

Grad-CAM-Inspired Interpretation of Nearfield Acoustic Holography using Physics-Informed Explainable Neural Network

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CONTEXT

ISSUE: Visual explanation of a recent physics-informed approach for Nearfield Acoustic Holography (NAH) using vibrating rectangular plates with different boundary conditions and violin top plates with complex shapes.

GOAL: Interpret and explain the decision-making process of the Kirchhoff-Helmholtz-based Convolutional Neural Network (KHCNN) architecture.

PROPOSED METHODOLOGY: Propose a Grad-CAM-inspired approach for the visual explanation of neural network architecture for regression problems.

ABSTRACT

The interpretation and explanation of decision-making processes of neural networks are becoming a key factor in the deep learning field. Although several approaches have been presented for classification problems, the application to regression models needs to be further investigated. In this manuscript we propose a Grad-CAM-inspired approach for the visual explanation of neural network architecture for regression problems. We apply this methodology to a recent physics-informed approach for Nearfield Acoustic Holography, called Kirchhoff-Helmholtz-based Convolutional Neural Network (KHCNN) architecture.

We focus on the interpretation of KHCNN using vibrating rectangular plates with different boundary conditions and violin top plates with complex shapes. Results highlight the more informative regions of the input that the network exploits to correctly predict the desired output. The devised approach has been validated in terms of NCC and NMSE using the original input and the filtered one coming from the algorithm.

1. SCIENTIFIC BACKGROUND - Nearfield Acoustic Holography

The complex exterior radiated pressure (i.e., magnitude and phase information) measured at a point r due to the vibration of the structure at $\omega = 2\pi f$ can be formulated with the Kirchhoff-Helmholtz (KH) integral as:

$$p(r, \omega) = \int_S p(s, \omega) \frac{\partial}{\partial \mathbf{n}} g_\omega(r, s) dS - j\omega \rho_0 \int_S v_n(s, \omega) g_\omega(r, s) dS$$

- s a point of surface S
- ρ_0 the density of the medium (for air $\rho_0 = 1.225 \text{ kg m}^{-3}$)
- n the outward vector normal to the surface at s
- $v_n(s, \omega)$ the normal velocity field
- $p(s, \omega)$ pressure field on the vibrating surface considering the propagation from s to r
- $g_\omega(r, s)$ Free-field Green's function

Nearfield Acoustic Holography (NAH) aims at computing $v_n(s, \omega)$ starting from $p(r, \omega)$ acquired by a microphone array on the holographic plane \mathcal{H} ($r \in \mathcal{H}$). Therefore, the goal of NAH relies on the inversion of the equation above, namely:

$$\hat{v}_n(s, \omega) \Big|_{s \in S} \approx \Gamma^{-1} [p(r, \omega)] \Big|_{r \in \mathcal{H}}$$

2. SCIENTIFIC BACKGROUND - Grad-CAM

Gradient-weighted Class Activation Mapping (Grad-CAM) is a post-hoc explanation via visualisation of class discriminative activation for a network. Grad-CAM takes advantage on a key property of deep convolutional layers.

Grad-CAM determines the neuron importance weights as the global average pooling of the gradients over the spatial dimension, namely:

$$\alpha_k^c = \frac{1}{Z} \sum_i^H \sum_j^W \frac{\partial y^c}{\partial A_{ij}^k}$$

c a class $\in C$

k feature maps in the last convolution layer (A^k)

y^c the score for class c

α_k^c the neuron importance weights

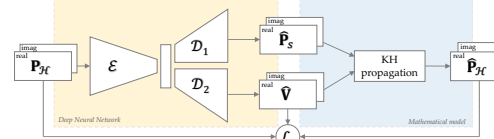
$$R^c = \text{ReLU} \left(\sum_k \alpha_k^c A^k \right)$$

$Z = H \times W$ the spatial resolution of the feature map with height H and width W .

Applying ReLU function to the linear weighted sum of the activation maps.

3. PROPOSED METHOD

The block scheme of KHCNN architecture is:



INPUT: $P_H(\omega) \in \mathbb{C}^{M_1 \times N_2}$ - the normal velocity field and the pressure field on S

OUTPUT: $\hat{P}_H(\omega) \in \mathbb{C}^{M_1 \times M_2}$ - the acoustic pressure fields

NETWORK ARCHITECTURE:

- Deep Neural Network Block - CNN with one encoder E and two decoders D_1 and D_2 to estimate the latent variable \hat{P}_S and the velocity \hat{V} from the input.
- Mathematical model block - contain layers of mathematical steps according to the KH integral to create the estimate \hat{P}_H for the training.

THE LOSS FUNCTION:

The proposed algorithm aims to visualize the heatmap H to highlight the important regions of the input P_H needed to produce the KHCNN estimate \hat{V} .

We use the loss function defined as: $\mathcal{L} = 0.5 \cdot \mathcal{L}_{Im} + 0.5 \cdot \mathcal{L}_{Re}$, with:

$$\mathcal{L}_{Re} = \left\| \text{Re}(\hat{V}) - \text{Re}(\hat{V}_H) \right\|_2^2 + \left\| \text{Re}(P_H) - \text{Re}(\hat{P}_H) \right\|_2^2,$$

$$\mathcal{L}_{Im} = \left\| \text{Im}(\hat{V}) - \text{Im}(\hat{V}_H) \right\|_2^2 + \left\| \text{Im}(P_H) - \text{Im}(\hat{P}_H) \right\|_2^2,$$

For regression problem, the Grad-Cam weights are modified:

$$\alpha_k = \frac{1}{Z} \sum_i \sum_j \frac{\partial \mathcal{L}}{\partial A_{ij}^k}$$

4. EVALUATION METRICS

- Normalized Cross Correlation (NCC) $\text{NCC} = \frac{|\hat{V}_f^H \cdot \hat{V}|}{\|\hat{V}_f\|_2 \cdot \|\hat{V}\|_2}$
- Normalized Mean Square Error (NMSE) $\text{NMSE} = 10 \log_{10} \left(\frac{e^H \cdot e}{\hat{V}^H \cdot \hat{V}} \right)$

between the KHCNN estimates coming from the acquired input pressure and the filtered one by the resulting heatmap H

5. SETUP

Using the pre-trained KHCNN architecture, we focus on two datasets:

- 672 aluminium rectangular plates (different dimensions and boundary conditions)
- 1568 violin top plates made of Sitka spruce (different resolutions and only free BC)
- The datasets were generated using COMSOL Multiphysics® software simulating the radiated pressure in M points and the normal velocity field in N points of different plates excited at different ω .

We consider high-resolution input with $M = 16 \times 64$ points and low-resolution input with $M = 8 \times 8$ points. In both cases KHCNN estimates the desired velocity in $N = 16 \times 64$ points.

6. RESULTS

The fig shows three examples of rectangular plates

having different BCs along with the input hologram pressure in $M = 1024$ points, the velocity estimate and its ground truth in $N = 1024$ points.

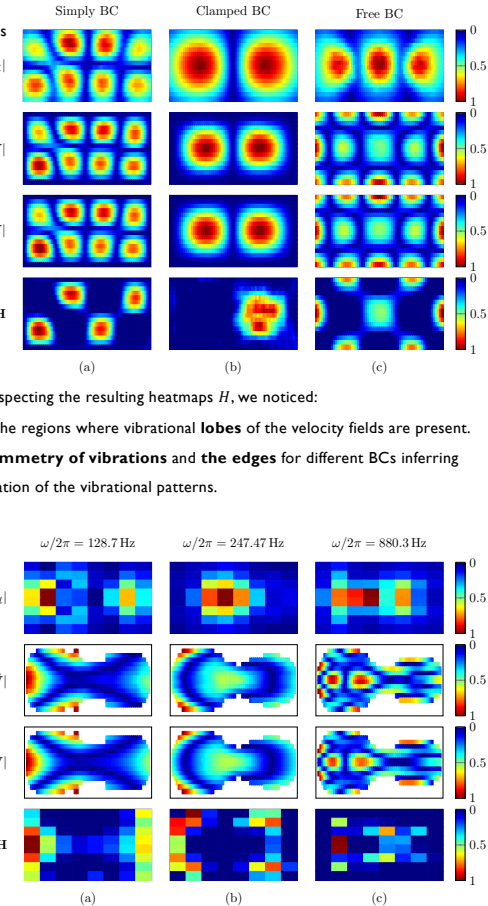
From the output of decoder D_2 we applied the algorithm to obtain

the heatmap H . In general, inspecting the resulting heatmaps H , we noticed:

- the network focuses on the regions where vibrational lobes of the velocity fields are present.
- KHCNN exploits the symmetry of vibrations and the edges for different BCs inferring the estimates as interpolation of the vibrational patterns.

For the violin top plate we analyze the KHCNN architecture using

$M = 64$ points for the input pressure. Again, three examples of violin top plates vibrating at different f with the computed $H \in \mathbb{R}^{8 \times 8}$.



We can notice that the network is more affected by the edges of the input mainly at low f . Conversely, when f increases the network focuses on the internal regions.

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