



LCMV Beamforming with Subspace Projection for Multi-Speaker Speech Enhancement

Amin Hassani, Alexander Bertrand, Marc Moonen

KU Leuven, Dept. of Electrical Engineering-ESAT
ICASSP 2016

ICASSP 2016
March 20-25, 2016
Shanghai, China

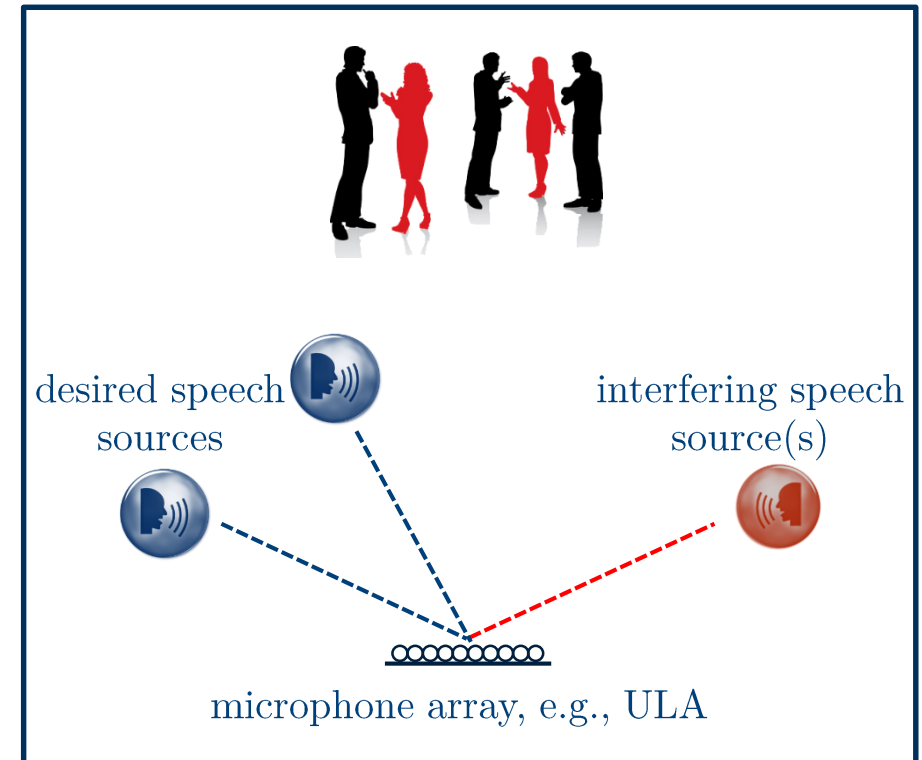


Presentation outline

- Motivation and Problem Statement
- LCMV Beamformer
- Proposed Subspace Projection-based Approach
- Simulation Results
- Conclusion

Motivation

- Microphone arrays for audio and speech enhancement
- **Problem:** extracting desired speech signals from microphone signals, polluted by other interfering speech signals and noise components
- **Approach:** Linearly Constrained Minimum Variance (LCMV) beamformer
- **Main Goal:** using subspace projection-based approach to improve the performance of the LCMV beamformer when insufficient relevant samples are available



LCMV beamformer (1/2)

- Data model of microphone signals (STFT):
 - \mathbf{y} : contains M microphone signals
 - \mathbf{s}_d : contains N_d desired speech sources
 - \mathbf{s}_i : contains N_i interfering speech sources
 - \mathbf{A}_d : $M \times N_d$ desired steering matrix
 - \mathbf{A}_i : $M \times N_i$ interfering steering matrix
- LCMV minimizes the total **output variance**, under a set of linear constraints (generalization of Minimum Variance Distortionless Response (MVDR)):

$$\mathbf{y} = \mathbf{A}_d \mathbf{s}_d + \mathbf{A}_i \mathbf{s}_i + \mathbf{n}$$
$$\triangleq \mathbf{d} + \mathbf{i} + \mathbf{n}$$

$$\min_{\mathbf{w}} E\{|\mathbf{w}^H \mathbf{y}|^2\}$$
$$\text{s.t. } \mathbf{A}^H \mathbf{w} = \mathbf{f}$$

$$\mathbf{w} = \mathbf{R}_{yy}^{-1} \mathbf{A} (\mathbf{A}^H \mathbf{R}_{yy}^{-1} \mathbf{A})^{-1} \mathbf{f}$$

$$\bar{d} = \mathbf{w}^H \mathbf{y}$$

$$\mathbf{A} = [\mathbf{A}_d \quad \mathbf{A}_i]$$
$$\mathbf{f} = [\underbrace{1 \dots 1}_{N_d} \quad \underbrace{0 \dots 0}_{N_i}]^T \text{ is the vector of desired responses}$$

LCMV beamformer (2/2)

- Two main classes of LCMV beamformer:
 - I. All Acoustic Transfer Functions (ATFs) are known → LCMV output contains mixture of desired source signals (mixture of *dry* speech signals)
 - II. Unknown ATFs: ‘*blind beamforming*’ requires subspace estimation → LCMV output contains mixture of the desired source signals as observed by a *reference microphone* (mixture of *wet* speech signals)
- If ATFs (class I) or subspaces (class II) are not accurately estimated, the LCMV beamformer that minimizes the *output variance* delivers severe speech distortion [1]

Blind LCMV beamformer (1/2)

- ‘*desired-sources-only*’ correlation matrix: $\mathbf{R}_{yy}^d = \mathbf{A}_d \mathbf{\Pi}_d \mathbf{A}_d^H + \mathbf{R}_{nn}$
- ‘*interfering-sources-only*’ correlation matrix: $\mathbf{R}_{yy}^i = \mathbf{A}_i \mathbf{\Pi}_i \mathbf{A}_i^H + \mathbf{R}_{nn}$
- ‘*noise-only*’ correlation matrix: \mathbf{R}_{nn}
- Estimating \mathbf{R}_{yy}^d and \mathbf{R}_{yy}^i via sample averaging (e.g., as in [2])
- Subspace estimation via **Generalized EigenValue Decomposition (GEVD)**:
better suited for scenarios with spatially correlated (e.g., localize noise sources)
and/or nonstationary noise (e.g., interfering speakers)

Blind LCMV beamformer (2/2)

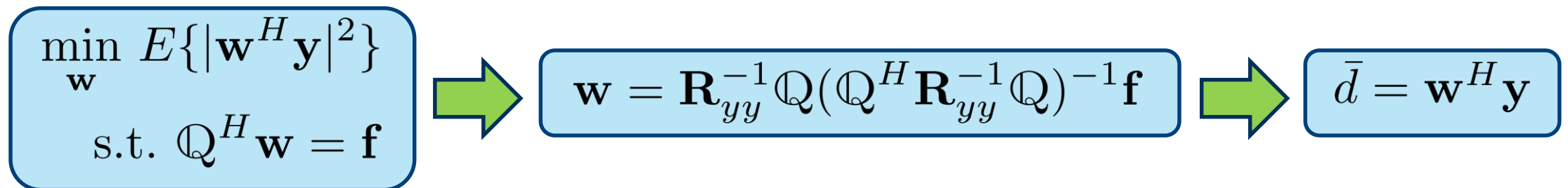
- Compute \mathbf{Q}_d : $M \times N_d$ subspace of desired speech

$$\text{GEVD} (\mathbf{R}_{yy}^d, \mathbf{R}_{nn}) \Rightarrow \mathbf{Q}_d$$

- Compute \mathbf{Q}_i : $M \times N_i$ subspace of interfering speech

$$\text{GEVD} (\mathbf{R}_{yy}^i, \mathbf{R}_{nn}) \Rightarrow \mathbf{Q}_i$$

- With modified constrain set $\mathbf{Q} \triangleq [\mathbf{Q}_d \ \mathbf{Q}_i]$, LCMV becomes [2]



$$\mathbf{f} = [\mathbf{q}_d^T \ \underbrace{0 \dots 0}_{N_i}]^T, \mathbf{q}_d \text{ is the } r\text{-th (reference) column of } \mathbf{Q}_d^H$$

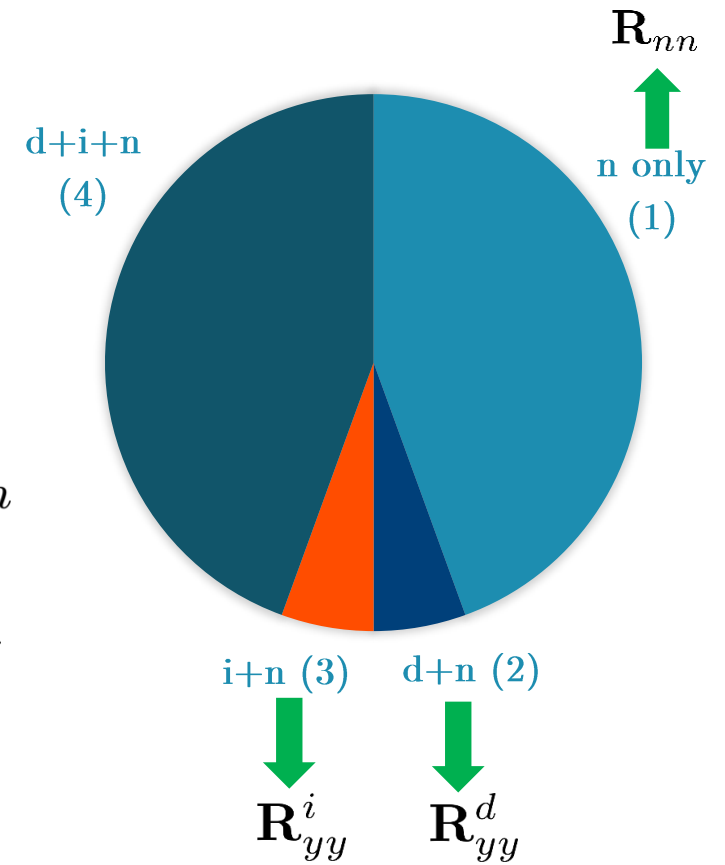
LCMV Beamforming with Subspace Projection

- The estimation of \mathbf{Q}_d and \mathbf{Q}_i may yield poor results when insufficient available '*desired-sources-only*' and/or '*interfering-sources-only*' samples
- '*desired+interfering*' segments were not exploited for the estimation of \mathbf{Q}_d and \mathbf{Q}_i
- Only excluding the samples of '*noise-only*' segments

$$\mathbf{R}_{yy}^{d,i} = \mathbf{A}_d \mathbf{\Pi}_d \mathbf{A}_d^H + \mathbf{A}_i \mathbf{\Pi}_i \mathbf{A}_i^H + \mathbf{R}_{nn}$$

- Compute $\mathbf{Q}_{d,i}$: $M \times (N_d + N_i)$ joint subspace of desired and interfering speech

$$\text{GEVD} (\mathbf{R}_{yy}^{d,i}, \mathbf{R}_{nn}) \Rightarrow \mathbf{Q}_{d,i}$$



LCMV Beamforming with Subspace Projection

- In theory: $\text{Col} (\mathbf{Q}_{d,i}) = \text{Col} ([\mathbf{Q}_d \ \mathbf{Q}_i])$
- In practice: $\text{Col} (\mathbf{Q}_{d,i}) \neq \text{Col} ([\mathbf{Q}_d \ \mathbf{Q}_i])$ due to different data segments

- Correction via projection:

$$\mathbf{Q}_d^{\text{proj}} \triangleq \mathbf{Q}_{d,i} (\mathbf{Q}_{d,i}^T \mathbf{Q}_{d,i})^{-1} \mathbf{Q}_{d,i}^T \mathbf{Q}_d$$

$$\mathbf{Q}_i^{\text{proj}} \triangleq \mathbf{Q}_{d,i} (\mathbf{Q}_{d,i}^T \mathbf{Q}_{d,i})^{-1} \mathbf{Q}_{d,i}^T \mathbf{Q}_i$$

- We define the new constraint matrix $\mathbf{Q}_{\text{proj}} \triangleq [\mathbf{Q}_d^{\text{proj}} \ \mathbf{Q}_i^{\text{proj}}]$:

$$\mathbf{w}_{\text{proj}} = (\mathbf{R}_{yy}^{d,i})^{-1} \mathbf{Q}_{\text{proj}} (\mathbf{Q}_{\text{proj}}^H (\mathbf{R}_{yy}^{d,i})^{-1} \mathbf{Q}_{\text{proj}})^{-1} \mathbf{f}_{\text{proj}} \quad \longrightarrow \quad \bar{d}_{\text{proj}} = \mathbf{w}_{\text{proj}}^H \mathbf{y}$$

$$\mathbf{f}_{\text{proj}} = [(\mathbf{Q}_d^{\text{proj}})^T \underbrace{0 \dots 0}_{N_i}]^T, \quad (\mathbf{Q}_d^{\text{proj}}) \text{ is the } r\text{-th (reference) column of } (\mathbf{Q}_d^{\text{proj}})^H$$

Simulations

- Two scenarios:
 - I. Monte Carlo (MC) simulations with narrowband source signals (multiple desired + multiple interfering sources)
 - II. multi-talker speech enhancement in a simulated cubic room
- Performance measure 1: output Signal to Interference plus Noise Ratio (oSINR):

$$\text{oSINR} = 10 \log_{10} \frac{E\{|\mathbf{w}^H \mathbf{d}|^2\}}{E\{|\mathbf{w}^H \mathbf{i}|^2\} + E\{|\mathbf{w}^H \mathbf{n}|^2\}}$$

- Performance measure 2: output Signal to Distortion Ratio (oSDR):

$$\text{oSDR} = 10 \log_{10} \frac{E\{|d_{\text{ref}}|^2\}}{E\{|d_{\text{ref}} - \mathbf{w}^H \mathbf{d}|^2\}}$$

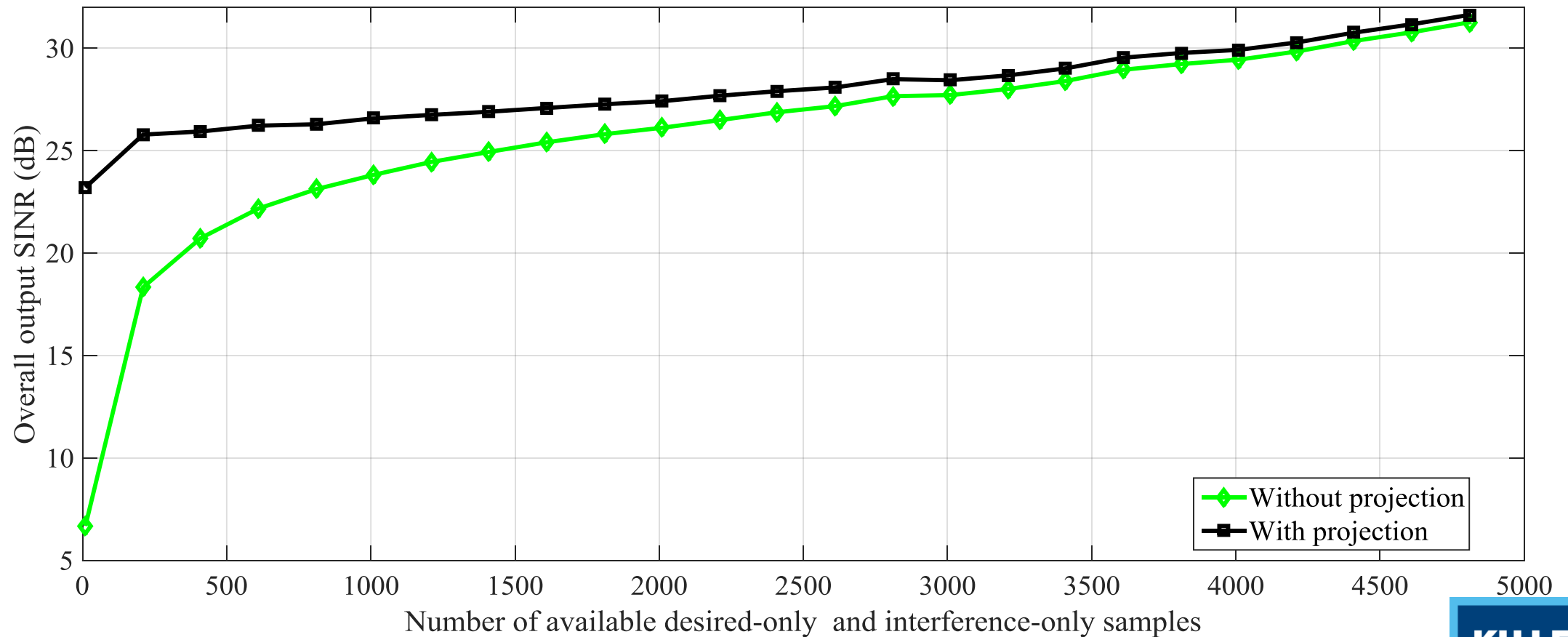
Narrowband simulations (MC=1000)

$M = 10$, $N_d = 2$ (power P), $N_i = 3$ (power P), 2 localized noise (power $0.5P$)

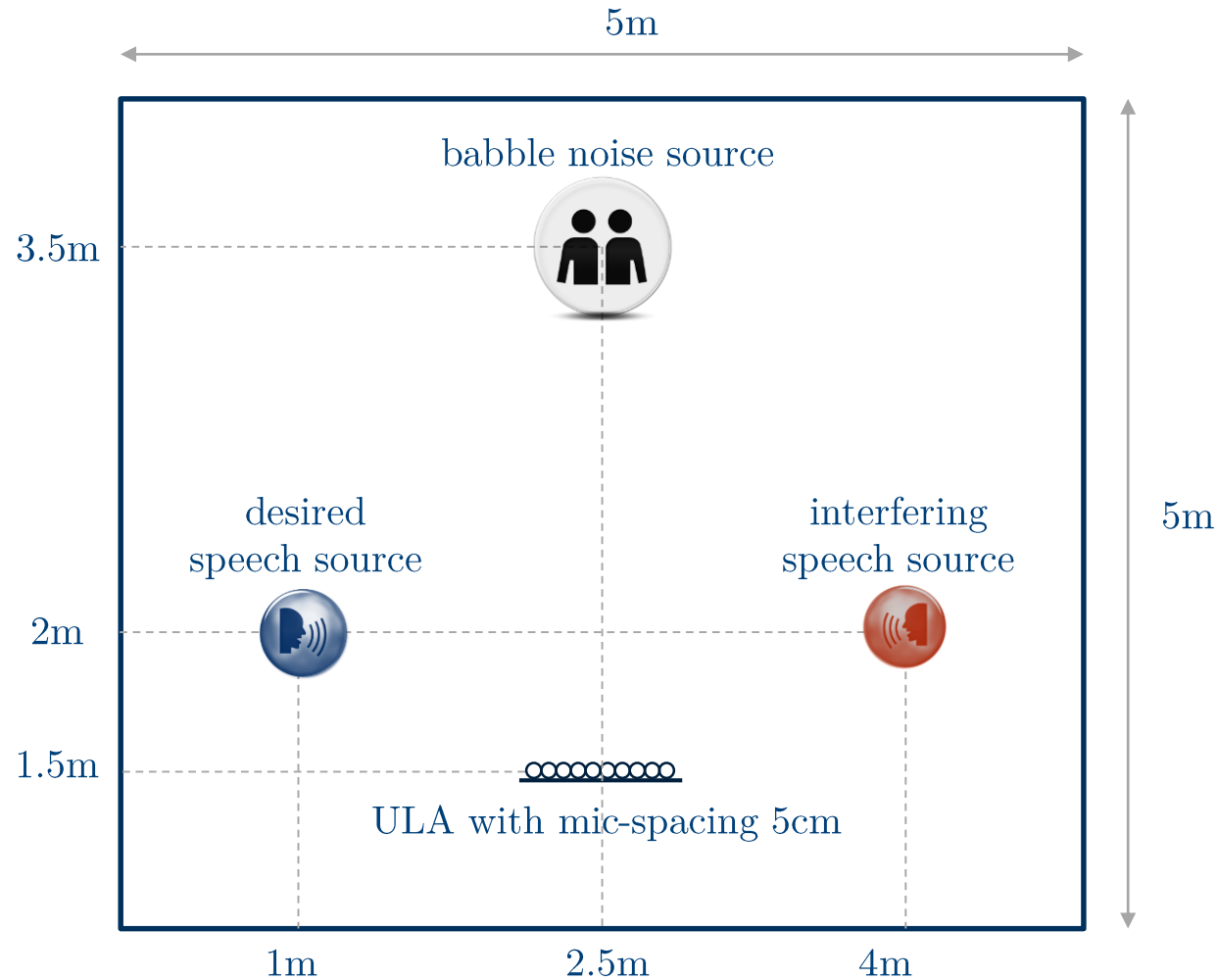
total # of samples = 20000

of samples in which both desired and interfering sources are active = 7000

increasing $N_{b_{\text{only}}}$ (number of desired/interfering-only samples)



Multi-talker speech simulations



$$M = 10$$

$$F_s = 16kHz, \text{DFTsize} = 512$$

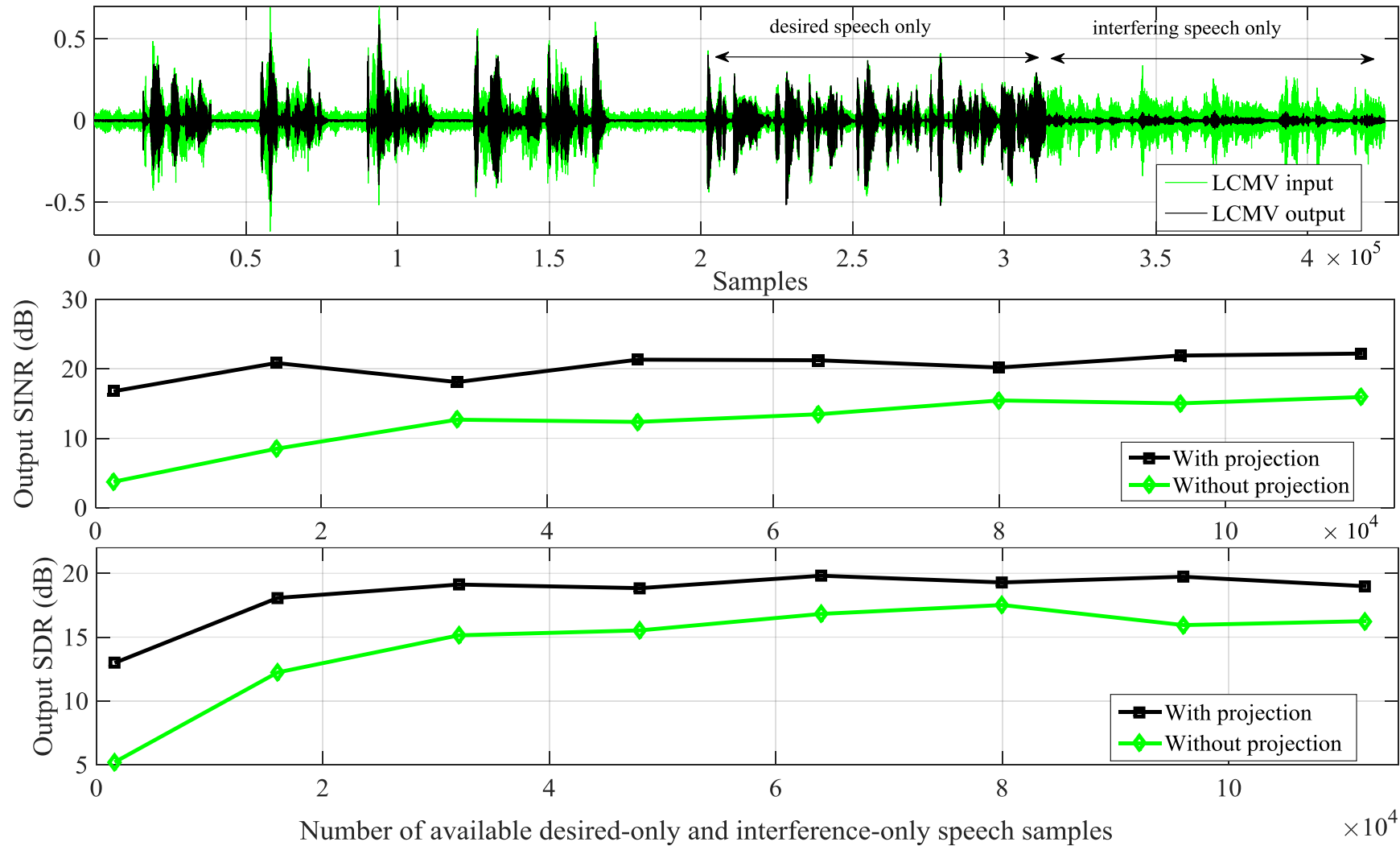
desired and interfering sources power $P_s = P_i$

babble noise power $0.5P_s$

AWGN with 5% of power of speech at the ref mic

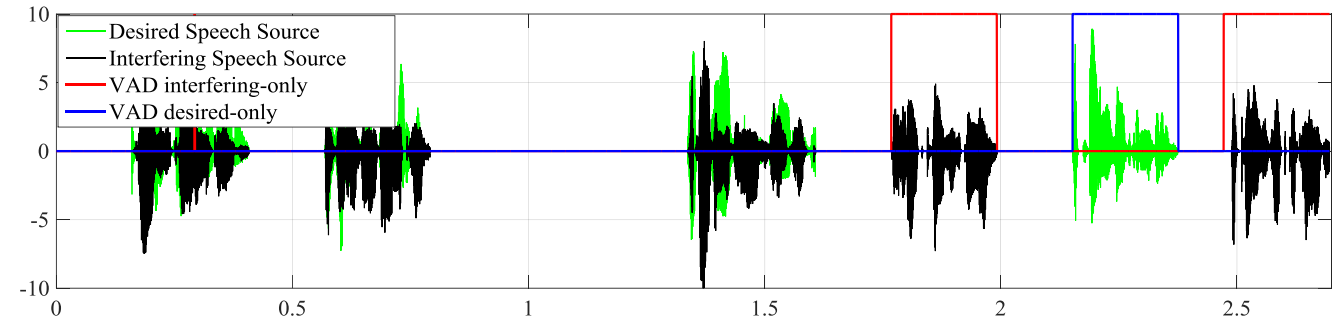
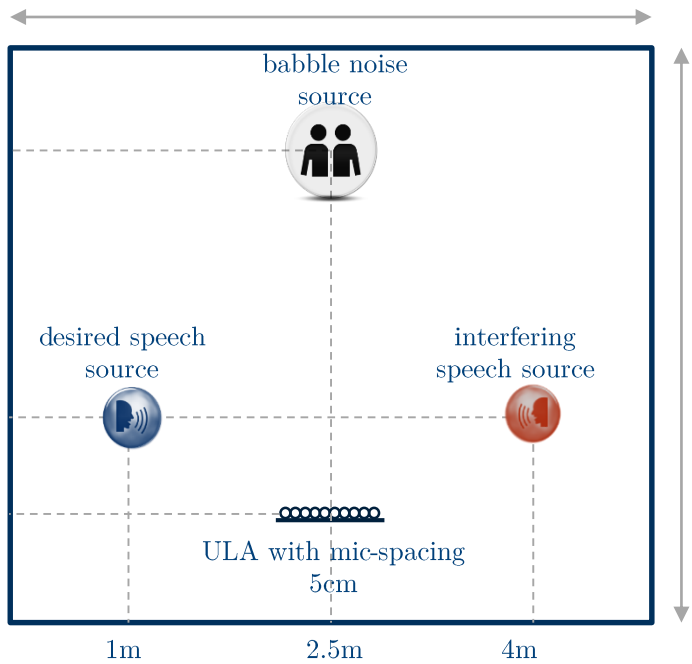
RIR-generator, image method [3]

increasing Nb_{only} from $0.1F_s$ to $7F_s$

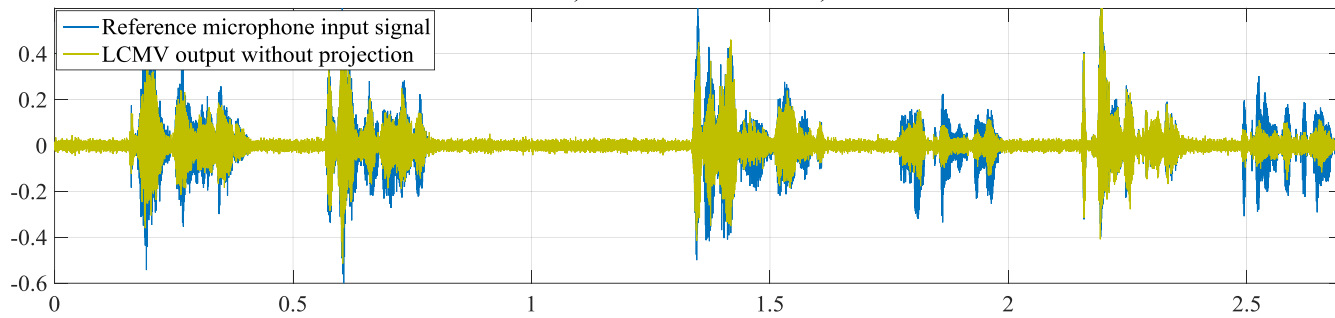


Audio demonstrations

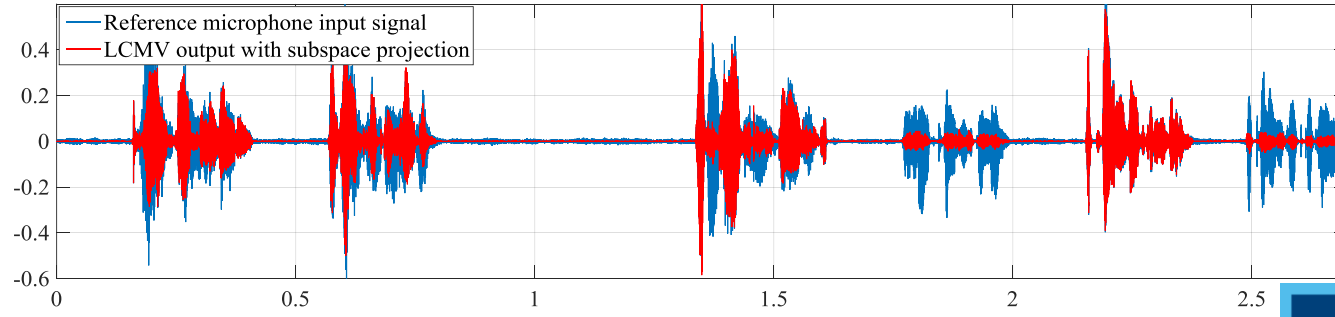
(batch-processing)



$SNR_i = 23.3104$, $SIR_i = 1.9237$, $SINR_i = 1.8923$
 $SNR_{o.without} = 10.4377$, $SIR_{o.without} = 7.4166$, $SINR_{o.without} = 5.6593$



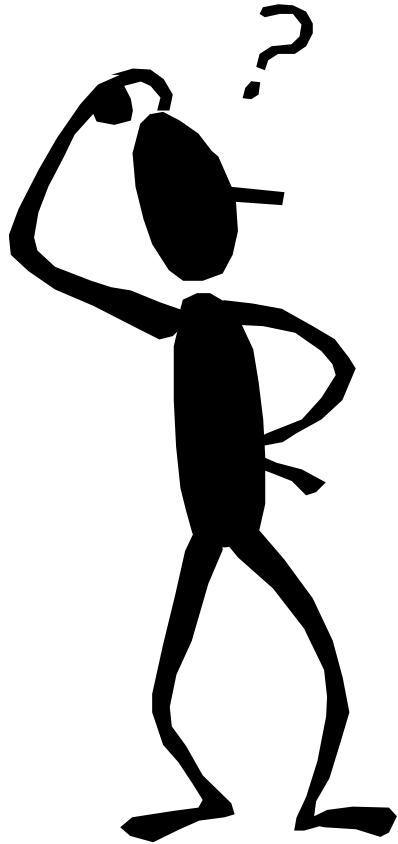
$SNR_i = 23.3104$, $SIR_i = 1.9237$, $SINR_i = 1.8923$
 $SNR_{o.with} = 31.9807$, $SIR_{o.with} = 11.5713$, $SINR_{o.with} = 11.5319$



Conclusions

- We have proposed a **subspace projection-based** approach when **insufficient relevant samples** are available
- GEVD-based approach has been considered (better subspace estimation performance)
- Improvement is achieved at the cost of **more complex computations**, as the poorly estimated subspaces **have to be projected onto the larger joint subspace**
→ extra GEVD

Thank you for your attention.



Discussion ...