Decoder-side Affine Model Refinement for Video Coding beyond VVC



Jie Chen, Ru-ling Liao, Yan Ye and Xinwei Li March 24 , 2023



Background

- Versatile Video Coding (VVC) was finalized on July 2020
 - Developed by Joint Video Experts Team (JVET)
 - Achieves about half bit-rate reduction compared with its predecessor high efficiency video coding (HEVC) [2]
- New video coding technology exploration beyond VVC was launched by JVET on 2021
 - The exploration platform, Enhanced Compression Model (ECM)-1.0, was released in April 2021
 - By December 2022, ECM-7.0 achieves 19.2% luma BD rate savings over VTM-11.0
 - Quite a lot of technology improvement and new coding tools were adopted in ECM
- It is proposed to refine the affine model for affine motion compensation blocks on top of ECM software in this paper





Affine Motion Model (1/2)

- The affine motion can be described by a affine motion model with 6 or 4 parameters
 - > 6 parameter affine model
 - > 4 parameter affine model
- The 6-parameter affine model is a generalized linear mapping which can preserve lines and parallelism.

$$\begin{cases} mv_x = a(x - x_0) + c(y - y_0) + mv_{0x} \\ mv_y = b(x - x_0) + d(y - y_0) + mv_{0y} \end{cases}$$
(1)

• The 4-parameter affine model is a subset of 6-parameter affine model but still can support translation, rotation and zooming.

$$\begin{cases} mv_x = a(x - x_0) - b(y - y_0) + mv_{0x} \\ mv_y = b(x - x_0) + a(y - y_0) + mv_{0y} \end{cases}$$
(2)

 (mv_x, mv_y) : MV at any coordinate (x, y) in the plane (mv_{0x}, mv_{0y}) : base MV controlling the translation movement of the model a, b, c and d: non-translation parameters defining rotation, zooming, shearing and other more complex motion





Affine Motion Model (2/2)

- The affine motion model can be determined by the control point motion vectors (CPMVs)
 - > CPMVs of a affine coded blocks are stored in VVC and ECM
 - > 3 CPMVs for 6 parameter affine model

$$\begin{cases} a = \frac{mv_{1x} - mv_{0x}}{x_1 - x_0} \\ b = \frac{mv_{1y} - mv_{0y}}{x_1 - x_0} \\ c = \frac{mv_{2x} - mv_{0x}}{y_2 - y_0} \\ d = \frac{mv_{2y} - mv_{0y}}{y_2 - y_0} \end{cases}$$

> 2 CPMVs for 4 parameter affine model

$$\begin{cases} a = \frac{mv_{1x} - mv_{0x}}{x_1 - x_0} \\ b = \frac{mv_{1y} - mv_{0y}}{x_1 - x_0} \end{cases}$$

 $(mv_{0x}, mv_{0y}), (mv_{1x}, mv_{1y})$ and (mv_{2x}, mv_{2y}) : CPMVs which are MVs at top-left, top-right and bottom-left corner of CU $(x_0, y_0), (x_1, y_1)$ and (x_2, y_2) : coordinates of top-left, top-right and bottom-left corner of CU

E Alibaba

(3)

(4)



Affine motion compensation (AMC)

- Two affine motion compensation modes, affine inter mode and affine merge mode, are supported in VVC and ECM
 - **CPMV** predictors.
 - \succ derived from a affine merge list. The index to the affine merge list is signaled.
- Subblock level motion compensation is performed for AMC instead of pixel level
 - Subblock MVs are derived based on the CPMVs
 - Subblock motion compensation is performed with subblock MV \bullet



Affine inter mode: an inter mode requiring CPMV differences signaled (2 differences for 4-parameter affine) model and 3 differences for 6-parameter affine model). CPMVs are derived by adding CPMV differences to

Affine merge mode: a merge mode where motion info is derived by the neighboring bocks. The CPMVs are





Decoder-side Motion Vector Refinement (DMVR)

- vector accuracy without additional signaling
 - Applied on merge mode and based on a search scheme in both decoder and encoder
 - Applied on bi-prediction block as it is based on bilateral matching (BM) cost (e.g., the SAD/SATD between two predictors)
 - initial MVs: the MV pair derived in merge mode
 - refined MVs: The MV pair with the minimum BM cost in the search window around initial MVs



• DMVR was adopted in VVC and further extended in ECM which aims at increasing the motion



The method proposed

- In VVC and ECM-5.0, DMVR can only be applied on translation motion compensated blocks
- For affine merge mode, the affine motion is inherited or derived from the previously coded blocks and may not well match with the current block
- It is proposed to refine the affine motion model in decoder side for AMC blocks to improve the affine model accuracy
 - Similar with conventional DMVR \succ
 - Applied on affine merge and based on a search scheme both in encoder and decoder \checkmark
 - Applied on bi-predicted block with one reference forward and on reference backward \checkmark
 - No additional signaling always on if condition satisfied. \checkmark
 - It consists of two steps
 - Base MV refinement
 - Non-translation parameter refinement \checkmark







Base MV refinement

- - The MV offset for base MV is searched to minimize the BM cost
 - The MV offset search process also obey the symmetrical rule \succ

 $mv'_{0x\ L0} = mv_{0x\ L0} + mv_{offsetx}$ $mv'_{0y_L0} = mv_{0y_L0} + mv_{offsety}$ $mv'_{0x_L1} = mv_{0x_L1} - mv_{offsetx}$ $\left(mv_{0y_L1}' = mv_{0y_L1} - mv_{offsety}\right)$

 $(mv_{0x_{L0}}, mv_{0y_{L0}}), (mv_{0x_{L1}}, mv_{0y_{L1}})$: initial base MV pair $(mv'_{0x_L0}, mv'_{0y_L0})$, $(mv'_{0x_L1}, mv'_{0y_L1})$: refined base MV pair $(mv_{offsetx}, mv_{offsety})$: the MV offset obtained in the search process

- A search process followed by a parametric error surface based fractional MV estimation \succ
 - Integer search followed by half pixel search \checkmark
 - 3x3 square search pattern is used \checkmark



Only base MV of the affine model is refined and the non-translation parameters are unchanged

(5)



 $\bigcirc \bigcirc \bigcirc \bigcirc$

()

 \bigcirc

• the search center

O the neighboring search position



Non-translation parameter refinement

- The refined base MV is kept unchanged and non-translation parameters are refined
 - The parameter offsets are searched to minimize the BM cost \succ
 - The parameter offset search process also obey the symmetrical rule \succ

$$\begin{cases} a'_{L0} = a_{L0} + a_{offset} \\ a'_{L1} = a_{L1} - a_{offset} \\ b'_{L0} = b_{L0} + b_{offset} \\ b'_{L1} = b_{L1} - b_{offset} \\ c'_{L0} = c_{L0} + c_{offset} \\ c'_{L1} = c_{L1} - c_{offset} \\ d'_{L0} = d_{L0} + d_{offset} \\ d'_{L1} = d_{L1} - d_{offset} \end{cases}$$
(6)

- Different search patterns for different affine motion models \succ
 - Square search pattern is used for 6-parameter affine motion model \checkmark
 - d_0), $(a_0, b_0, c_0, d_0 + s)$
 - Cross search pattern is used for 4-paraterm affine motion model \checkmark

•
$$(a_0, b_0) \rightarrow (a_0 - s, b_0 - s), (a_0 - s, b_0), (a_0 - s, b_0 + s), (a_0 - s, b_0$$

Decoder-side Affine Model Refinement for Video Coding Beyond VVC - J. Chen et. al. DCC 2023

E Alibaba

 $_{0}/a_{L1}, b_{L0}/b_{L1}, c_{L0}/c_{L1}$ and d_{L0}/d_{L1} : initial non-translation parameters a'_{L1} , b'_{L0}/b'_{L1} , c'_{L0}/c'_{L1} and d'_{L0}/d'_{L1} : refined non-translation parameters ffset, b_{offset} , c_{offset} and d_{offset} : parameter offsets obtained in the search process

• $(a_0, b_0, c_0, d_0) \rightarrow (a_0 - s, b_0, c_0, d_0), (a_0, b_0 - s, c_0, d_0), (a_0, b_0, c_0 - s, d_0), (a_0, b_0, c_0, d_0 - s), (a_0 + s, b_0, c_0, d_0), (a_0, b_0 + s, c_0, d_0), (a_0, b_0, c_0 + s, c_0, d_0), (a_0, b_0, c_0,$

 $(a_0, b_0 + s), (a_0 + s, b_0 + s), (a_0 + s, b_0), (a_0 + s, b_0 - s), (a_0, b_0 - s)$



Non-translation parameter refinement

- Iteration process is introduced for non-translation parameter refinement
 - > Iteration 1: the top-left CPMV is fixed as base MV, two other CPMVs are refined
 - > Iteration 2: the refined top-right CPMV is fixed as base MV, two other CPMV are further refined
 - > Iteration 3: the refined bottom-left CPMV is fixed as base MV, two other CPMVs are further refined







Experimental Results

 To show the effectiveness of the proposed n with affine merge mode is collected

Table 1: The comparison of the area percentage of the blocks coded with affine merge mode

Sequence	ECM-6.0 anchor	Base MV refinement	Both base MV and non-translation	
Tango2	5.22%	8.99%	12.97%	
FoodMarket4	13.38%	18.08%	20.86%	
Campfire	2.76%	3.09%	3.38%	
CatRobot1	5.89%	8.28%	10.51%	
DaylightRoad2	10.42%	15.50%	19.39%	
ParkRunning3	20.00%	25.75%	27.73%	
MarketPlace	10.83%	14.63%	16.99%	
RitualDance	8.19%	10.56%	12.25%	
Cactus	5.49%	6.51%	7.27%	
BasketballDrive	5.70%	7.09%	8.14%	
BQTerrace	3.51%	3.53%	3.64%	
BasketballDrill	2.35%	2.72%	3.60%	
BQMall	1.87%	2.39%	2.92%	
PartyScene	6.80%	7.70%	7.73%	
RaceHorses	4.17%	5.93%	8.19%	
Average	7.11%	9.38%	11.04%	

Decoder-side Affine Model Refinement for Video Coding Beyond VVC - J. Chen et. al. DCC 2023



• To show the effectiveness of the proposed method, the percentage of area of the blocks coded



Experimental Results

• BD-rate reduction of the proposed method on top of ECM-6.0

Class	Sequence	Base MV refinement			Both base MV and non-translation parameter refinement		
		Y	U	V	Y	U	V
	Tango2	-0.23%	-0.13%	-0.21%	-0.64%	-0.55%	-0.49%
A1	FoodMarket4	-0.33%	-0.40%	-0.32%	-0.49%	-0.47%	-0.24%
	Campfire	-0.02%	-0.01%	0.03%	-0.04%	-0.03%	-0.03%
	CatRobot1	-0.26%	-0.09%	-0.18%	-0.47%	-0.36%	-0.44%
A2	DaylightRoad2	-0.48%	-0.41%	-0.29%	-0.86%	-0.53%	-0.57%
	ParkRunning3	-0.15%	-0.07%	-0.09%	-0.19%	-0.11%	-0.08%
	MarketPlace	-0.23%	-0.12%	-0.20%	-0.41%	-0.27%	-0.40%
	RitualDance	-0.10%	0.12%	-0.16%	-0.21%	0.13%	-0.20%
В	Cactus	-0.15%	0.00%	-0.06%	-0.20%	-0.20%	-0.08%
	BasketballDrive	-0.06%	0.09%	-0.07%	-0.17%	-0.04%	-0.13%
	BQTerrace	-0.02%	0.18%	0.11%	-0.01%	0.23%	-0.08%
	BasketballDrill	-0.05%	0.05%	-0.20%	-0.10%	0.03%	-0.18%
C	BQMall	-0.05%	0.02%	-0.01%	-0.10%	0.13%	-0.02%
L	PartyScene	-0.03%	-0.01%	0.20%	-0.03%	-0.05%	0.28%
	RaceHorses	-0.01%	-0.12%	-0.25%	-0.09%	-0.24%	-0.14%
	Class A1	-0.20%	-0.18%	-0.17%	-0.39%	-0.35%	-0.25%
Dan Class	Class A2	-0.30%	-0.19%	-0.19%	-0.50%	-0.33%	-0.36%
Per-Class	Class B	-0.11%	0.06%	-0.08%	-0.20%	-0.03%	-0.18%
	Class C	-0.04%	-0.01%	-0.06%	-0.08%	-0.03%	-0.01%
	Overall		-0.06%	-0.11%	-0.27%	-0.15%	-0.19%
	EncT		102%			113%	
	DecT		102%			113%	

Decoder-side Affine Model Refinement for Video Coding Beyond VVC - J. Chen et. al. DCC 2023



Table 2: Simulation results of the proposed method (Random Access)



Experimental Results

- Further work has been done to reduce the complexity of the non-translation parameter refinement
 - Anchor: ECM-7.0 (with base MV refinement)
 - Test: non-translation parameter refinement



Class	Sequence	Non-translation parameter refinement			
Clubb	Jequence .	Y	U	V	
A1	Tango2	-0.23%	0.00%	0.05%	
	FoodMarket4	-0.20%	-0.27%	-0.27%	
	Campfire	-0.02%	-0.01%	0.09%	
	CatRobot1	-0.20%	-0.02%	-0.03%	
A2	DaylightRoad2	-0.22%	-0.24%	-0.40%	
	ParkRunning3	-0.05%	0.01%	-0.07%	
	MarketPlace	-0.04%	0.14%	0.01%	
	RitualDance	-0.03%	-0.07%	-0.14%	
В	Cactus	-0.16%	-0.16%	-0.06%	
	BasketballDrive	-0.07%	-0.06%	-0.19%	
	BQTerrace	-0.05%	-0.11%	-0.19%	
С	BasketballDrill	-0.04%	-0.12%	0.04%	
	BQMall	-0.03%	0.17%	0.08%	
	PartyScene	0.05%	-0.13%	0.00%	
	RaceHorses	-0.13%	-0.05%	-0.29%	
Per-Class	Class A1	-0.15%	-0.09%	-0.04%	
	Class A2	-0.16%	-0.08%	-0.17%	
	Class B	-0.07%	-0.05%	-0.11%	
	Class C	-0.04%	-0.03%	-0.04%	
Overall		-0.10%	-0.06%	-0.09%	
	EncT		103%		
	DecT		103%		

Table 3: Simulation results on ECM-7.0



Summary

- model accuracy
- Two steps are in the proposed method
 - Base MV refinement
 - Non-translation parameter refinement \triangleright
- The experimental results show the BD-rate reduction on top of ECM ullet

 - \triangleright
 - refinement is applied
 - More coding gain on 4K sequences \succ



• It is proposed to refine affine motion model for affine merge coded blocks to increase the

{0.15% (Y), 0.06% (U), 0.11% (V), 102% (ENC), 102% (DEC)} on ECM-6.0, if only base MV refinement is applied

{0.27% (Y), 0.15% (U), 0.19% (V), 113% (ENC), 113% (DEC)} on ECM-6.0 if both two steps are applied

{0.10% (Y), 0.06% (U), 0.09% (V), 103%(ENC), 103%(DEC)} on ECM-7.0 when non-transaltion paramter



Reference

- Systems for Video Technology, vol. 31, issue 10, pp 3736-3764, Aug. 2021.
- 22, no. 12, pp. 1649-1668, Dec. 2012.
- 3. ECM-1.0, https://vcgit.hhi.fraunhofer.de/ecm/ECM/-/tree/ECM-1.0
- 4. VTM software, https://vcgit.hhi.fraunhofer.de/jvet/VVCSoftware_VTM
- 5. ECM-6.0, https://vcgit.hhi.fraunhofer.de/ecm/ECM/-/tree/ECM-6.0
- 6. S. Esenlik and Y.-W. Chen, "CE9: Summary report on decoder side MV derivation," JVET-K0029, Ljubljana, SI, Jul. 2018.
- 7. S. Esenlik, Y.-W. Chen, and F. Chen, "CE9: Summary report on decoder side motion vector derivation," JVET-L0029, Macao, CN, Oct. 2018.
- 8. X. Xiu and S. Esenlik, "CE9: Summary report on decoder side motion vector derivation", JVET-M0029, Marrakech, MA, Jan. 2019.
- 9. H. Gao, X. Chen, S. Esenlik, J. Chen and E. Steinbach, "Decoder-side motion vector refinement in VVC: algorithm and hardware implementation considerations," IEEE Transactions on Circuits and Systems for Video Technology, vol. 31, no. 8, pp. 3197-3211, Aug. 2021.
- 10. M. Coban, F. Le Léannec, K. Naser, J. Ström, "Algorithm description of enhanced compression model 6 (ECM 6)," JVET-AA2025, Jul. 2022.
- 11. H. Huang, J. Woods, Y. Zhao, and H. Bai, "Control-point representation and differential coding affine-motion compensation," IEEE Transactions on Circuits and Systems for Video *Technology*, vol. 23, no. 10, pp.1651–1660, Oct. 2013.
- 27, no. 11, pp. 2437-2449, Nov. 2017.
- *Video Technology*, vol. 28, no. 8, pp. 1934-1948, Apr. 2017.
- 28, no. 3, pp. 1456-1469, Mar. 2019.
- coding standard," IEEE Transactions on Circuits and Systems for Video Technology, vol. 31, no. 10, pp. 3862-3877, Oct. 2021.
- 16. M. Karczewice, Y. Yan, "Common test conditions and evaluation procedures for enhanced compression tool testing," JVET-Y2017, teleconference, Jan. 2022.
- 17. G. Bjøntegaard, "Calculation of average PSNR differences between RD-curves," ITU-T SG16 Q.6 Document, VCEG-M33, Austin, US, Apr. 2001.

EAlibaba

1. B. Bross, Y.-K. Wang, Y. Ye, S. Liu, J. Chen, G. J. Sullivan, J. R. Ohm, "Overview of the versatile video coding (VVC) standard and its applications," IEEE Transactions on Circuits and

2. G. J. Sullivan, J. Ohm, W. Han, T. Wiegand, "Overview of the high efficiency video coding (HEVC) standard," IEEE Transactions on Circuits and Systems for Video Technology, vol.

12. N. Zhang, X. Fan, D. Zhao, and W. Gao, "Merge mode for deformable block motion information derivation," IEEE Transactions on Circuits and Systems for Video Technology, vol.

13. L. Li, H. Li, D. Liu, Z. Li, H. Yang, S. Lin, H. Chen, and F. Wu, "An efficient four-parameter affine motion model for video coding," IEEE Transactions on Circuits and Systems for

14. K. Zhang, Y. Chen, L. Zhang, W. Chien and M. Karczewicz, "An improved framework of affine motion compensation in video coding," IEEE Transactions on Image Processing, vol.

15. H. Yang, H. Chen, J. Chen, S. Esenlik, S. Sethuranman, X. Xiu, E. Alshina and J. Luo, "Subblock-based motion derivation and inter prediction refinement in the versatile video



Thank you



