

## Biased Backpressure (BP) Routing for Wireless Multihop Networks

**Backpressure (BP) routing in 4 steps [1]**

- Select optimal commodity  

$$c_{ij}^*(t) = \operatorname{argmax}_{c \in \mathcal{V}} (U_i^{(c)}(t) - U_j^{(c)}(t))$$
- Find link gradient  

$$w_{ij}(t) = \max\{U_i^{(c_{ij}^*(t))}(t) - U_j^{(c_{ij}^*(t))}(t), 0\}$$
- MaxWeight scheduling (distributed heuristic)  

$$\mathbf{I}^{BP}(t) = \operatorname{argmax}_{\mathbf{I}(t) \in \{0,1\}^{|\mathcal{E}|}} \mathbf{I}(t)^\top \cdot [\mathbf{r}(t) \odot \mathbf{w}(t)]$$
- Assign link capacity to optimal commodities  

$$\mu_{ij}^{(c)}(t) = \begin{cases} r_{ij}(t), & \text{if } c = c_{ij}^*, w_{ij} > 0 \\ 0, & \text{otherwise} \end{cases}$$

Graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

Per-destination queues:  $Q_i^{(1)}(t), Q_i^{(c)}(t), Q_i^{(V)}(t)$

Commodity

Routing

Link Scheduling

Source: zhongyuanzhao.com

**Basic BP driven by congestion gradient only**

$U_i^{(c)}(t) = Q_i^{(c)}(t)$

Queue length

- ✓ Distributed Routing
- ✓ Congestion prevention
- ✓ Throughput optimality
- ✗ Poor latency performance
- ✗ Slow start
- ✗ Loop
- ✗ Last-packet problem

Loops

Source

Basic BP

**Biased BP adds distance gradient**

$U_i^{(c)}(t) = Q_i^{(c)}(t) + B_i^{(c)}$

Queue length

shortest path bias (e.g., hop counts from  $i$  to  $c$ )

- ✓ Distributed Routing
- ✓ Path finding
- ✓ Throughput optimality
- ✓ Better latency performance
- ✓ Slow start
- ✓ Loop
- ✓ Last-packet problem

No loops

Route established quickly

Source

Biased BP: shortest hop distance [2]

**Basic v.s. biased BP:** route visualization for simulations of 500 steps

## Test Results: 100 random network instances

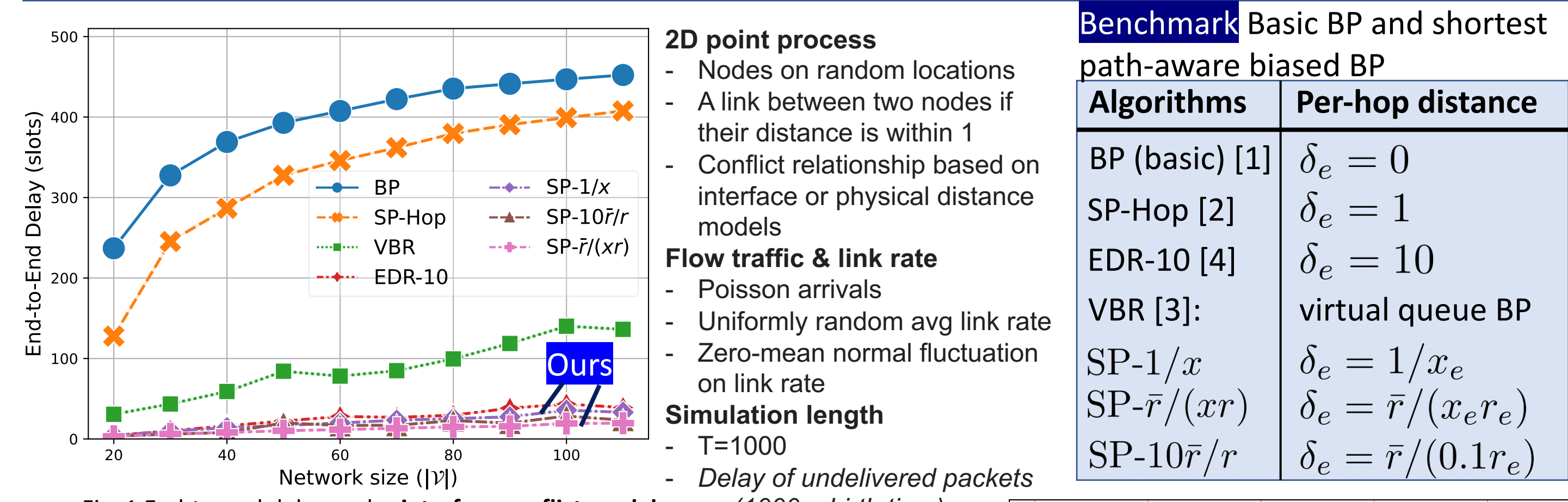


Fig. 1 End-to-end delay under interface conflict model (e.g., mmWave/THz wireless backhaul networks)

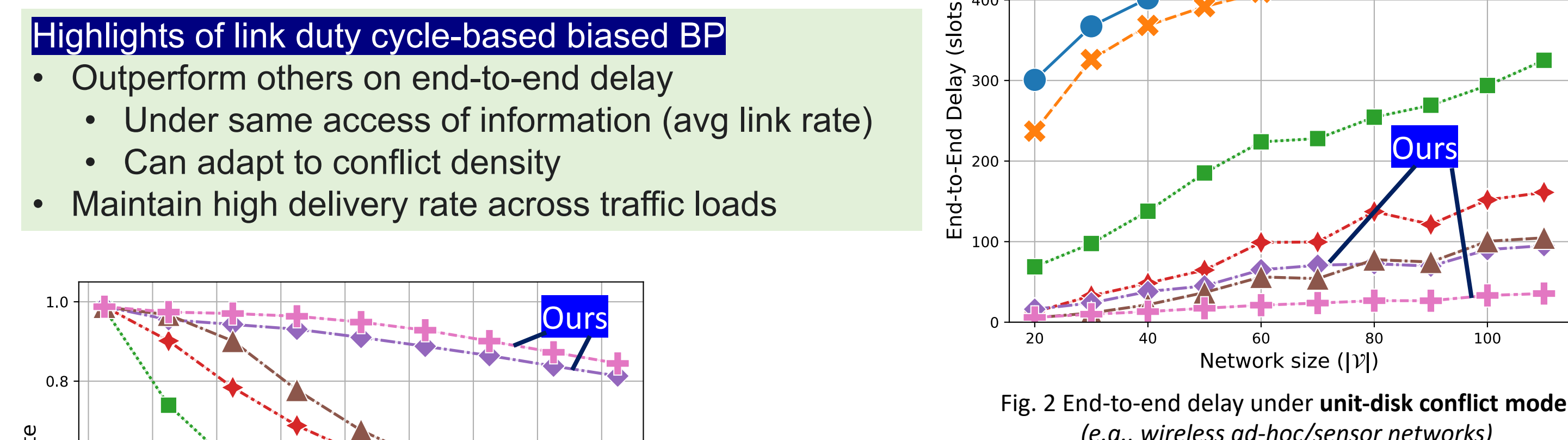


Fig. 2 End-to-end delay under unit-disk conflict model (e.g., wireless ad-hoc/sensor networks)

## Improve "Shortest Hop Counts" with "Conflict-aware shortest distance"

Shortest hop count bias promotes the **orange route**, of which both links have 8 conflicting neighbors, thus less likely being scheduled (link duty cycle = 1/9)

**Example**

Assume every link has an equal chance of being scheduled

Destination

Source

Shortest path bias based on link duty cycle promotes the **green route**, of which links have fewer conflicting neighbors, thus more likely to be scheduled (higher link duty cycle)

**Cost: Additional Distributed Complexity**

- GCNN  $\mathcal{O}(L)$  Constant
- Single source shortest path (SSSP)  $\mathcal{O}(V)$  Linear
- All pairs shortest path (APSP) weighted graph

Note: GCNN and APSP algorithms only need to be ran once a while, when network topology changes.

**Conflict-awareness**

Link duty cycle  $0 < x_e \leq 1 \quad e \in \mathcal{E}$

How likely a link is scheduled under current network topology and traffics

Per hop distance  $\delta_e = \frac{1}{x_e}$

Per hop distance with link rate  $\delta_e = \frac{\bar{r}}{x_e r_e}$

Link duty cycle estimated by an L-layer graph convolutional neural network (GCNN)

Fully distributed execution of GCNN

$$\mathbf{x}_{e^*}^t = \sigma \left( \mathbf{x}_{e^*}^{t-1} \Theta_0 + \left[ \mathbf{x}_{e^*}^{t-1} - \sum_{u \in \mathcal{N}_{GC}(e)} \frac{\mathbf{x}_u^{t-1}}{\sqrt{d(e)d(u)}} \right] \Theta_1 \right)$$

**Training of GCNN**

1. Draw a random network instance
2. Find delay-aware shortest path bias with GCNN and APSP
3. Run routing simulation for T steps, collect empirical schedules
4. After simulation, update GCNN with mean-square-error loss

Episode iteration

Connectivity graph  $\mathcal{G}(k)$ , Conflict graph  $\mathcal{G}^c(k)$ , Flows  $\mathcal{F}(k)$ , Packet arrivals  $\mathbf{A}(k)$ , Link rates  $\mathbf{R}(k)$

Per-link distance  $\mathbf{x}(k) = \Psi_{\mathcal{G}^c(k)}(\mathbf{1}; \omega)$

Shortest path bias  $\mathcal{B}(k)$

Empirical schedule  $\mathbf{s}^k(t) \in \{0, 1\}^{|\mathcal{E}|}$

$\ell(\omega) = \mathbb{E}_{\Omega} [MSE(\mathbf{x}(k), \mathbb{E}_t(\mathbf{s}^k(t)))]$

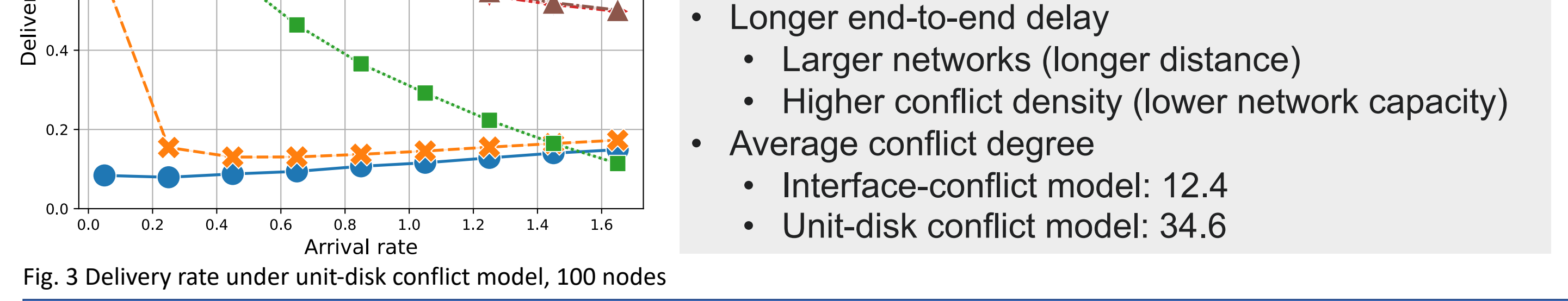


Fig. 3 Delivery rate under unit-disk conflict model, 100 nodes

## Conclusion & Future work

- Use shortest path bias to improve delay performance of back-pressure routing
  - Delay/conflict-aware shortest path bias based on link duty cycle
  - Link duty cycle predicted by Graph Convolutional Neural Networks (GCNN)
- Key advantages of biased backpressure routing
  - Fully distributed execution
  - Low overhead (low complexity & reusable bias)
- Future work: apply to other routing schemes, improve training method

### References

[1] L. Tassiulas, "Stability properties of constrained queueing systems and scheduling policies for maximum throughput in multihop radio networks," IEEE Trans. on Automatic Control, vol. 31, no. 12, 1992.

[2] M. Neely, E. Modiano, and C. Rohrs, "Dynamic power allocation and routing for time-varying wireless networks," IEEE J. Sel. Areas Commun., vol. 23, no. 1, pp. 89–103, 2005

[3] Z. Jiao, B. Zhang, W. Gong, and H. Moufah, "A virtual queue-based back-pressure scheduling algorithm for wireless sensor networks," EURASIP J. on Wireless Commun. and Netw., vol. 2015, no. 1, pp. 1–9, 2015.

[4] Y. Cui, E. M. Yeh, and R. Liu, "Enhancing the delay performance of dynamic backpressure algorithms," IEEE/ACM Trans. Netw., vol. 24, no. 2, pp. 954–967, 2016.