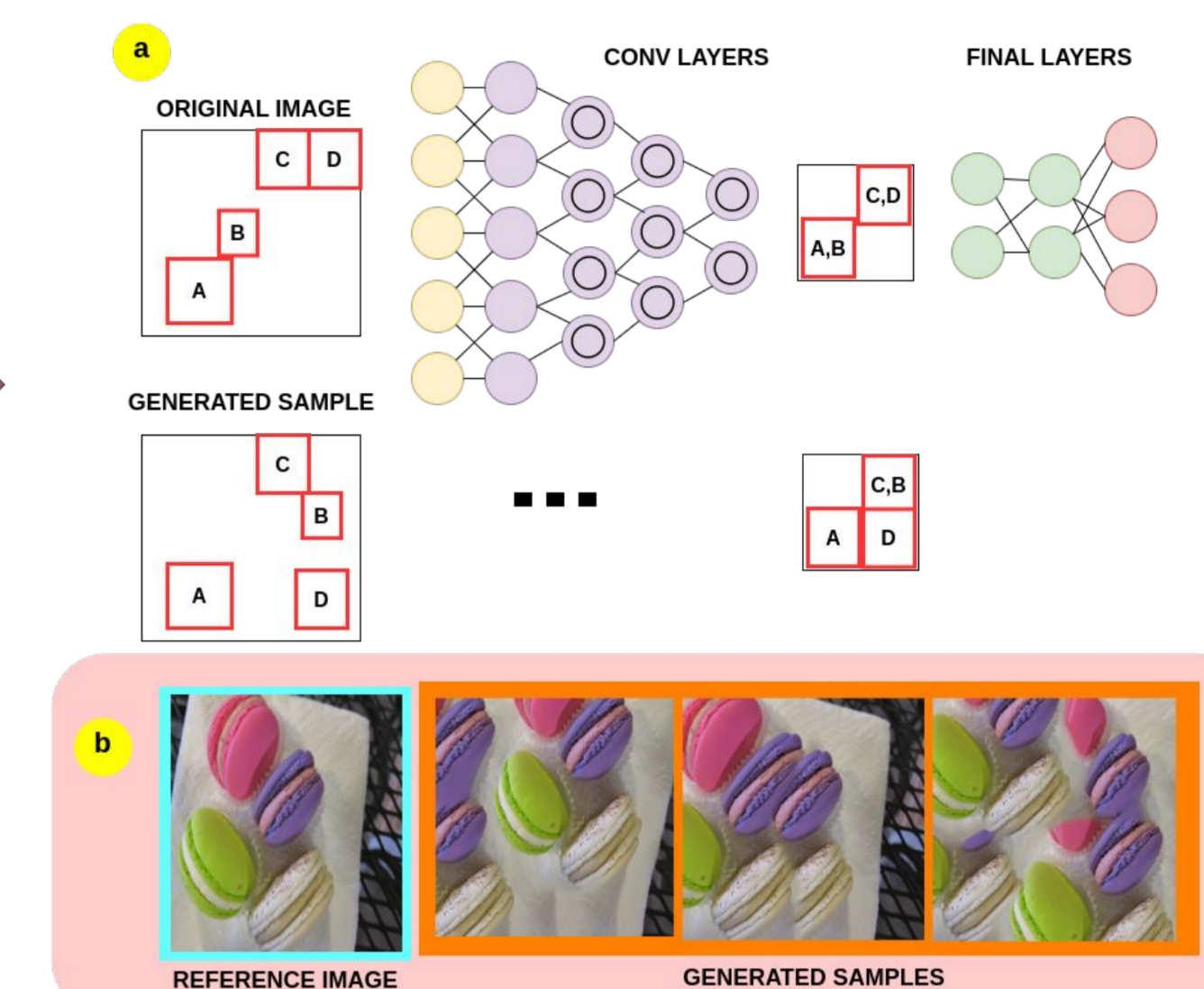


## Terminology

- **Attribution:** (a.k.a heat maps) Identifying where classifier looks to make its decision
- **CAM:** Class Activation Maps. A family of Attribution Methods (e.g. GradCAM, ScoreCAM)
- **Single Image Generation:** Making realistic variations of a single Image (e.g. SinGAN).

## Motivation

- (right) If we can create variations of an image, we can see a broader range of the classifier's behaviour. This may help attribution.
- (left) t-sne of conv-features from variations (red) and from original image (blue). red feats semantically interpolate between blue feats.
- But, need a fast generative model: SinGAN too slow (~hours/image), so we use Generative Patch Nearest Neighbors (GPNN) (~seconds/image)

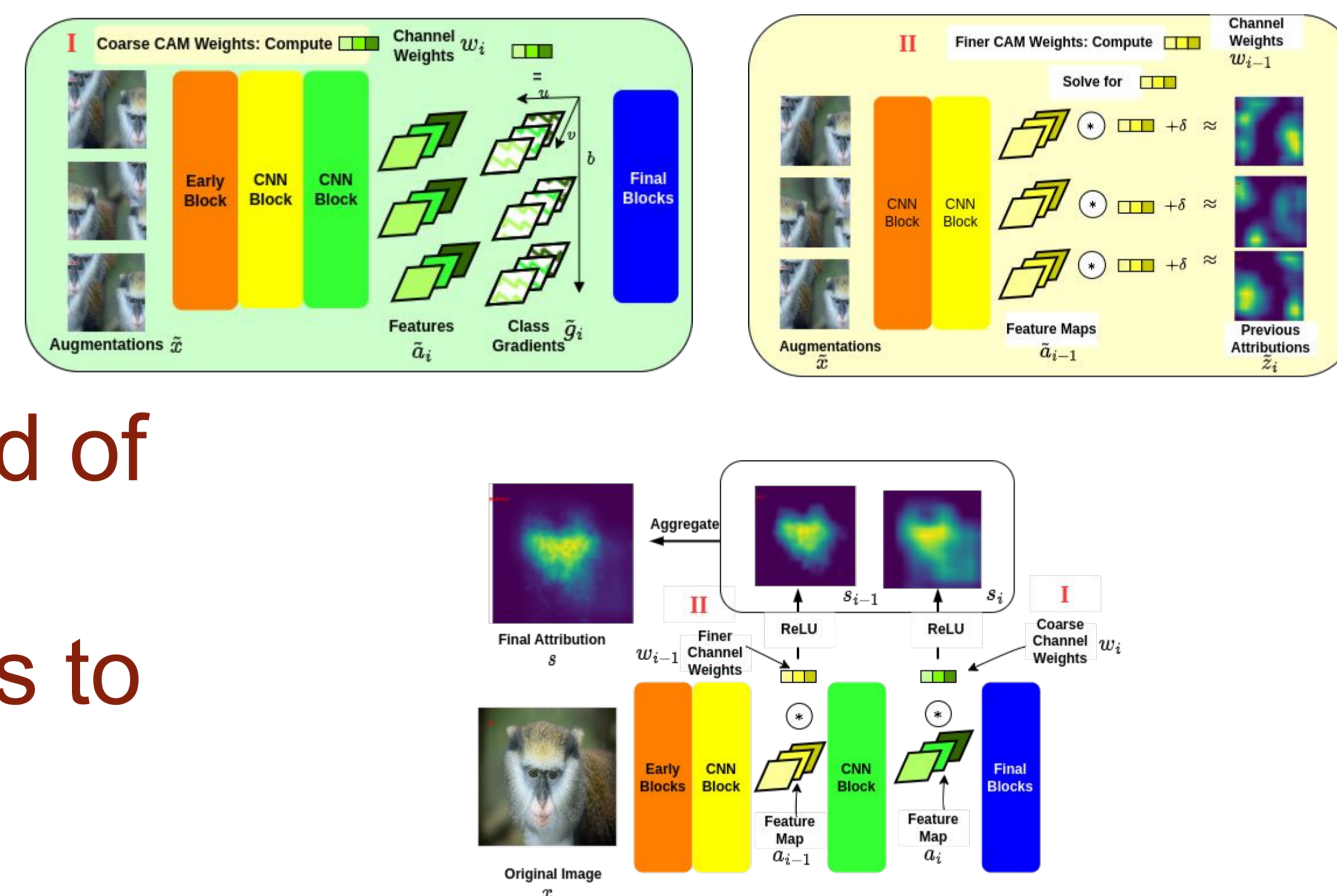


## Contributions

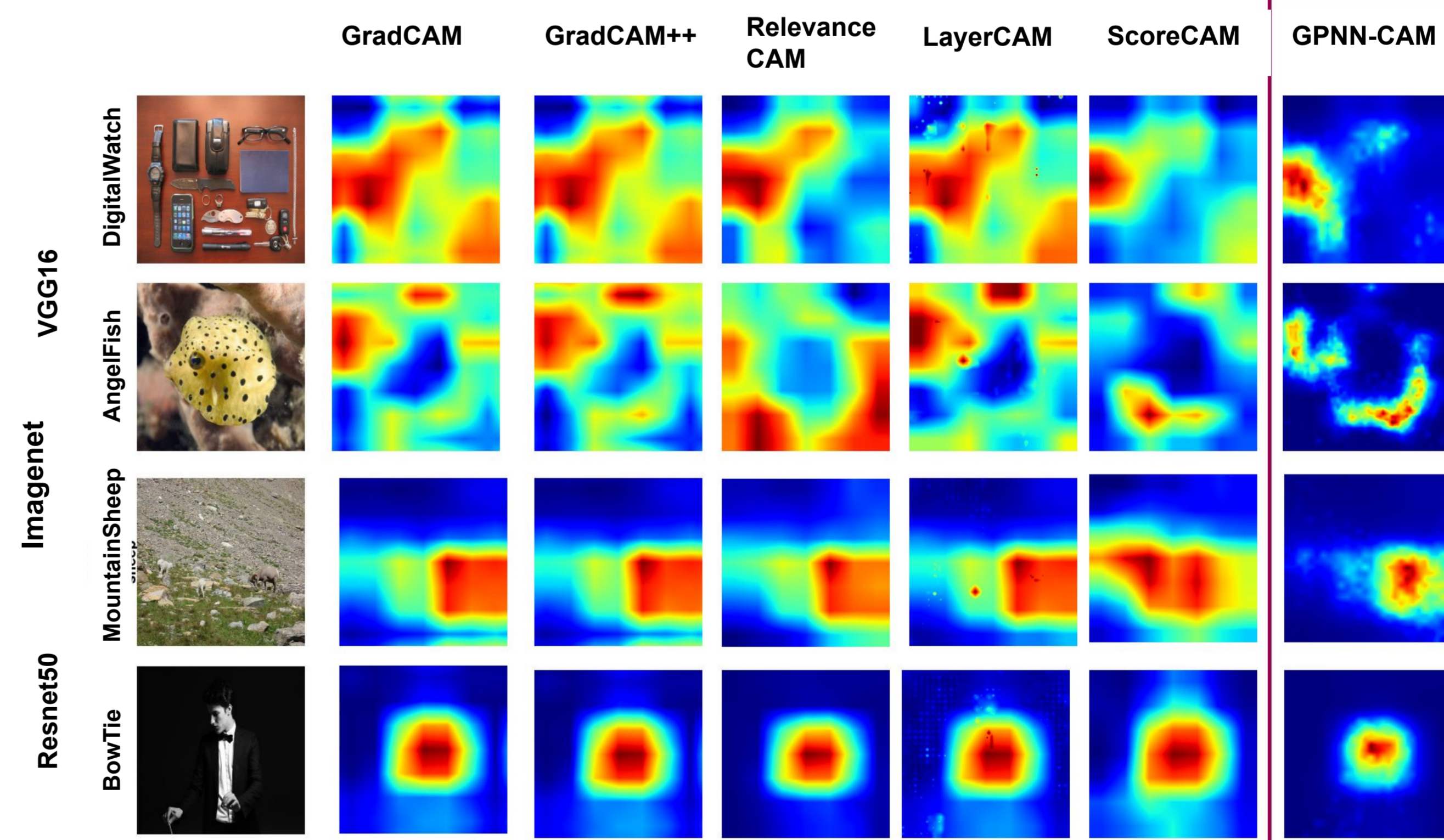
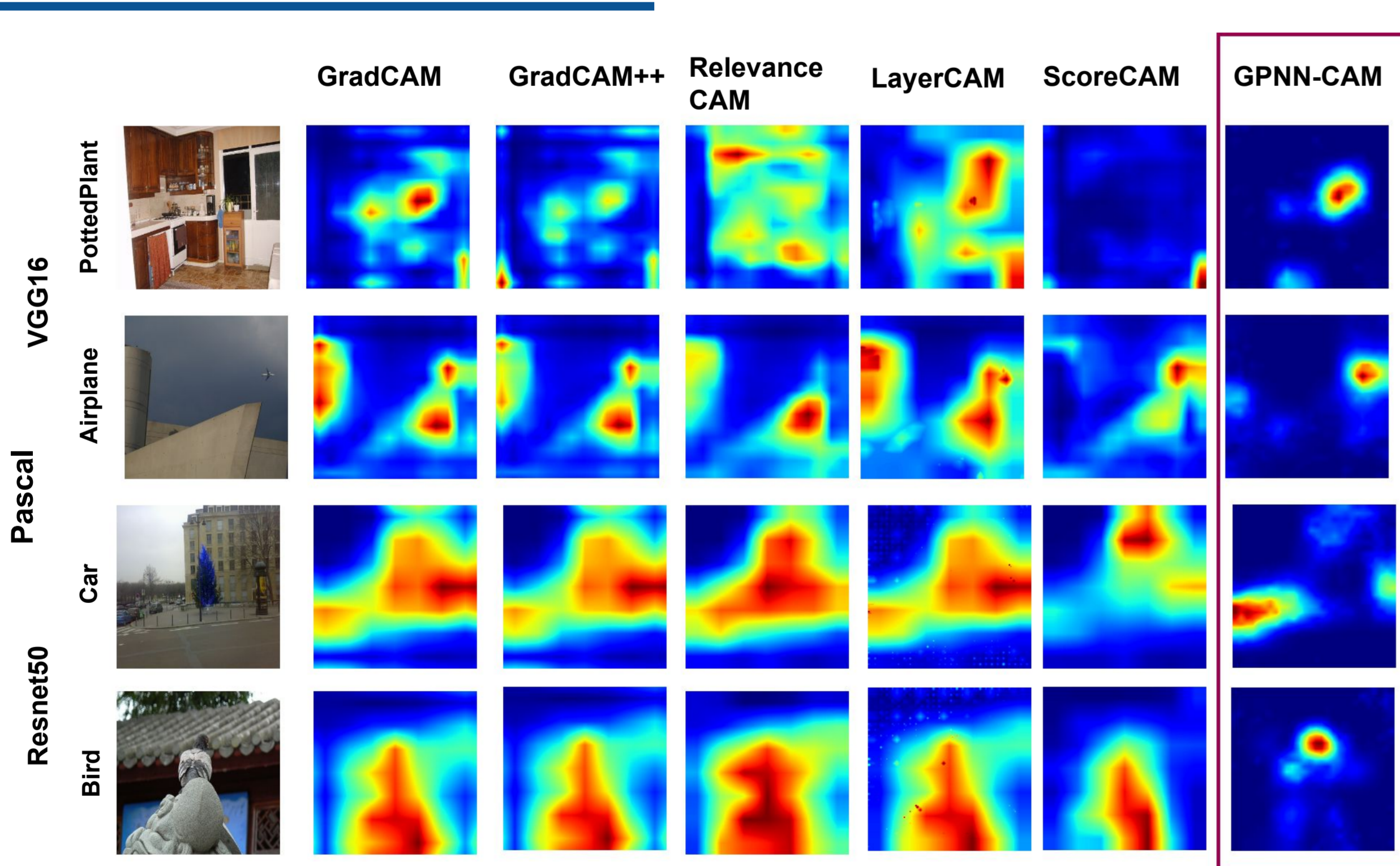
- Investigating how generated variations of a image can help improve attribution.
- A new Attribution method, **GPNN-CAM** to effectively utilize these variations

## Method 2 step pipeline GPNN-CAM

- **Phase 1 (green):** GradCAM flavoured algorithm, GradCAM: combine gradients (grads) and activations (acts) to get heat map. **GPNN-CAM:** Instead of single image, we use act and grad of all variations.
- **Phase 2 (yellow):** Use lower conv-layer acts to regress to previous heat map.
- Combine heat maps from all layers



## Qualitative Results



## Quantitative Results

- **Pointing Game:** % of times the highest point of the heat map is inside the object bounding box. (Best in bold, second best underlined)

	Imagenet		Pascal(All/Diff)	
	VGG16	ResNet50	VGG16	ResNet50
GradCAM	<u>0.937</u>	0.928	<u>0.780/0.595</u>	0.765/0.552
GradCAM++	0.927	<u>0.929</u>	0.724/0.513	0.759/0.543
RelevanceCAM	0.914	0.917	0.634/0.362	0.757/0.533
ScoreCAM	0.918	0.905	0.682/0.508	<u>0.789/0.624</u>
LayerCAM	0.899	0.917	0.750/0.557	0.771/0.611
<b>GPNN-CAM</b>	<b>0.946</b>	<b>0.945</b>	<b>0.830/0.699</b>	<b>0.866/0.749</b>

## References

- Drop the gan: In defense of patches nearest neighbors as single image generative models, Granot et. al. CVPR 2022
- Grad-cam: Visual explanations from deep networks via gradient-based localization, Selvaraju et. al. ICCV 2017

## Contact

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