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# Redefining Visual Quality: The Impact of Loss Functions on INR-Based Image Compression

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#### **Implicit Neural Representations**

Contributions

Implicit Neural Representations (INR) is an emerging paradigm for data representation in which a signal is interpreted as a function from coordinates to samples:  $I(i_{x,y}) = (R_c, G_c, B_c)$ .

A neural network is then overfitted to this function. If the purpose is to compress data, then the parameters are compressed and transmitted. The signal is therefore reconstructed by inference through the neural network.

• The evaluation of five functions as losses in three SotA INR-based image compression, a paradigm in which the choice of the loss function is fundamental yet nearly unexplored. Results are presented in terms of averaged quantitative results, visual fidelity of specific samples and

A fundamental step when defining an INR pipeline is to choose a proper loss function that represents the distortion between the original signal and the one reconstructed by the network. In the case of images, the most common loss is the L2 mean, also known as Mean Square Error (MSE), and compression distortion is commonly evaluated by using the traditional *Peak Signal-to-Noise Ratio* (PSNR). However, these simple metrics may not match the perceived quality of decoded images,

- appearance of artifacts.
- We examine in depth the potential of adding structural factors in loss functions when training INRs for image compression, proposing recommendations that consistently improve the state-of-the-art in terms of perceptive metrics while maintaining a high PSNR. Also, decoded images benefit reduced artifacts and better visual fidelity.
- The code used for the experiments and the full results are publicly released to the community on GitHub: https://github.com/INRAnalysis-ICIP24.

#### **Network architectures**

NIF [1]: A SIREN architecture which takes positional features as input. COOL-CHIC v1 [2]: A multi-layer perception with ReLU activations which takes latent grid COOL-CHIC v2 [3]: An evolution of [2] which A modulation module alters the period of each activation based on the features as input. The purpose of this architecture is to reduce the decoding complexity of adds convolutional layers to the original arcoordinates of the pixel. Also, the number of features on each layer is the method limiting the amount of the operations needed to decode each pixel. An auto- chitecture and adaptive upsampling instead reduced proportionally to its depth. This technique has been empirically regressive probability model is added to estimate the parameters' distribution and an entropy of fixed one to upsample grid features. proved to enhance the bitrate/distortion ratio. factor is added to the loss function to minimize the parameters' entropy.

#### Methodology

### **Quantitative results**



and MSE for small values, obtaining the best of both worlds.

1.0 1.5 2.0 2.5 3.0 1.0 1.5 2.0 2.5 3.0 1.0 1.5 2.0 2.5 3.0 0.5 0.0 0.5 0.5 0.0 0.0 bits per pixel (bpp) bits per pixel (bpp) bits per pixel (bpp) LPIPS ↓ - COOL-CHICv1 LPIPS ↓ - NIF LPIPS ↓ - COOL-CHICv2 0.3 0.3 0.3 0.2 0.2 0.2 0.1 0.1 0.1 0.0 0.0 -0.01.0 1.5 2.0 2.5 0.5 0.5 1.0 1.5 2.0 2.5 3.0 0.0 0.5 1.0 1.5 2.0 0.0 3.0 0.0 bits per pixel (bpp) bits per pixel (bpp) bits per pixel (bpp) LogCosh+SSIM ---- LogCosh → L1 ----- IPEG ---- LogCosh IPEG → LogCosh → L1+SSIM → L1+SSIM ▲ L1+SSIM LogCosh+SSIM - AVIF 🗕 L1 ---- AVIF

— MSE (Original)

**L1SSIM (L1 + SSIM)**: A combination of L1 and SSIM:

 $L1SSIM(y, \hat{y}) = (1 - \alpha) * L1(y, \hat{y}) + \alpha * (1 - SSIM(y, \hat{y}))$ 

In this case, the  $\alpha$  factor increases the influence of SSIM on the values and decreases the influence of L1

*LcSSIM (LogCosh + SSIM)*: A combination of LogCosh and SSIM [4]:

 $LcSSIM(y, \hat{y}) = Lc(y, \hat{y}) + \alpha * (1 - SSIM(y, \hat{y}))$ 

Where  $\alpha$  is a factor which scales the SSIM, as it is usually much bigger than LogCosh and may dominate the loss value. First proposed in [1], it aids the training process to consider structural information on the image instead of optimizing each point independently

## Visual comparisons

— MSE (Original)





LogCosh+SSIM (Original)

2.5 3.0







CCv2 - L1 0.29bpp, 25.01db 0.31bpp, 27.43db 0.30bpp, 27.50db 0.31bpp, 26.29db 0.34bpp, 25.24db 0.92, 0.32 0.92, 0.33 0.92, 0.31 0.94, 0.22 0.94, 0.23



NIF - LogCosh NIF - Lc+SSIM NIF - L1+SSIM NIF - MSE 0.33bpp, 25.38db 0.32bpp, 24.07db 0.32bpp, 24.19db 0.33bpp, 25.62db 0.32bpp, 25.55db 0.91, 0.39 0.88, 0.39 0.88.0.39 0.90, 0.38 0.92, 0.39

CCv2 - L1 CCv2 - MSE CCv2 - LogCosh CCv2 - Lc+SSIM CCv2 - L1+SSIM 0.30bpp, 25.28db 0.29bpp, 26.59db 0.32bpp, 26.85db 0.33bpp, 26.54db 0.29bpp, 24.87db 0.91, 0.29



NIF - L1+SSIM NIF - LogCosh NIF - Lc+SSIM NIF - L1 NIF - MSE 0.32bpp, 24.88db 0.33bpp, 25.45db 0.33bpp, 25.42db 0.33bpp, 25.31db 0.33bpp, 24.39db 0.90, 0.27 0.91, 0.24 0.91, 0.24 0.92, 0.23 0.92, 0.25



CCv2 - MSE CCv2 - L1 CCv2 - LogCosh CCv2 - Lc+SSIM CCv2 - L1+SSIM 0.34bpp, 23.58db 0.31bpp, 24.59db 0.33bpp, 23.67db 0.37bpp, 25.04db 0.31bpp, 22.64db 0.92, 0.31 0.93, 0.27 0.92, 0.29 0.95, 0.21 0.93, 0.27



NIF - MSE NIF - L1 NIF - LogCosh NIF - Lc+SSIM NIF - L1+SSIM 0.32bpp, 21.94db 0.32bpp, 22.56db 0.32bpp, 22.51db 0.32bpp, 22.45db 0.32bpp, 21.72db 0.90, 0.35 0.89, 0.33 0.89, 0.33 0.90, 0.32 0.91, 0.32

Contraction)-				
GT, #5, 768×512	CCv1 - MSE	CCv2 - MSE	CCv1 - Lc+SSIM	CCv2 - Lc+SSIM
bpp, PSNR	0.58bpp, 26.95db	0.55bpp, 28.07db	0.38bpp, 24.78db	0.41bpp, 26.20db
MS-SSIM, LPIPS	0.95, 0.15	0.96, 0.12	0.94, 0.19	0.96, 0.13
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GT, #18, 512×768	CCv1 - MSE	CCv2 - MSE	CCv1 - Lc+SSIM	CCv2 - Lc+SSIM
bpp, PSNR	0.33bpp, 27.06db	0.37bpp, 28.08db	0.19bpp, 24.44db	0.30bpp, 26.63db
MS-SSIM, LPIPS	0.92, 0.32	0.93, 0.29	0.90, 0.38	0.94, 0.26
Original	MSE (Original)		Lc+SSIM (Suggested)	

#### References

- [1] Lorenzo Catania and Dario Allegra. NIF: a fast implicit image compression with bottleneck layers and modulated sinusoidal activations. In ACM International Conference on Multimedia, 2023.
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- [4] Zhou Wang, A.C. Bovik, H.R. Sheikh, and E.P. Simoncelli. Image quality assessment: from error visibility to structural similarity. IEEE Transactions on Image Processing, 2004.