

Overview OBackground Problem Statement Model and Attack Experiments Questions Risk-Aware Vulnerability Analysis of Electric Grids from Attacker's Perspective By Yihai Zhu, Ph. D. Candidate, URI (Kingston, RI)

Background

- The largest blackouts around the world
 - 2003 Italy, 2003 Northest, 2005 Java-Bali, 2009 Brazil and Parguay, and 2012 India (670 millions)
 - · Rare to happen
 - · Cause disasters to modern society
- What is the cascading failure of power grid?
 - One of major reasons of large blackous
 - A cascading failure is an initial failure of certain parts, such as transmission lines, which triggers the successive failure of other parts, and finally disable the whole power grid.
 - To understand cascading failure is an important step to solve the problem of blackouts.

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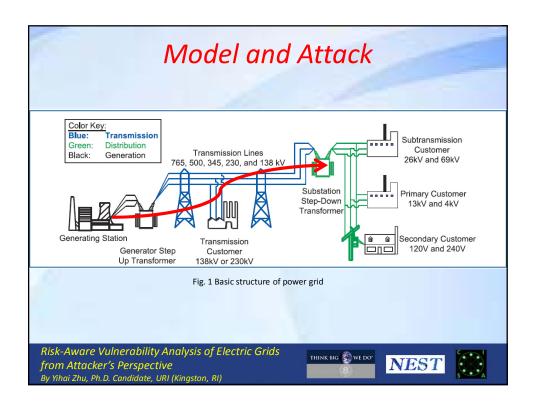
Problem Statement

- To find stronger attack strategies, aiming to cause severe cascading failures.
- Comparisons schemes
 - Load-based approach
 - Optimal search approach
- Contribution
 - Understanding vulnerability of power grid systems
 - Provide insights for future defense solutions









Extended Model

- Basic concepts
 - Directed graph (A): current direction on a link
 - Nodes: Generators, load substations, and transmission substations.
 - Adopt Power Transfer
 Distribution Factors (PTDFs) to reflect the power distribution in transmission lines.
 - Extended Betweenness (EB) of a node
 - Summation of the power in all links connecting to this node.

- Cascading simulator
 - Load: extende betweenness
 - Capacity: proportional to the initial load, e.g. node i

$$C_i = T * L_i(0)$$

- System tolerance: T
- Overloadeing: removed from power grid network
- Load rebalance
 - Recalculate EB
- Assessment: percent of failure (PoF)

$$PoF = 1 - \frac{M}{N}$$

N and M the number of surviving nodes before and after an attack







Sub-optimal Search Attack

Motivation

- Exisiting malicious attacks do not stand for the strongest attacks.
- Optimal search is computationally infeasible.
 - Five-node attack on IEEE 118 bus system needs to search more than a hundred million node combinations

Sub-optimal Search Attack

- Goals: (1) sharply reduce the computation task, (2) obtain good attack performance
- Primary idea: limit the number of candidate combinations during the each round search.

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The sub-optimal search attack

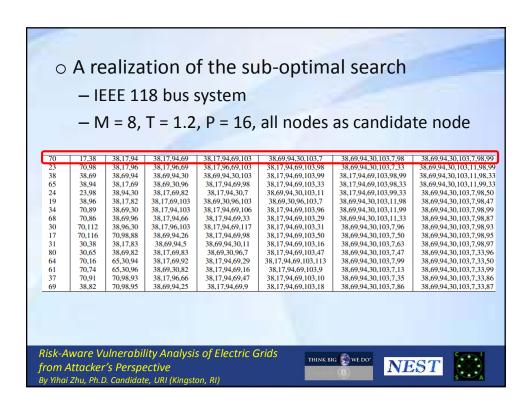
o Procedure

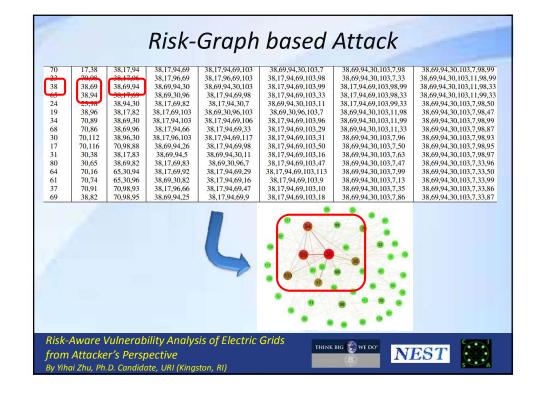
- Step 1: Set the number of target nodes, *M*, and system tolerance, *T*.
- Step 2: Run one-node attacks, and select the top P strongest nodes as first round chosen combinations.
- Step 3: Cascading simulator runs M 1 rounds. In each round
 - Combine each candidate node with each chosen combination from the previous round to get new combinations.
 - · Run attacks for all new combinations.
 - Top P strongest attacks as this round chosen combinations.











Construction of Risk Graph

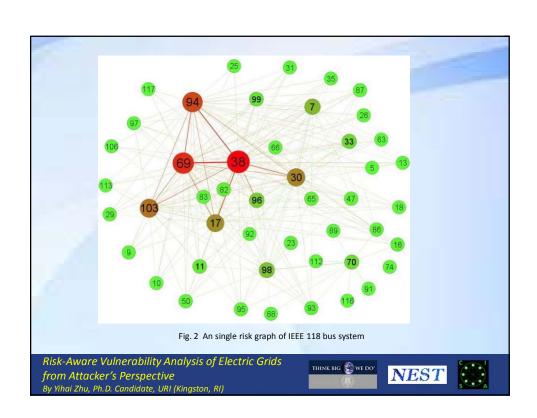
o Procedure

- Step 1: all the nodes in the table are vertexes in the risk graph.
- Step 2: deal with the combinations one by one.
 - A node appears in a combination, its frequency +1.
 - A combination contains more than one node, e.g. K nodes.
 - Add K(K-1)/2 edges into the risk graph.
 - Add the weight of each edge with 2/[K(K-1)].









Risk-graph Based Attack

- Integrated Risk Graph (IRG)
 - Set T from 1.05 to 2 with an interval 0.05, and obtain 20 single risk graphs.
 - Add those 20 single risk graphs as a IRG.
- Risk-graph based attack based IRG
 - M == 1, choose the node with largest frequency.
 - M >= 2, choose the M nodes. First, there must exist an edge between each pair of vertexes.
 Second, the summation of the weight on all those edges is maximum.

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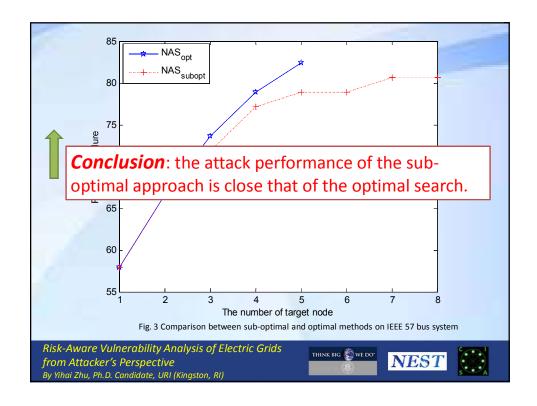
Experiments

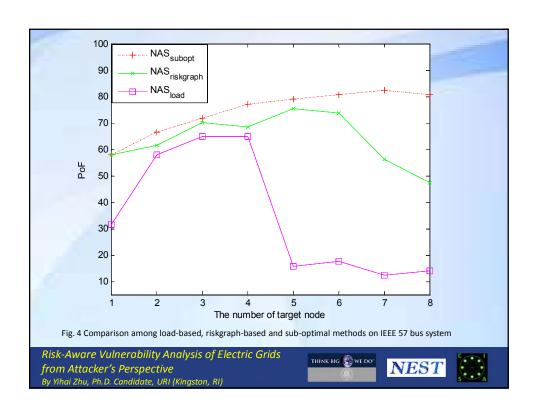
- Test benchmarks
 - IEEE 57 bus system and IEEE 118 bus system
- Comparisons
 - Sub-optimal vs optimal
 - Load-based, riskgraph-based, sub-optimal

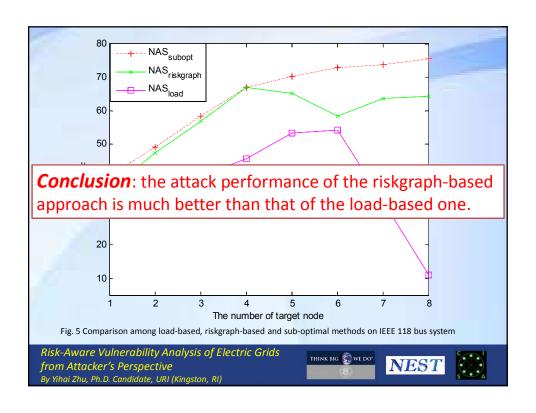












| | THE SUMMA | RY OF DIFFEREN | ATTACK STRATEG | IES |
|-----------------------------|------------------|-----------------------|--------------------|-----------------|
| Attack Strategy | NAS^{M}_{load} | $NAS^{M}_{riskgraph}$ | NAS^{M}_{subopt} | NAS_{opt}^{M} |
| Comple- xity | O(1) | O(1) | $O(M(N_B)^2)$ | $O((N_B)^M$ |
| Effective- ness | Low | High | High | High |
| Need system tolerance | No | No | Yes | Yes |
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