}^7 \Leftrightarrow \begin{cases} \text{Eigenvector Property : } \mathbf{v}_{i,j+k} = \boldsymbol{\Omega}^k \mathbf{v}_{i,j} \\ \text{Eigenvalue Property : } \lambda_{i,j+k} = w^k \lambda_{i,j} \end{cases}$$

For any polynomial $H(\mathbf{A})$

$$H(\mathbf{Q}\mathbf{A}\mathbf{Q}^{-1}) = \mathbf{Q}H(\mathbf{A})\mathbf{Q}^{-1} \text{ for any invertible } \mathbf{Q}$$



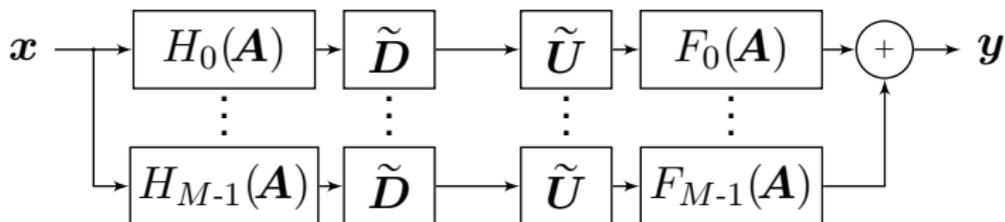
⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Is M -Block Cyclic Property Necessary?

$$M\text{-Block Cyclic}^7 \Leftrightarrow \begin{cases} \text{Eigenvector Property : } \mathbf{v}_{i,j+k} = \boldsymbol{\Omega}^k \mathbf{v}_{i,j} \\ \text{Eigenvalue Property : } \lambda_{i,j+k} = w^k \lambda_{i,j} \end{cases}$$

For any polynomial $H(\mathbf{A})$

$$H(\mathbf{Q}\mathbf{A}\mathbf{Q}^{-1}) = \mathbf{Q}H(\mathbf{A})\mathbf{Q}^{-1} \text{ for any invertible } \mathbf{Q}$$



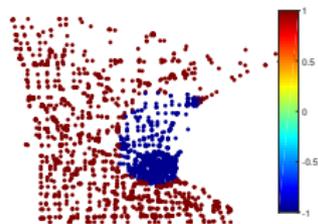
$\tilde{\mathbf{D}}$ and $\tilde{\mathbf{U}}$ have higher complexity, but **no restrictive assumptions** on \mathbf{A} .

⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Outline

- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks
 - Extending Classical Tools to Graph Case
- 3 Multirate Processing of Graph Signals
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 **Some Examples**

Examples

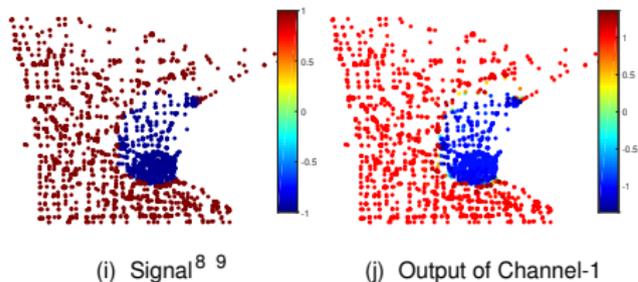


(a) Signal^{8 9}

⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

⁹D. K. Hammond, P. Vandergheynst, and R. Gribonval. The spectral graph wavelets toolbox. [Online]. <http://wiki.epfl.ch/sgwt>

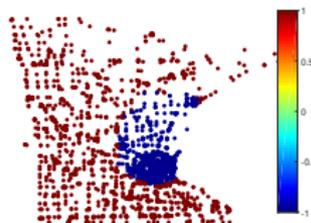
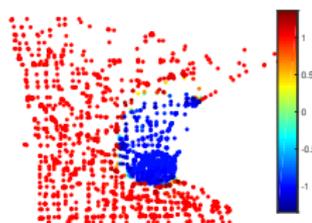
Examples



⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

⁹D. K. Hammond, P. Vandergheynst, and R. Gribonval. The spectral graph wavelets toolbox. [Online]. <http://wiki.epfl.ch/sgwt>

Examples

(q) Signal^{8 9}

(r) Output of Channel-1



(s) Output of Channel-2

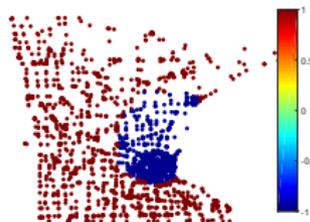
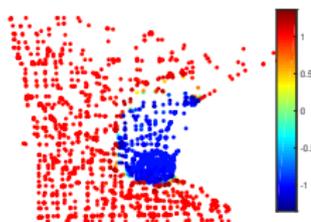


(t) Output of Channel-3

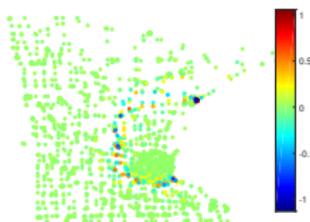
⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

⁹D. K. Hammond, P. Vandergheynst, and R. Gribonval. The spectral graph wavelets toolbox. [Online]. <http://wiki.epfl.ch/sgwt>

Examples

(y) Signal^{8 9}

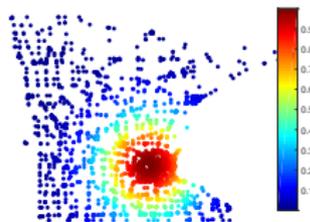
(z) Output of Channel-1



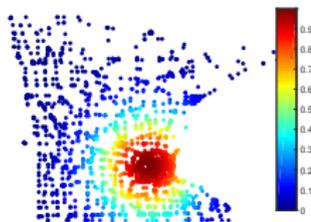
(j) Output of Channel-2



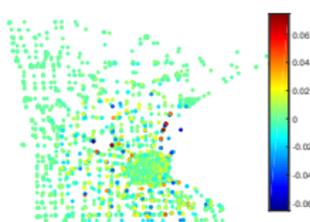
(l) Output of Channel-3



(i) Signal



(j) Output of Channel-1



(k) Output of Channel-2



(l) Output of Channel-3

⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

⁹D. K. Hammond, P. Vandergheynst, and R. Gribonval. The spectral graph wavelets toolbox. [Online]. <http://wiki.epfl.ch/sgwt>

Conclusions

- Brute-Force Filter Banks
- Decimator
- M -Block Cyclic Graph
 - Unique Eigenvalue-Eigenvector Structure
- Spectrum Folding
 - Decimation-then-Expansion
 - Bandlimited Signals
 - Interpolation
- M -Channel Filter Banks
- Further Directions
 - How does this compare with alternative ways?
 - From ideal to non-ideal?

Conclusions

- Brute-Force Filter Banks
- Decimator
- M -Block Cyclic Graph
 - Unique Eigenvalue-Eigenvector Structure
- Spectrum Folding
 - Decimation-then-Expansion
 - Bandlimited Signals
 - Interpolation
- M -Channel Filter Banks
- Further Directions
 - How does this compare with alternative ways?
 - From ideal to non-ideal?

Any questions?

Please email me: oteke@caltech.edu