

# LOW COST VARIABLE STEP-SIZE LMS WITH MAXIMUM SIMILARITY TO THE AFFINE PROJECTION ALGORITHM



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## Abstract

The LMS algorithm is widely employed in adaptive systems due to its robustness, simplicity, and reasonable performance. However, it is well known that this algorithm suffers from a slow convergence speed when dealing with colored reference signals. The affine projection algorithm is a good alternative in this case. This algorithm has the peculiarity of starting from  $N$  data vectors of the reference signal. It transforms these vectors into as many data vectors suitably normalized in energy and mutually orthogonal. In this work, we propose a **version of the LMS algorithm** that, similar to the affine projection algorithm, **starts from  $N$  data vectors of the reference signal but corrects them by using only a scalar factor** that functions as a convergence step. Our goal is to align the behavior of this algorithm with the behavior of the affine projection algorithm without significantly increasing the computational cost of the LMS. [1]

## Algorithms update equations

### NLMS:

$$\mathbf{w}(n) = \mathbf{w}(n-1) + \frac{1}{\mathbf{x}_L^T(n)\mathbf{x}_L(n)} \mathbf{x}_L(n)e^a(n). \quad (1)$$

### AP:

$$\mathbf{w}(n) = \mathbf{w}(n-1) + \mathbf{X}(n)[\mathbf{X}^T(n)\mathbf{X}(n)]^{-1} \mathbf{e}^a(n), \quad (2)$$

$$\mathbf{X}(n) = [\mathbf{x}_L(n), \mathbf{x}_L(n-1), \dots, \mathbf{x}_L(n-N+1)].$$

### APL:

$$\mathbf{w}(n) = \mathbf{w}(n-1) + \mu(n)\mathbf{X}(n)\mathbf{e}^a(n), \quad (3)$$

with

$$\mu(n) = \mu_I(n) = \frac{\|\mathbf{X}(n)\mathbf{e}^a(n)\|^2}{\|\mathbf{X}^T(n)\mathbf{X}(n)\mathbf{e}^a(n)\|^2}, \quad (4)$$

defines the affine-like-I (APL-I) [2].

## Conclusion

In this work, it is proposed a **modification of the LMS algorithm that behaves like the AP avoiding matrix inversion**. It is a **robust** algorithm that significantly improves the performance of NLMS with minimal additional computational cost.

It exhibits **excellent performance for colored signals** up to the projection orders where the convergence behavior of the AP cannot be improved either. Therefore, the algorithm's performance is significant, and the trade-off between convergence speed and computational cost is, in most cases, much superior to that of other similar algorithms such as NLMS or other APL proposals.

## References

- [1] Miguel Ferrer, María de Diego, and Alberto Gonzalez. Low cost variable step-size lms with maximum similarity to the affine projection algorithm. *IEEE Open Journal of Signal Processing*, 5:82–91, 2024.
- [2] Md. Zulfikar Ali Bhotto and Andreas Antoniou. Affine-projection-like adaptive-filtering algorithms using gradient-based step size. *IEEE Transactions on Circuits and Systems I: Regular Papers*, 61(7):2048–2056, 2014.

## Proposed variable step-size selection

It may be inferred that an adaptive algorithm would exhibit similar behaviour to a given one if its coefficients were very close at each algorithm iteration. Therefore, we **propose the use of a variable convergence step that minimises the squared 2-norm of the difference between the coefficients of the exact AP algorithm**, denoted as  $\mathbf{w}_{AP}(n)$  and shown in (2), **and the approximate version**, denoted as  $\mathbf{w}_{APL}(n)$  and shown in (3). This means

$$\tilde{\mu}(n) = \arg \min_{\mu(n)} \{ \|\mathbf{w}_{AP}(n) - \mathbf{w}_{APL}(n)\|^2 \}, \quad (5)$$

or equivalently

$$\tilde{\mu}(n) = \arg \min_{\mu(n)} \{ \|\mathbf{X}(n)(\mathbf{X}(n)^T\mathbf{X}(n))^{-1} - \mu(n)\mathbf{X}(n)\mathbf{e}^a(n)\|^2 \}, \quad (6)$$

leading to

$$\tilde{\mu}(n) = \frac{(\mathbf{e}^a(n))^T \mathbf{e}^a(n)}{[\mathbf{X}(n)\mathbf{e}^a(n)]^T \mathbf{X}(n)\mathbf{e}^a(n)} = \frac{\|\mathbf{e}^a(n)\|^2}{\|\mathbf{e}^a(n)\|_{\Sigma(n)}^2}, \quad (7)$$

where  $\Sigma(n) = \mathbf{X}(n)^T\mathbf{X}(n)$ . Thus, the proposed approach uses the update equation in (3), just like the AP and the APL-I, except that the convergence step is obtained by solving the minimization problem in (5). This approach would require  $LN + 3N$  multiplications for updating the coefficients, which is a lower count compared to the AP and the APL-I algorithms.

## Convergence discussion

It is suggested in [2] that:

$$0 < \mu(n) < \mu_{\max}(n) = \frac{2}{\lambda_{\max}(n)}, \quad (8)$$

where  $\lambda_{\max}(n)$  is the maximum eigenvalue of  $\mathbf{X}(n)\mathbf{X}^T(n)$  (equivalently  $\lambda_{\min}(n)$ ).

Equation (7) is a generalised Rayleigh quotient. This ensures that the following boundaries are satisfied

$$\frac{1}{\lambda_{\max}(n)} \leq \tilde{\mu}(n) \{ \mu_I(n) \} \leq \frac{1}{\lambda_{\min}(n)}. \quad (9)$$

We can only guarantee that (8) is fulfilled when the eigenvalues of the matrix  $\mathbf{X}^T(n)\mathbf{X}(n)$  are not sparse.

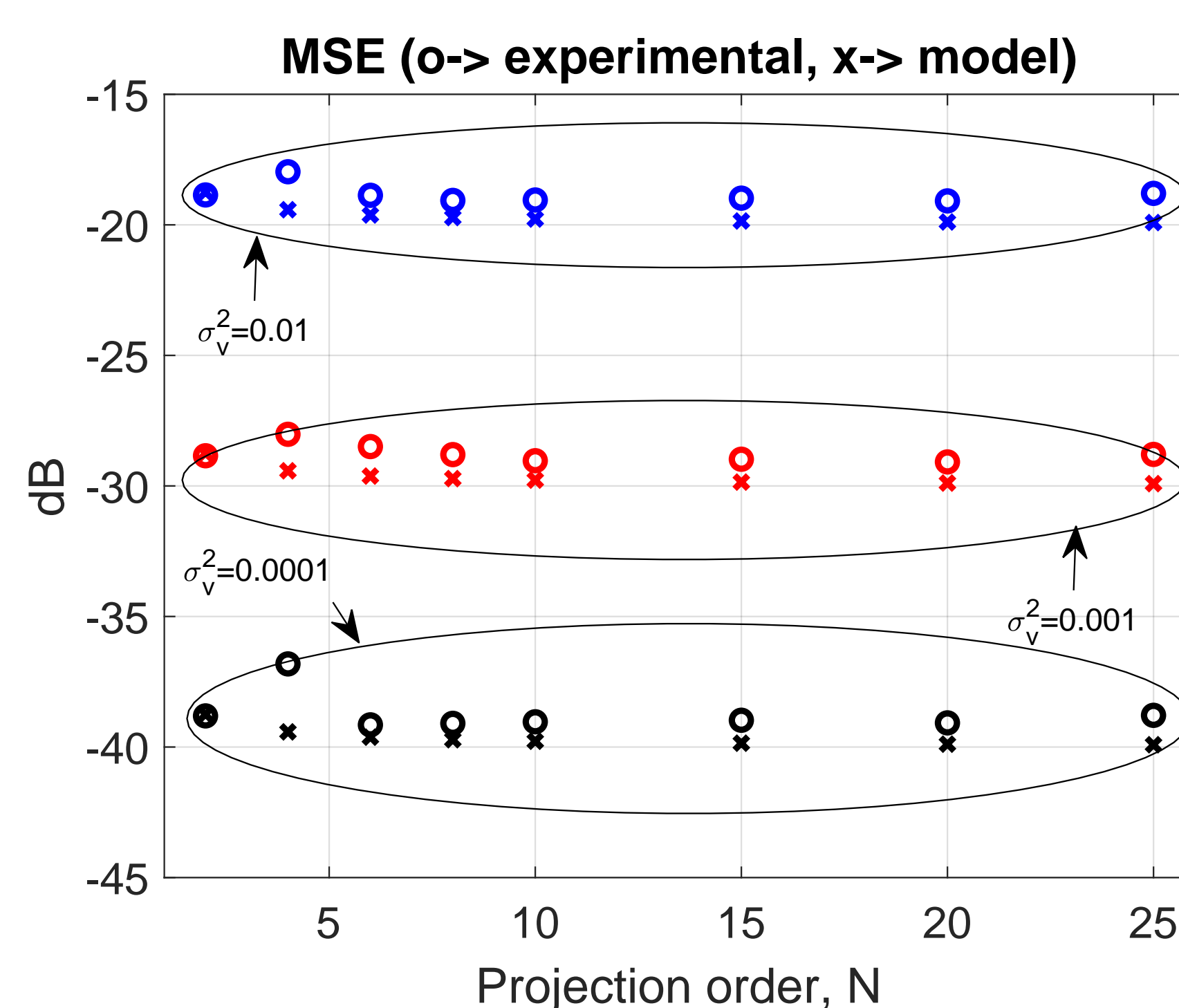
$$\lambda_{\max}(n)/\lambda_{\min}(n) < 2, \quad (10)$$

which stands for low colored signals and colored ones and low projection orders.

The MSE can be approximated as

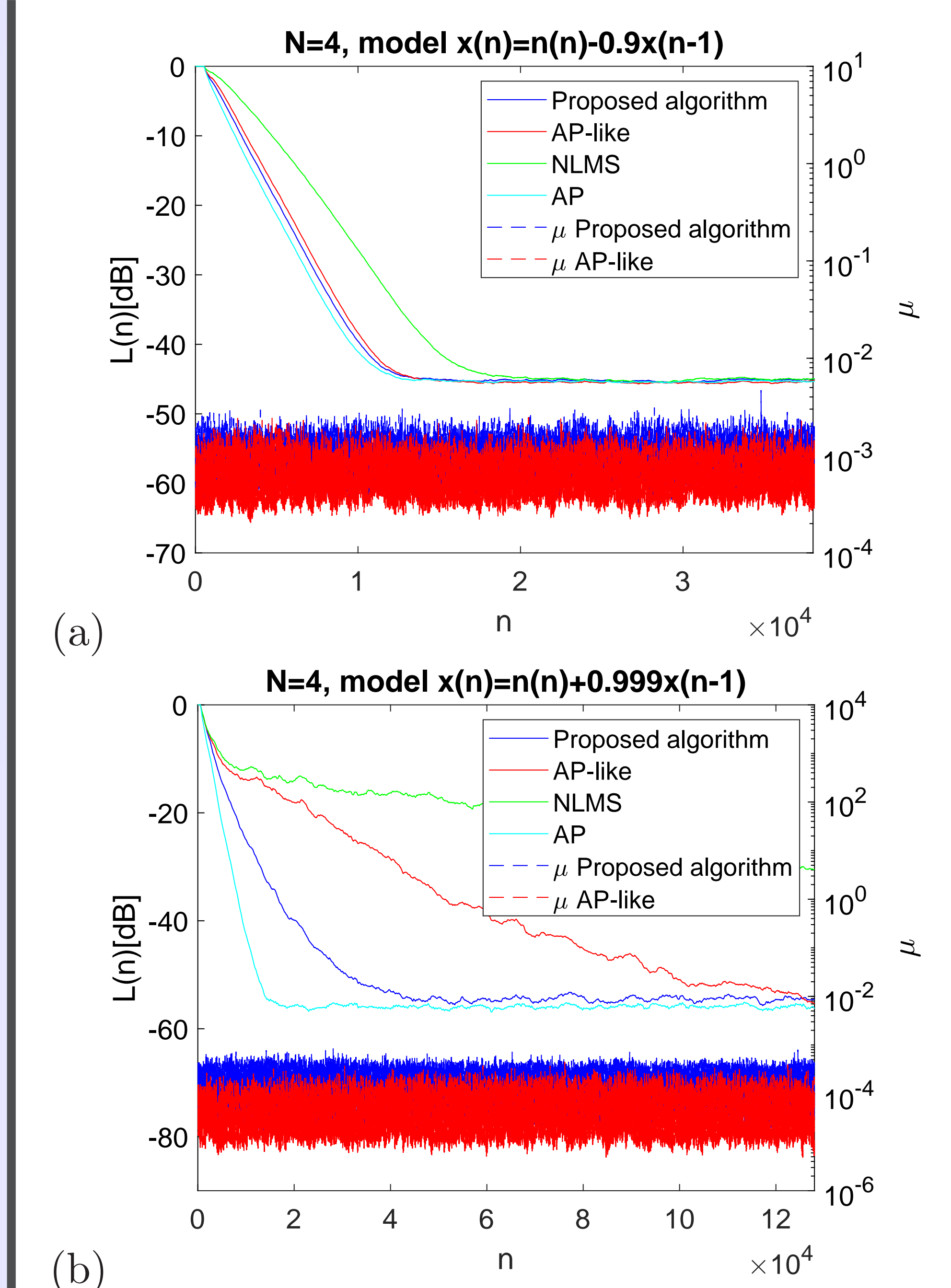
$$\text{MSE} \approx \sigma_v^2 \frac{3N-1}{2N-1}, \quad (11)$$

and  $\text{MSE} < 2\sigma_v^2$ .

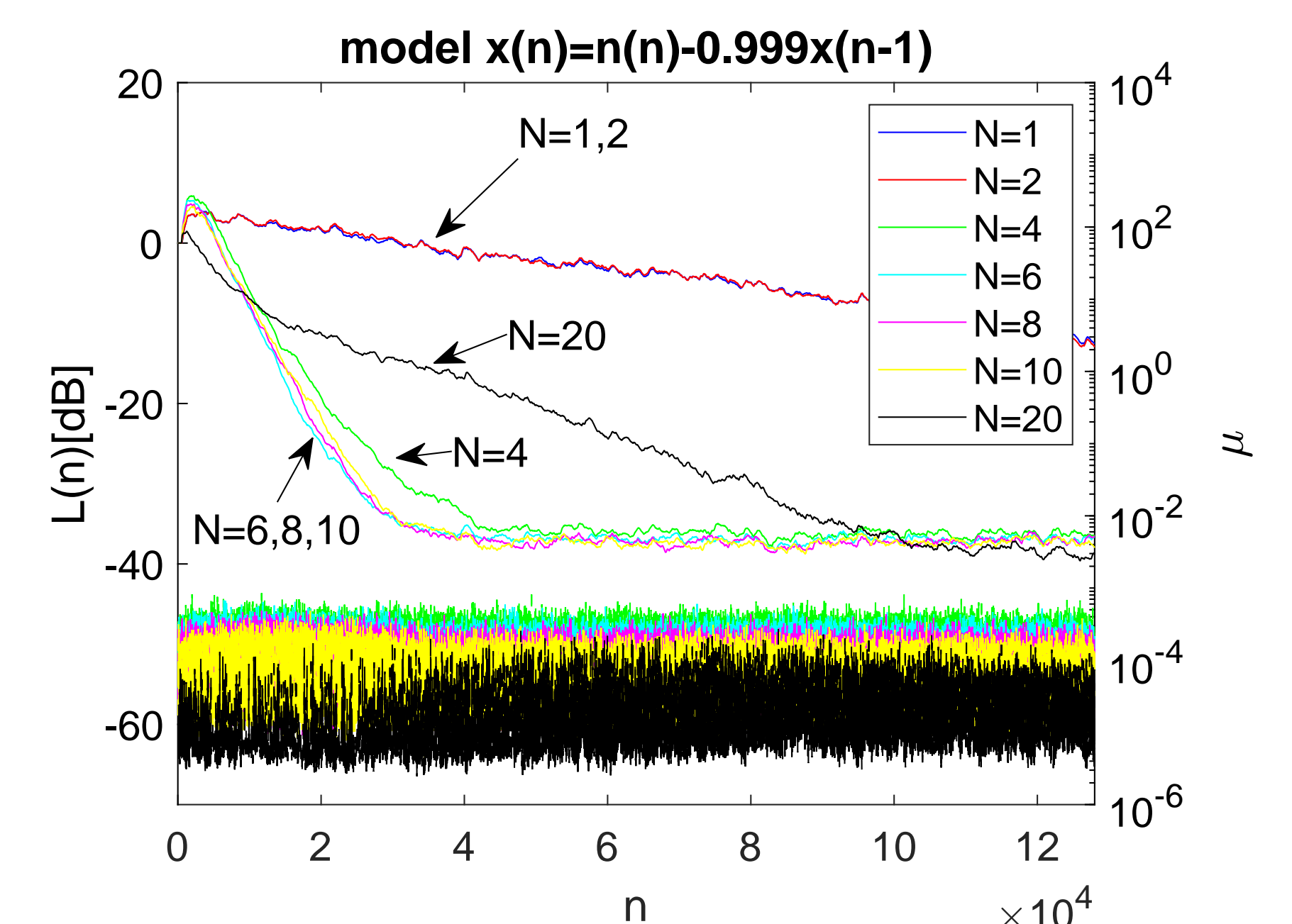


**Figure 1:** Experimental and theoretical MSE versus projection order for the system identification problem.

## Results



**Figure 2:** Comparative learning curves and step-size values for: AP, APL-I and the proposed algorithm for  $N = 4$  when the input signal is: (a) slightly colored ( $\gamma = 0.9$ ) and (b) highly colored ( $\gamma = 0.999$ ).



**Figure 3:** Learning curves and step-size values of the proposed algorithm and different projection orders for highly colored reference signal.