

Data-Scarce Condition Modeling requires Model-Based Prior Regularization

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Abstract

- Intermediate target values of the wear time series are not available and need to be estimated from an accumulated, end-of-process measurement.
- An iterative least-squares approach is used to estimate the hidden intermediate targets based on linear regression.
- The target estimates are used as regularization prior for DNN training.
- Experiments use real-world data of refractory wear processes in steel production.

Model-Based Prior Regularization

- Neural networks often struggle with convergence and overfitting on scarce and noisy data, but linear models cannot adequately represent complex relationships.
- We use an **Iterative Least Squares (ILS)** method to estimate intermediate targets from linear models.
- Target estimates are used to train deep neural networks (DNN).
- Estimated and measured targets are balanced by a regularization term.

- Step 1: Run ILS algorithm to generate target estimates \mathbf{h}^T
- Step 2: Use ILS regularization during DNN training:

$$\mathcal{L} = \alpha \frac{1}{K} \sum_{k=1}^K (y_c - \bar{y}_c)^2 + (1 - \alpha) \frac{1}{K} \sum_{k=1}^K \frac{1}{N_c} \sum_{n=1}^{N_c} (h_c^T[n] - \bar{h}_c[n])^2$$

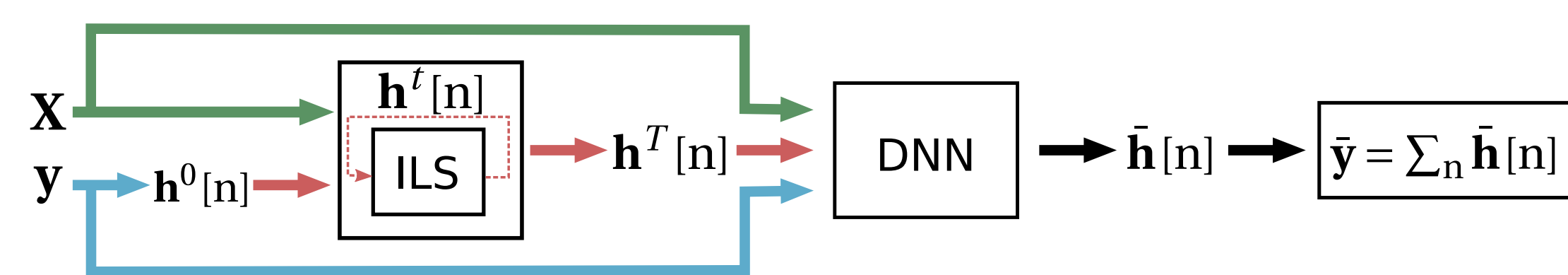


Figure 1: DNN bootstrapping process for the hidden targets \mathbf{h} .

ILS

Input: $X_c, y_c \forall c$
Parameters: T (T : # iterations)
Output: $h_c^T \forall c$ (estimated targets)
for $c = 1$ **to** C **do**
 Initialize: $h_c^0 \leftarrow h_c^0[n] = \frac{y_c}{N_c}; \forall n$
end for
for $t = 1$ **to** T **do**
 for $c = 1$ **to** C **do**
 (least squares fit)
 $X_I \leftarrow x_i[n]; \forall n, i \in C \setminus c$
 $h_I \leftarrow h_i^{t-1}[n]; \forall n, i \in C \setminus c$
 $\hat{\beta}^t \leftarrow (X_I^T X_I)^{-1} X_I^T h_I$ (predictor step)
 $X_V \leftarrow x_c[n]$
 $\hat{h}_c \leftarrow X_V \hat{\beta}^t$ (corrector step)
 $b_c \leftarrow y_c - \sum_{n=1}^{N_c} \hat{h}_c[n]$
 $\hat{h}_c^t[n] \leftarrow \frac{1}{N_c} b_c + \hat{h}_c[n]; \forall n$
 $h_c^t[n] \leftarrow \begin{cases} \hat{h}_c^t[n], & \text{if } b_{min} \leq \hat{h}_c^t[n] \\ b_{min}, & \text{else} \end{cases}; \forall n$
 $h_c^t \leftarrow h_c^t[n]; \forall n$
 end for
end for
Return $h_c^T \forall c$

Conclusion

- We propose a regularization prior for wear prediction of refractory material in metallurgical vessels.
- Use of a two step estimation principle: first estimate hidden targets with our proposed ILS approach, second estimate DNN parameters using hidden targets as regularization prior.
- Models trained with ILS-estimated targets outperform the same models using aggregations in the feature domain or normalizing overall measurements.
- Bootstrapping DNNs with estimates of intermediate targets is beneficial for small and noisy data sets.
- Our proposed regularized DNNs show substantial improvement over DNNs trained solely with MSE.

Results

- Variation of regularization between $\alpha = 0$ (only ILS-estimated targets) and $\alpha = 1$ (only measurements).
- Blending intermediate target estimates into the loss function clearly improves prediction accuracy.

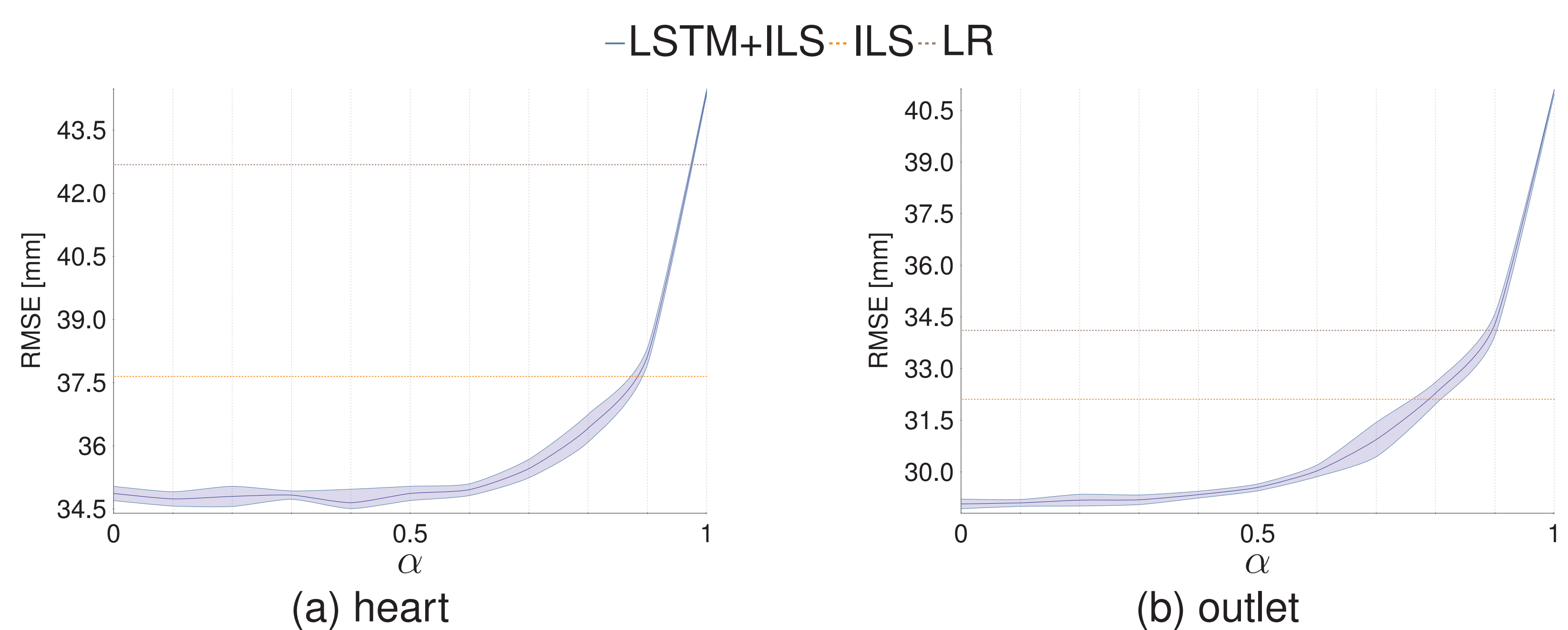


Figure 2: Influence of α on the LSTM model performance.

- Linear Regression (LR):** Linear regression with uniform intermediate targets
- Iterative Least Squares (ILS):** Linear regression with iteratively estimated intermediate targets
- Deep Neural Network (DNN) Architectures (ILS bootstrapped):** LSTM, 1D CNN, 2D CNN

Table 1: RMSE performance in [mm] and standard deviation for the DNN models.

	LSTM	1D CNN	2D CNN	ILS	LR
Metal zone	17.33 ± 0.17	17.56 ± 0.20	17.40 ± 0.07	19.48	22.66
Slag zone	24.54 ± 0.17	23.25 ± 0.22	24.66 ± 0.07	26.34	31.07
Heart	34.65 ± 0.14	35.01 ± 0.20	34.40 ± 0.30	37.65	42.68
Inlet	22.24 ± 0.17	23.21 ± 0.26	22.61 ± 0.63	24.39	29.02
Outlet	29.07 ± 0.14	29.84 ± 0.10	29.15 ± 0.41	32.11	34.33