

A Statistical Interpretation of the Maximum Subarray Problem

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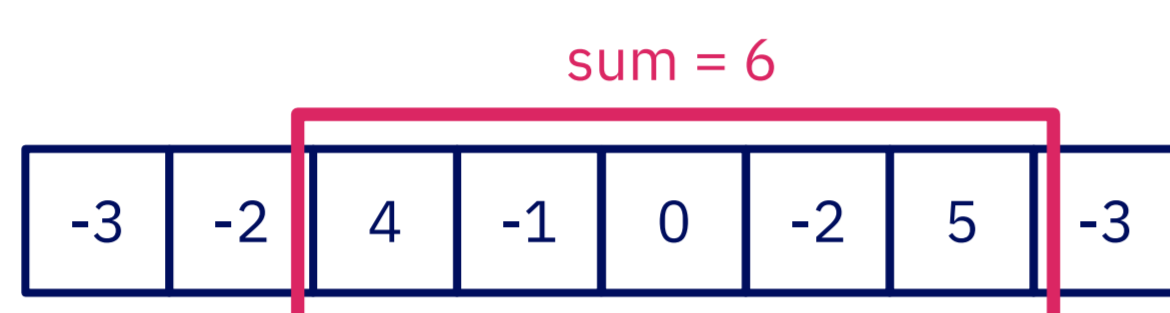
Dmitry Malioutov Millenium Management



We study a noisy localization problem inspired by the classical maximum subarray problem. While the naïve solution fails completely, penalized and constrained versions can succeed and are theoretically justified.

Maximum Subarray Problem

Given an array of numbers, find contiguous **subarray with largest sum**



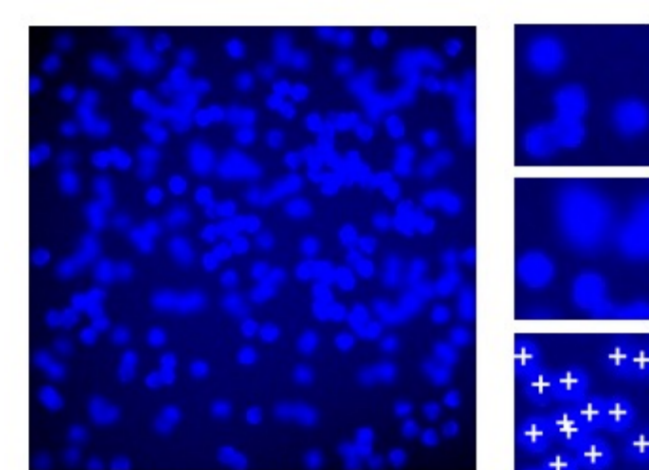
Efficient $O(N)$ algorithm by Kadane [1]

Some generalizations also have $O(N)$ algorithms [2]

Applications:

- Biomolecular sequence analysis [2,3]
- Image processing, computer vision (2-D) [4]

Species	MDR	consensus	GC region
rat mdr1b	-59	GCG GGG CAA	GGG GGC GGC GGC GGC GGC -36
mouse mdr1b	-55	GCC GGG CCA	TAG GGC GGC GGC GGC GGC -32
hamster pgp2	-17	ACG GGG CCG	GCG GGC GGC GGC GGC GGC -28
hamster pgp1	-51	GAG TCA AGC	TGG GTC GGC GGC GGC GGC -28
mouse mdr1a	-123	GAG TCA AGC	TGG GGC GGC GGC GGC GGC -100
human MDR1	-120	CAG TCA ATC	GCG GGC GGC GGC GGC GGC -97
human MDR1	-64	ACA GCG CCC	GCG GGC GGC GGC GGC GGC -41

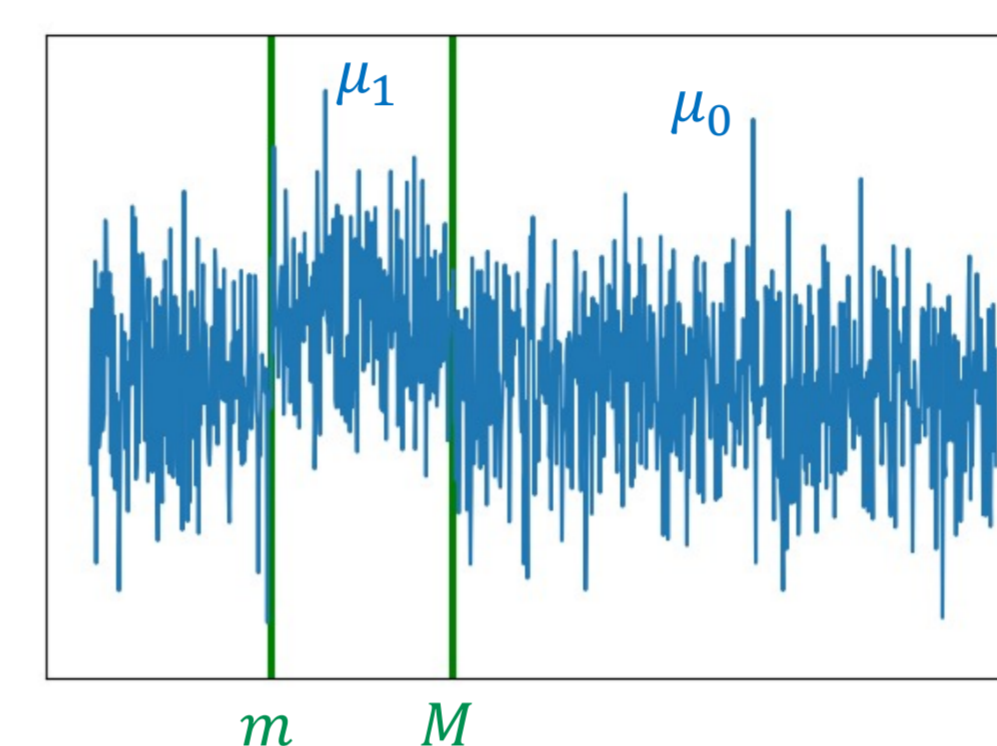


A Statistical Localization Problem

Sequence of random variables w_1, \dots, w_N

Interval w_m, \dots, w_M has mean μ_1 different from background mean μ_0

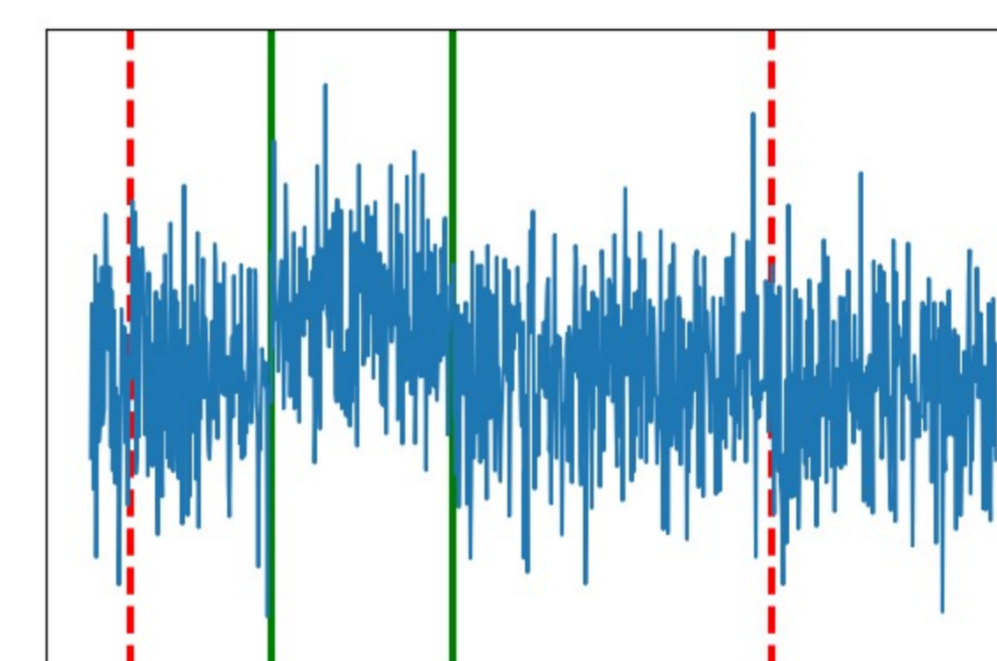
Estimate m, M from one observation of w_1, \dots, w_N



Naïve Maximum Subarray Fails Completely

Naïve maximum subarray:

$$\hat{m}, \hat{M} = \arg \max_{m, M} \sum_{t=m}^M w_t$$



Penalized and Constrained Versions Succeed

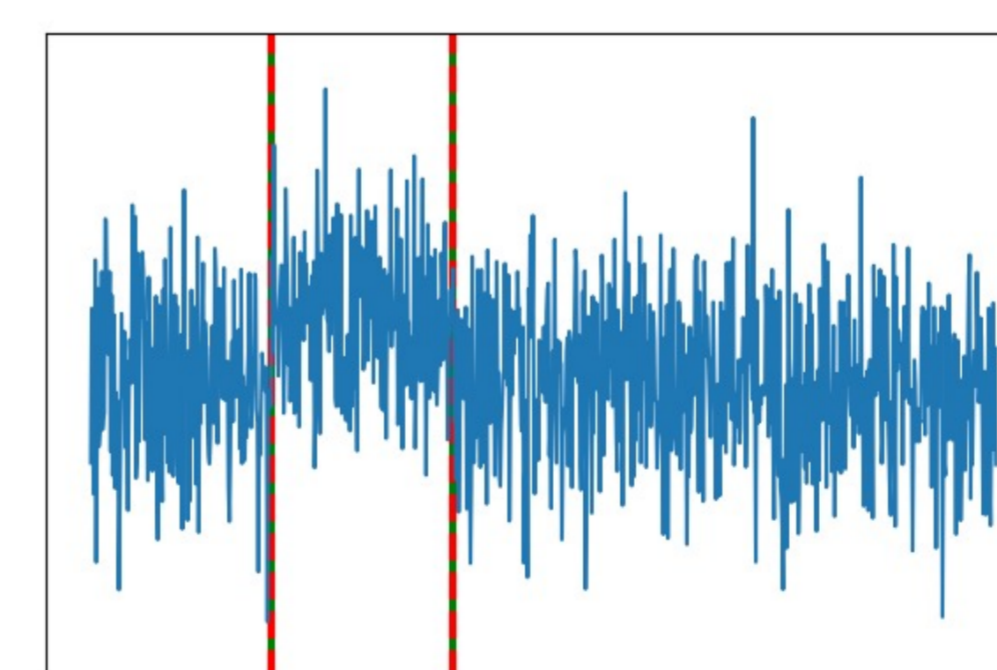
1) Penalized:

$$\hat{m}, \hat{M} = \arg \max_{m, M} \sum_{t=m}^M (w_t - \delta)$$

2) Constrained:

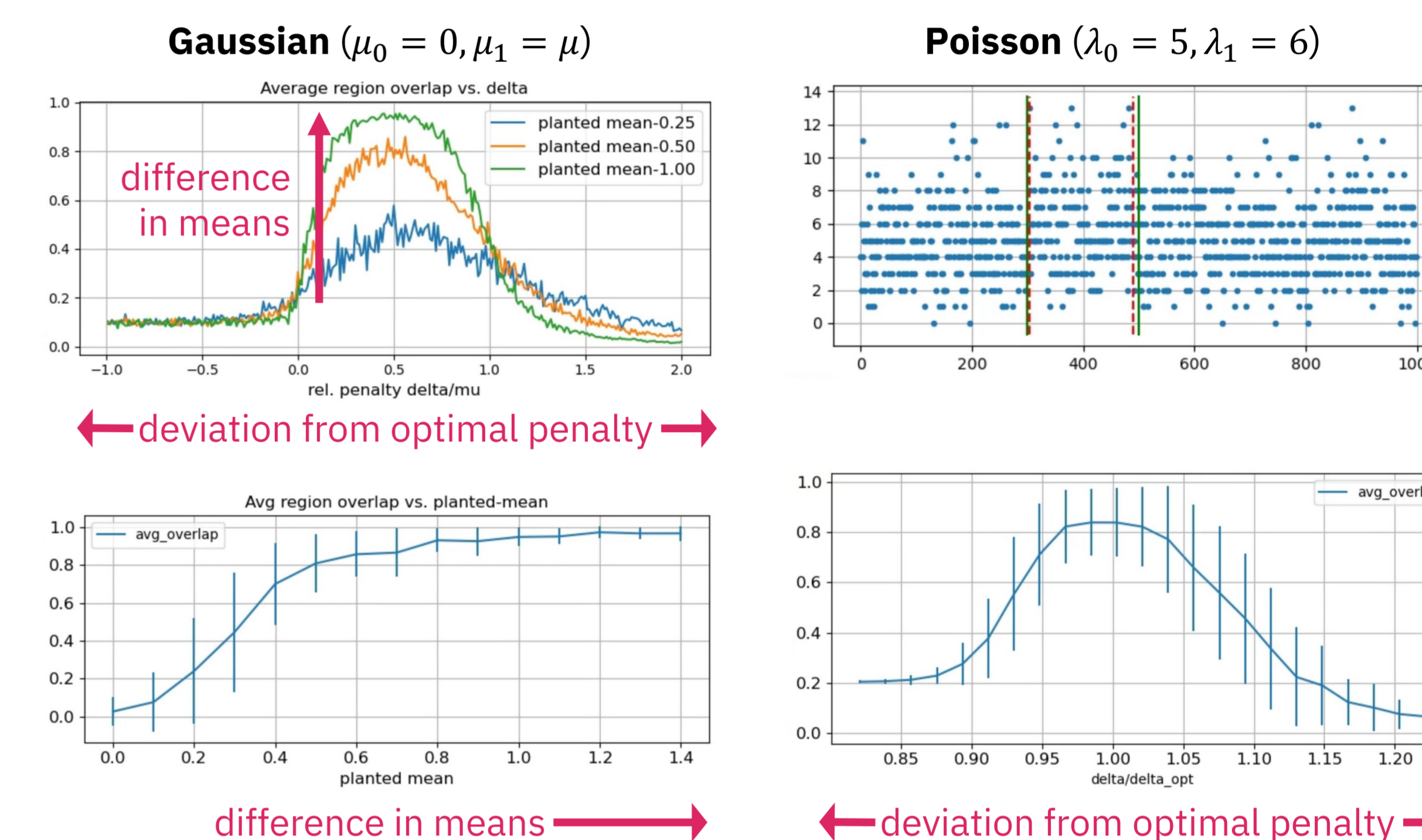
$$\hat{m}, \hat{M} = \arg \max_{m, M} \sum_{t=m}^M w_t \text{ s.t. } M - m + 1 \leq K$$

1) is the Lagrangean of 2)

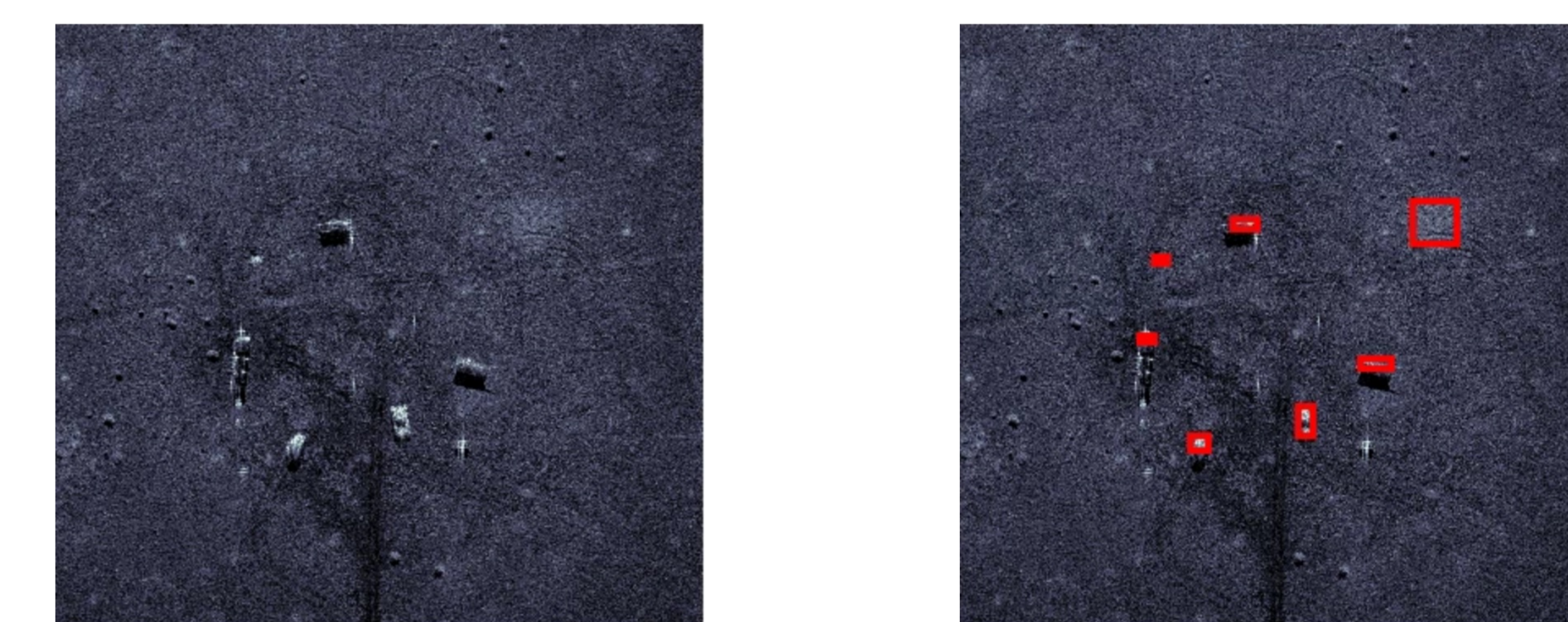


Numerical Simulations

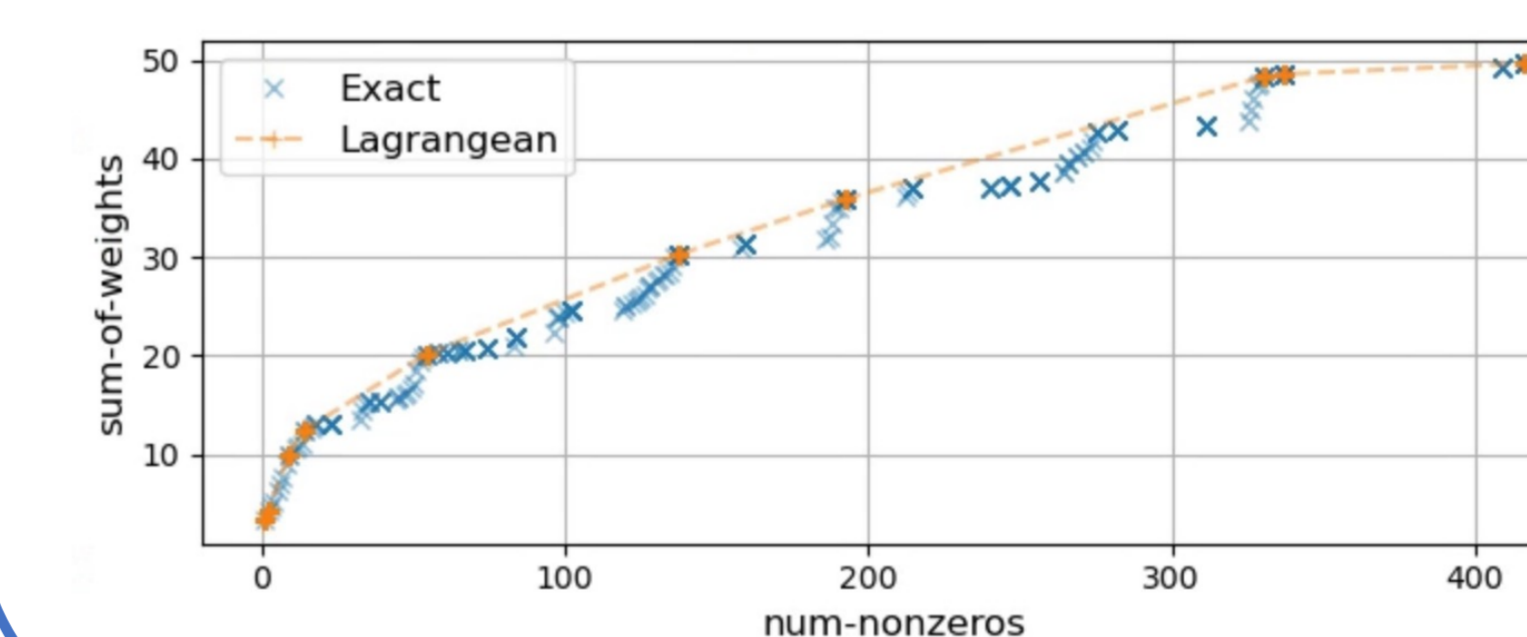
Recovery of Planted Intervals



2-D Example: SAR Vehicle Localization



Penalized vs. Constrained Formulations



Penalized solutions appear to lie on convex hull of constrained solutions

Penalized Maximum Subarray from Exponential Families

Assume w_1, \dots, w_N i.i.d. \sim exponential family

$$f(w_t) = h(w_t) \exp(\eta w_t + \eta^T T(w_t) - A(\eta, \eta'))$$

natural parameter interval: $\eta = \eta_1$
background: $\eta = \eta_0$

w_t itself is one of the sufficient statistics

other sufficient statistics

log-partition function

Then maximum likelihood estimate of m, M reduces to **penalized max subarray with optimal penalty**

$$\delta = \frac{A(\eta_1, \eta') - A(\eta_0, \eta')}{\eta_1 - \eta_0}$$

Proposition: Penalty falls between interval mean and background mean

$$\mu_0 \leq \delta \leq \mu_1$$

Example: **Gaussian**

$$\delta = \frac{\mu_0 + \mu_1}{2}$$

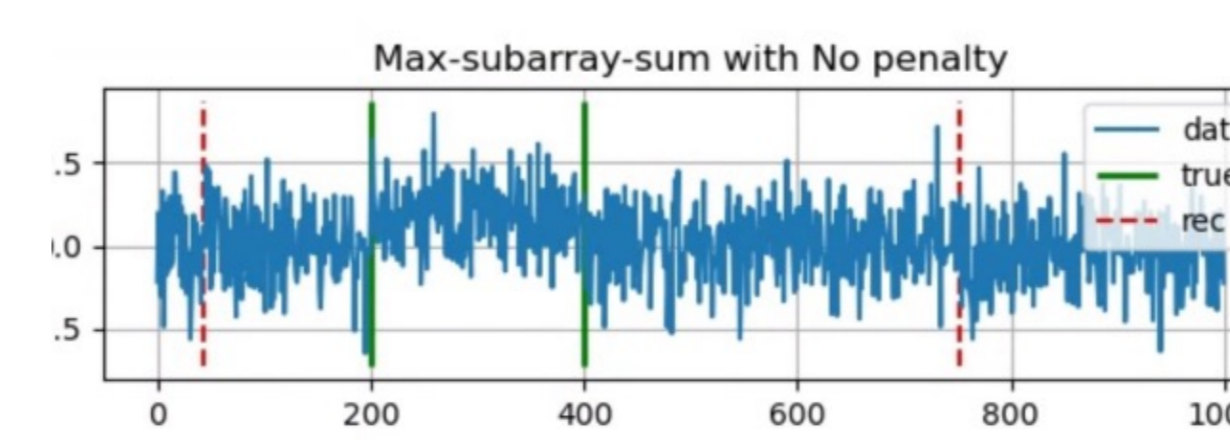
Example: **Poisson** with rates λ_0, λ_1

$$\delta = \frac{\lambda_1 - \lambda_0}{\log \lambda_1 - \log \lambda_0}$$

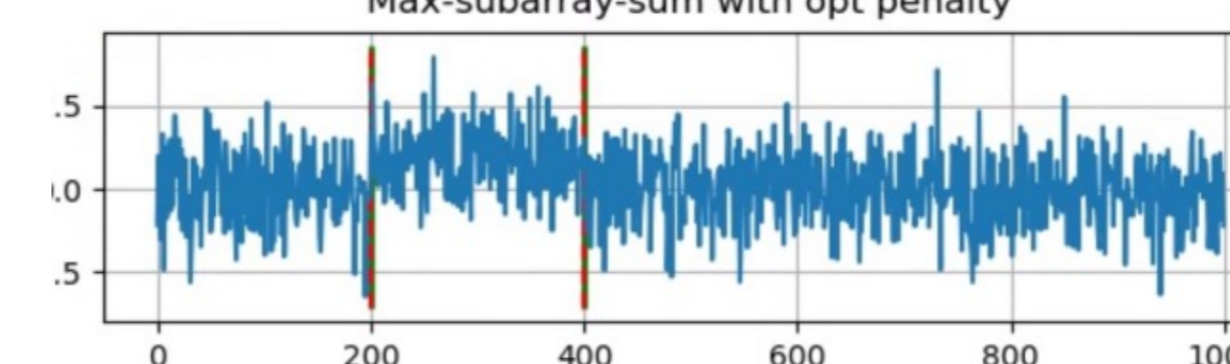
In practice, can set δ based on prior knowledge of $\mu_1 - \mu_0$

Localization Error Analysis

Lemma: For naïve max subarray $\delta = 0$, expected localization error $\mathbb{E}[\hat{M} - M | \hat{M} \geq M] = \frac{N - M}{2}$



Lemma: For penalized version $\delta > 0$, error independent of N



References

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