



# Fractional Fourier Transform in Time Series Prediction

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## Introduction

- Thriving tendency towards integrating DNNs with classical signal processing tools; e.g. FT, STFT, WT.
- FrFT as a generalized version of FT, controlled by a fraction order  $a$ .
- No additional computational load; fast computation algorithm with  $O(N \log N)$  time complexity [Ozaktas et al., 1996].
- Allowing signal representation in a continuum between time and frequency.
- Different information flows and feature extractions in neural networks with FrFT [Sahinuc et al., 2022].
- Working with best signal representation in the underlying network.

## Contributions

- Introducing FrFT to machine learning by combining it with RNNs for time series prediction.
- Motivated by using a generalized transform for infinitely many transformations to enhance model performance.
- FrFT-based RNNs surpass those in time or frequency domain for prediction performance.
- Additionally, incorporating FrFT order  $a$  as a learnable parameter.

## Primer on Fractional Fourier Transform

- For  $a \in \mathbb{R}$ , the  $a$ th order FrFT  $\mathcal{F}^a$  of a function or signal  $f(t) \in \mathcal{L}^2(\mathbb{R})$  is defined as follows:

$$\mathcal{F}^a(u) = \mathcal{F}^a\{f(t)\}(u) = \int_{-\infty}^{\infty} K_a(u, t) f(t) dt,$$

$$K_a(u, t) = A_\phi e^{i\pi(u^2 \cot \phi - 2ut \csc \phi + t^2 \cot \phi)},$$

$$A_\phi = \sqrt{1 - i \cot \phi}, \quad \phi = a\pi/2,$$

$$K_a(u, t) = \begin{cases} A_\phi e^{i\pi(u^2 \cot \phi - 2ut \csc \phi + t^2 \cot \phi)} & \text{if } a \neq 2k \\ \delta(u - t) & \text{if } a = 4k - 2 \\ \delta(u + t) & \text{if } a = 4k + 2, \end{cases}$$

where  $k$  is an integer. FrFT operates with period 4 such that  $\mathcal{F}^a = \mathcal{F}^b$  where  $a \equiv b \pmod{4}$  [Ozaktas et al., 2001, Tao et al., 2009].

- Possible to represent the discrete-time signals in FrFT domain
- Like DFT computed via matrix-vector multiplication, DFrFT can also be expressed similarly.
- Let  $\mathcal{X}_n \in \mathbb{R}^L$  is a sequence of length  $L$  and the formal definition for DFrFT of  $\mathcal{X}_n$  is given as a matrix multiplication:

$$\mathcal{X}_{F^a} = W^a \mathcal{X}_n, \quad (1)$$

where  $\mathcal{X}_n$  is manifested as a column vector, and  $W^a$  is the  $L \times L$  DFrFT matrix with order  $a$  as given below:

$$W^a[m, n] = \sum_{k=0, k \neq (L-1+(L)_2)}^L u_k[m] e^{-i\frac{\pi}{2}ka} u_k[n], \quad (2)$$

where  $(L)_2 \equiv L \pmod{2}$  and  $u_k$  is the  $k$ th discrete Hermite-Gaussian function [Candan et al., 2000].

## Time Series Prediction Using Fractional Fourier Representations

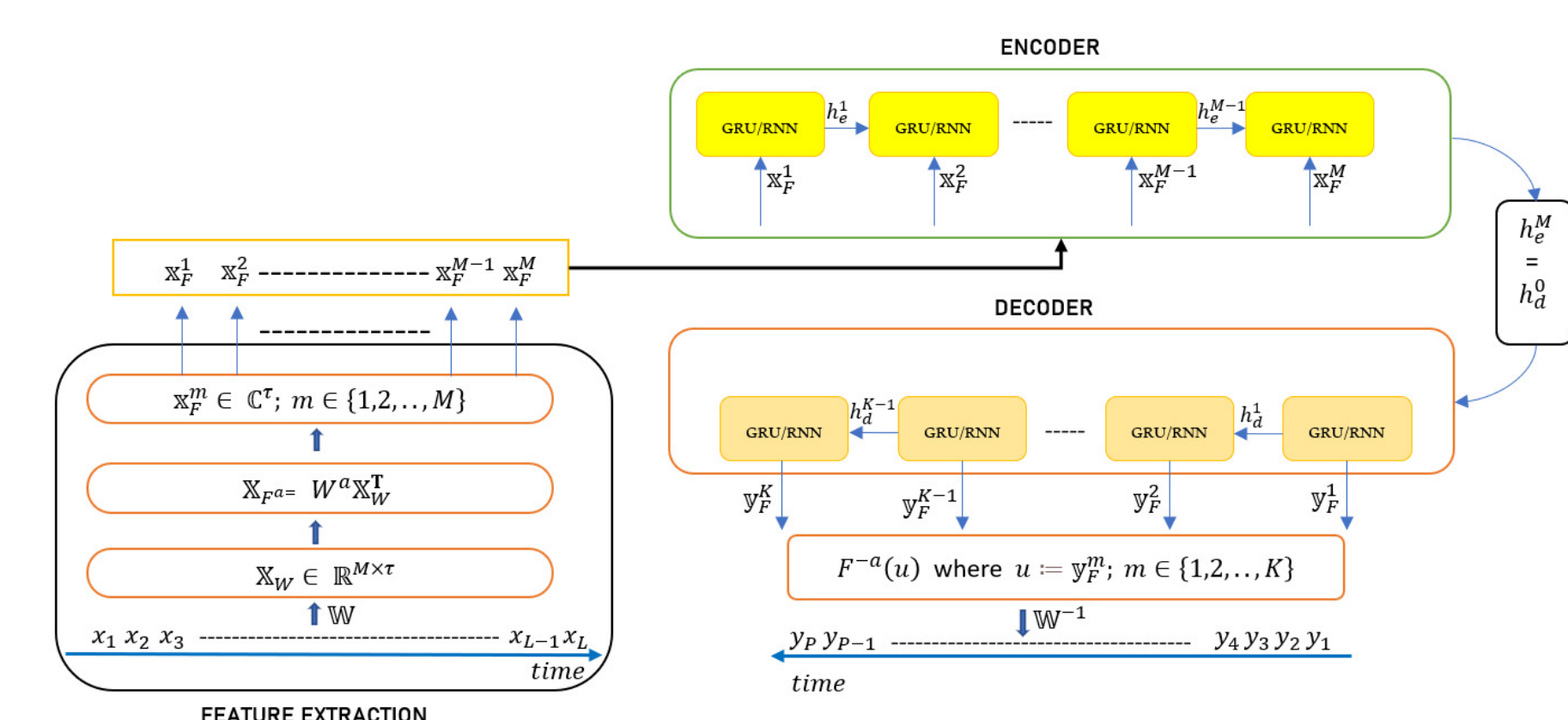


Figure 1: End-to-end FrFT based time series prediction with sequence models.

- The first stage is FrFT-based feature extraction:

$$\mathcal{X}_n[m] = w_n[n - Sm] \mathcal{X}_n[n], \quad (3)$$

$$\mathbb{X}_W = \mathbb{W}(\mathcal{X}_n) \in \mathbb{R}^{M \times \tau}, \quad (4)$$

$$\mathbb{X}_{F^a} = W^a \mathbb{X}_W, \quad (5)$$

$$\mathbb{X}_{F^a} \in \mathbb{C}^{\tau \times M} \mapsto \{\mathbf{x}_F^m\}_{m=1}^M \in \mathbb{C}^\tau, \quad (6)$$

where  $\mathbb{W}$  is a mapping from a sequence to matrix of where each row is a windowed segment  $X_n[m]$  and  $W^a \in \mathbb{C}^{\tau \times \tau}$  is a DFrFT matrix of  $a$

- **Second stage:** Many-to-many encoder-decoder with GRU or basic RNN cells, resulting in two variants.
- First stage features feed the second stage's encoder; decoder processes only time-domain data.

## Model Training

- The information propagates through encoder cells.
- The final hidden state information is passed to the decoder.
- The output vectors of the decoder are multiplied with DFrFT of order  $-a$  to calculate the inverse FrFT, then converted to one-dimensional sequences.
- In the backward pass, the mean-squared error (MSE) between the predicted sequence and the decoder training sequence is calculated.

## Datasets

- **Mackey-Glass Chaotic Time Series:**

- It is generated from a nonlinear, time delay differential system that is described by the following differential equation:

$$\frac{dx}{dt} = \frac{\beta x(t-T)}{1 + x^{10}(t-T)} - \gamma x(t), \quad (7)$$

where  $\beta = 0.2$ ,  $\gamma = 0.1$ ,  $dt = 0.1$ , and  $T = 17$ . Starting values up to  $T$ -th second are initialized as  $1 + u[-0.1, +0.1]$  where  $u$  stands for the uniform distribution.

- **UCI Electricity Load Dataset**

- Contains the electricity consumption of 370 customers from Jan. 1, 2011, to Jan. 1, 2015, in 15 min. resolution, and values are in kW.
- Due to many missing values, data before 2011 is not utilized. Each value is divided by 4 (since 15 minutes is one-fourth of an hour) to convert energy consumption into kWh.

- **USD-TRY Currency Exchange Ratio:**

- Data of the currency exchange ratio between USD and Turkish lira (TRY) from Jan. 1, 2007, to Jan. 1, 2020.

## Results

- Normalized mean-squared percentage error (NMSPE) as our evaluation metric:
- Defined as  $100 \frac{\sum_{i=1}^N (y_i - \hat{y}_i)^2}{\sum_{i=1}^N (y_i)^2}$  and expressed as a percentage:  $y_i$  is the target value and  $\hat{y}_i$  is the predicted value.

Table 1: Mackey-Glass for various architectures and orders  $a$ .

		Model					
$a$	GRU64	RNN64	GRU64 <sub>LP16</sub>	RNN64 <sub>LP16</sub>	cgGRU64	cgGRU32	
0.5	0.030	<b>0.022</b>	71.84	71.63	<b>0.005</b>	<b>0.022</b>	
0.6	<b>0.021</b>	0.034	64.14	64.20	<b>0.010</b>	<b>0.020</b>	
0.7	0.026	<b>0.026</b>	47.14	47.55	<b>0.011</b>	<b>0.032</b>	
0.8	<b>0.020</b>	<b>0.017</b>	2.256	3.614	<b>0.006</b>	<b>0.054</b>	
0.9	0.024	<b>0.013</b>	<b>0.039</b>	0.027	<b>0.010</b>	<b>0.039</b>	
1.0	0.023	0.034	0.044	0.012	0.015	<b>0.175</b>	
1.1	0.027	<b>0.031</b>	<b>0.040</b>	0.041	<b>0.004</b>	<b>0.078</b>	
1.2	0.033	<b>0.023</b>	0.942	2.556	<b>0.011</b>	<b>0.029</b>	
1.3	<b>0.018</b>	<b>0.019</b>	46.85	46.91	<b>0.009</b>	<b>0.013</b>	
1.4	0.024	<b>0.016</b>	64.13	64.19	<b>0.009</b>	<b>0.014</b>	
1.5	<b>0.016</b>	<b>0.017</b>	71.71	71.81	<b>0.013</b>	<b>0.035</b>	

Table 2: Try/Usd for various architectures and orders  $a$ .

		Model					
$a$	GRU64	RNN64	GRU64 <sub>LP16</sub>	RNN64 <sub>LP16</sub>	cgGRU64	cgGRU32	
0.5	<b>9.33</b>	9.78	63.22	63.31	9.07	<b>8.81</b>	
0.6	<b>9.72</b>	9.32	49.01	48.95	8.95	<b>7.65</b>	
0.7	<b>9.61</b>	10.17	43.43	43.05	9.03	<b>8.48</b>	
0.8	9.84	9.28	<b>10.08</b>	<b>10.40</b>	8.84	<b>8.49</b>	
0.9	9.99	8.72	<b>9.91</b>	<b>10.39</b>	9.23	<b>9.10</b>	
1.0	9.74	8.15	10.74	10.92	8.57	9.73	
1.1	<b>9.54</b>	9.03	<b>10.08</b>	<b>10.39</b>	9.33	<b>8.94</b>	
1.2	<b>9.43</b>	9.89	10.83	10.92	8.84	<b>8.48</b>	
1.3	<b>9.70</b>	10.44	44.55	44.58	<b>8.06</b>	<b>8.15</b>	
1.4	10.13	10.05	49.08	48.89	9.38	<b>8.23</b>	
1.5	<b>9.05</b>	10.17	62.70	62.96	9.22	<b>8.68</b>	

Table 3: Electric consumption for various architectures and orders  $a$ .

		Model					
$a$	GRU64	RNN64	GRU64 <sub>LP16</sub>	RNN64 <sub>LP16</sub>	cgGRU64	cgGRU32	
0.5	28.54	11.98	79.52	71.43	17.25	22.30	
0.6	21.26	10.92	59.73	55.93	19.39	<b>20.30</b>	
0.7	20.62	11.58	56.78	47.2	<b>16.27</b>	<b>19.78</b>	
0.8	26.65	<b>10.34</b>	12.98	14.33	<b>15.14</b>	21.71	
0.9	19.95	<b>10.36</b>	12.47	<b>7.51</b>	18.41	<b>19.00</b>	
1.0	19.00	10.54	10.12	8.38	16.98	20.63	
1.1	<b>17.24</b>	11.52	12.94	<b>8.03</b>	<b>16.86</b>	<b>20.62</b>	
1.2	<b>18.58</b>	<b>10.40</b>	11.89	8.65	17.18	<b>19.70</b>	
1.3	25.38	10.64	53.55	47.26	18.68	25.65	
1.4	<b>18.82</b>	<b>10.42</b>	61.86	56.41	19.72	<b>18.38</b>	
1.5	21.54	12.19	85.77	71.43	18.41	<b>20.31</b>	

Table 4: Best model performances of the proposed method compared to baselines that use GRU/RNN.

Dataset	Model	NMSPE(%)
Mackey-Glass	RNN64 ( $a_1=0.944$ )	<b>0.0035</b>
	cgGRU64 ( $a=1.1$ )	0.004
	GRU64 <sub>baseline</sub>	0.23
	RNN64 <sub>baseline</sub>	5.48
TRY-USD	cgGRU32 ( $a_1=1.277$ )	<b>6.59</b>
	cgGRU64 ( $a=1.3$ )	8.06
	GRU64 <sub>baseline</sub>	10.30
	RNN64 <sub>baseline</sub>	12.01
Electric Consumption	GRU64 ( $a_1=0.858$ )	<b>6.20</b>
	RNN64 <sub>LP16</sub> ( $a=0.9$ )	7.51
	GRU64 <sub>baseline</sub>	10.84
	RNN64 <sub>baseline</sub>	14.76

## References

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