

# Co-segmentation of Non-homogeneous Image Sets

ICIP 2018

by

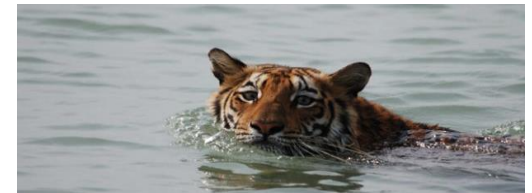
Avik Hati, **Subhasis Chaudhuri**, Rajbabu Velmurugan



Electrical Engineering Department, Indian Institute of Technology Bombay

# Image Co-segmentation

- Find co-occurring objects in a set of crowd-sourced images
  - similar feature matching
- Process multiple images simultaneously
  - Common object detected, not recognized



Images from internet

# Applications

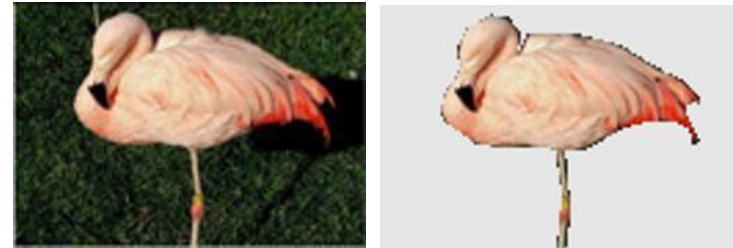
- Semi-supervised image foreground segmentation
  - Ground-truth annotation

- Image similarity measure



- Object classification

Co-segmentation output



Input image



Objects

Image courtesy: Image pair dataset [Li *et al.*, 2011]

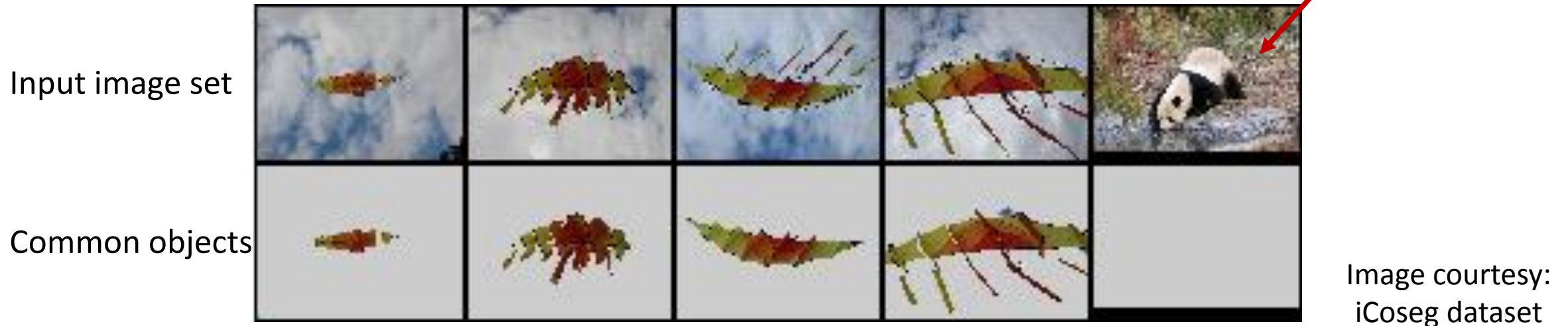
Image courtesy: MSRC dataset

# Existing works

- Supervised approaches
  - use scribbles
- Markov random field model based approaches
  - extension of single image segmentation
- Saliency based approaches
  - initialization

# Problem definition

- Co-segmentation of a large number ( $N$ ) of images
- Non-homogeneous image set
  - Common object(s) present only in  $M \leq N$  images



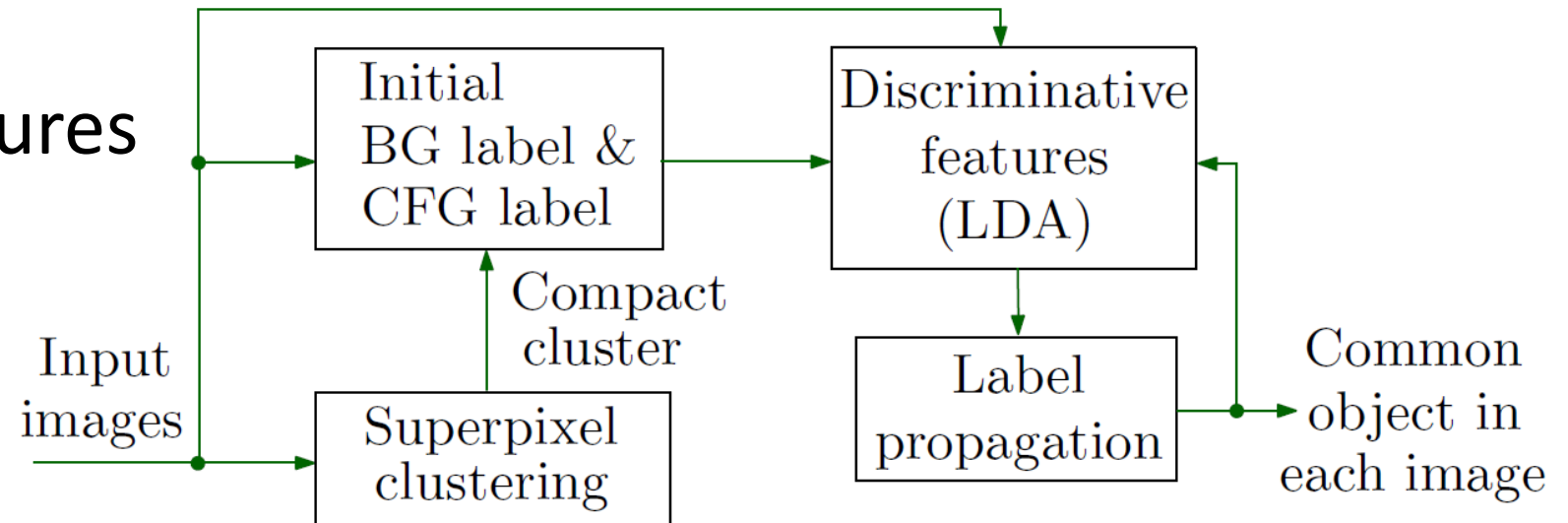
# Proposed solution

- Low-level features
  - Mean Lab color
  - SIFT
- Mid-level features
  - Bag-of-words
- Discriminative features
  - LDA
- Assign labels

SLIC superpixel segmentation



Image courtesy:  
Oxford flower  
dataset



# Common foreground seeds

- Superpixel clustering
- Average *spatial compactness* of every cluster- $j$

$$\Gamma_j = \left( \sum_{i=1}^N \frac{\sigma_{ij}^2}{A_{ij}} \right)^{-1}$$

← SP spatial variance

← SP area

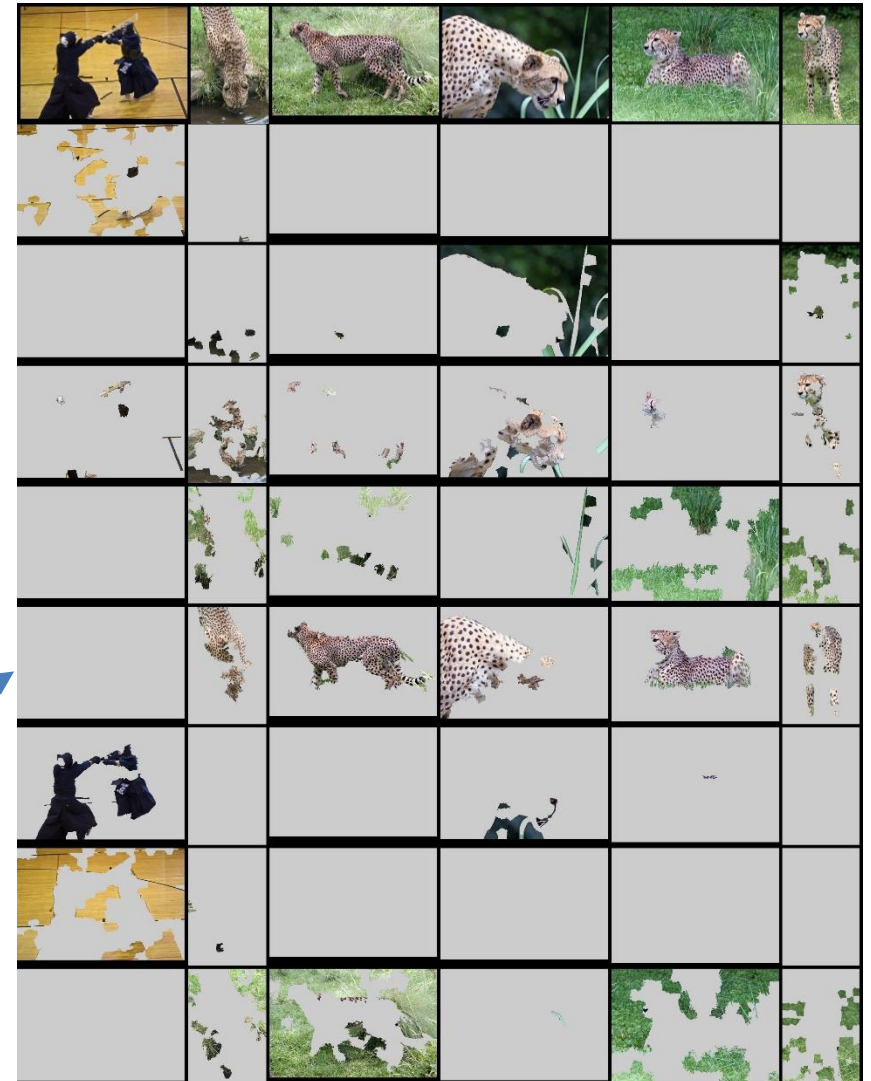
– highest compactness

$$p = \arg \max_j \Gamma_j$$

$$C_F = \{s \in \text{cluster-}p\}$$

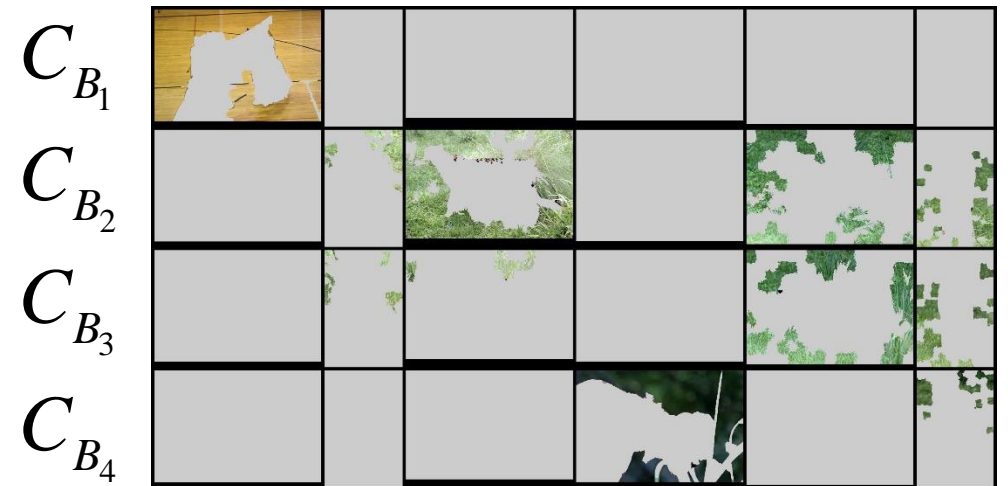
Cluster of interest

Image courtesy:  
iCoseg dataset



# Background seeds

- Background probability of every superpixel [Zhu *et al.*, CVPR 2014]
- Choose superpixels  $\{\mathbf{s} : P(\mathbf{s}) > 0.99\}$ 
  - Less false positives
- Clustering
- Common and different background



W. Zhu, S. Liang, Y. Wei and J. Sun, "Saliency Optimization from Robust Background Detection," *IEEE Conference on Computer Vision and Pattern Recognition*, 2014, pp. 2814-2821.

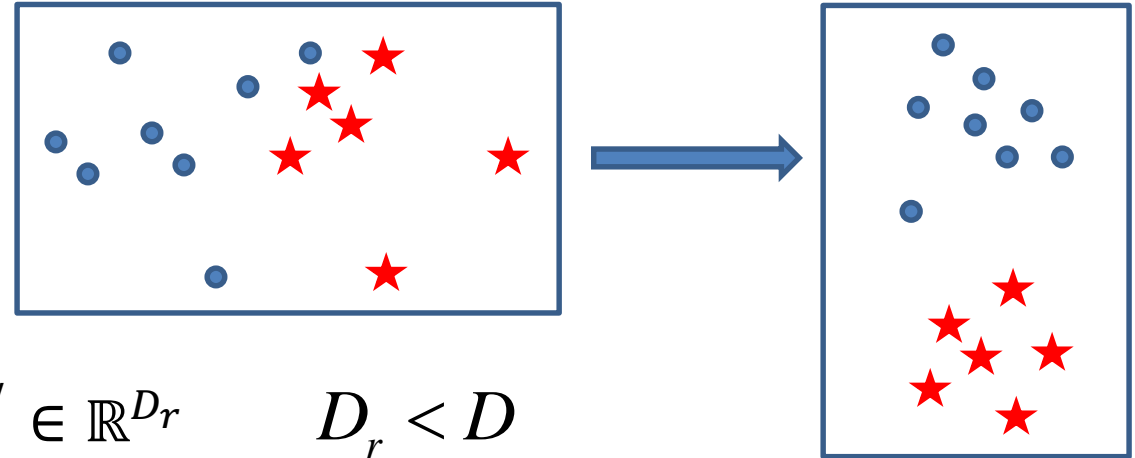


# Discriminative feature (1/2)

- Feature vector  $\mathbf{f} \in \mathbb{R}^D$

- Projection  $\mathbf{W} = [\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_{D_r}]$

– smaller dimension  $\mathbf{W}^T \mathbf{f} = \mathbf{f}' \in \mathbb{R}^{D_r} \quad D_r < D$



- Feature points in same class are closer in projected domain
- Use linear discriminant analysis

LDA: Bishop, 2006

# Discriminative feature (2/2)

- Between-class variance

$$\mathbf{V}_b = \sum_{i=1}^K \frac{n_i}{n_a} (\mathbf{m}_i - \bar{\mathbf{m}})(\mathbf{m}_i - \bar{\mathbf{m}})^T$$

- Within-class variance  $\mathbf{V}_w = \sum_{i=1}^K \frac{n_i}{n_a} \mathbf{V}_i$

- $\mathbf{W}$  = Eigenvectors of  $\mathbf{V}_w^{-1} \mathbf{V}_b$

$K$  : # of clusters

$n_i$  : class cardinality

$n_a$  : total # of superpixels

$\mathbf{m}_i$  : class mean

$\bar{\mathbf{m}}$  : all class mean

# Label propagation (1/2)

- Seed superpixels labels
- Find Label matrix  $\mathbf{L}$  containing label of all superpixels

$$\mathbf{Y} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}_{n_a \times K}$$

$\mathbf{s}_1 \in C_{B_2}$   
 $\mathbf{s}_2$   
 $\mathbf{s}_3 \in C_F$   
 $\mathbf{s}_4 \in C_{B_1}$   
 $\mathbf{s}_5$  Seed superpixels colored

$C_F$     $C_{B_1}$     $C_{B_2}$

similarity matrix

- Minimize  $\mathbf{L}$   $\sum_{i,j=1}^{n_a} \mathbf{S}_{ij} \left\| \frac{1}{\sqrt{\mathbf{D}_{ii}}} \mathbf{L}_i - \frac{1}{\sqrt{\mathbf{D}_{jj}}} \mathbf{L}_j \right\|^2 + \alpha \sum_{i=1}^{n_a} \|\mathbf{L}_i - \mathbf{Y}_i\|^2$   $\mathbf{D}$  : Diagonal matrix

D. Zhou, O. Bousquet, T. N. Lal, J. Weston, and B. Schölkopf. "Learning with local and global consistency." In *Advances in neural information processing systems*, pp. 321-328. 2004.

# Label propagation (1/2)

- Solution

$$\mathbf{L}^* = \beta_1 (\mathbf{I} - \beta_2 \mathbf{D}^{-1/2} \mathbf{S} \mathbf{D}^{-1/2})^{-1} \mathbf{Y}$$

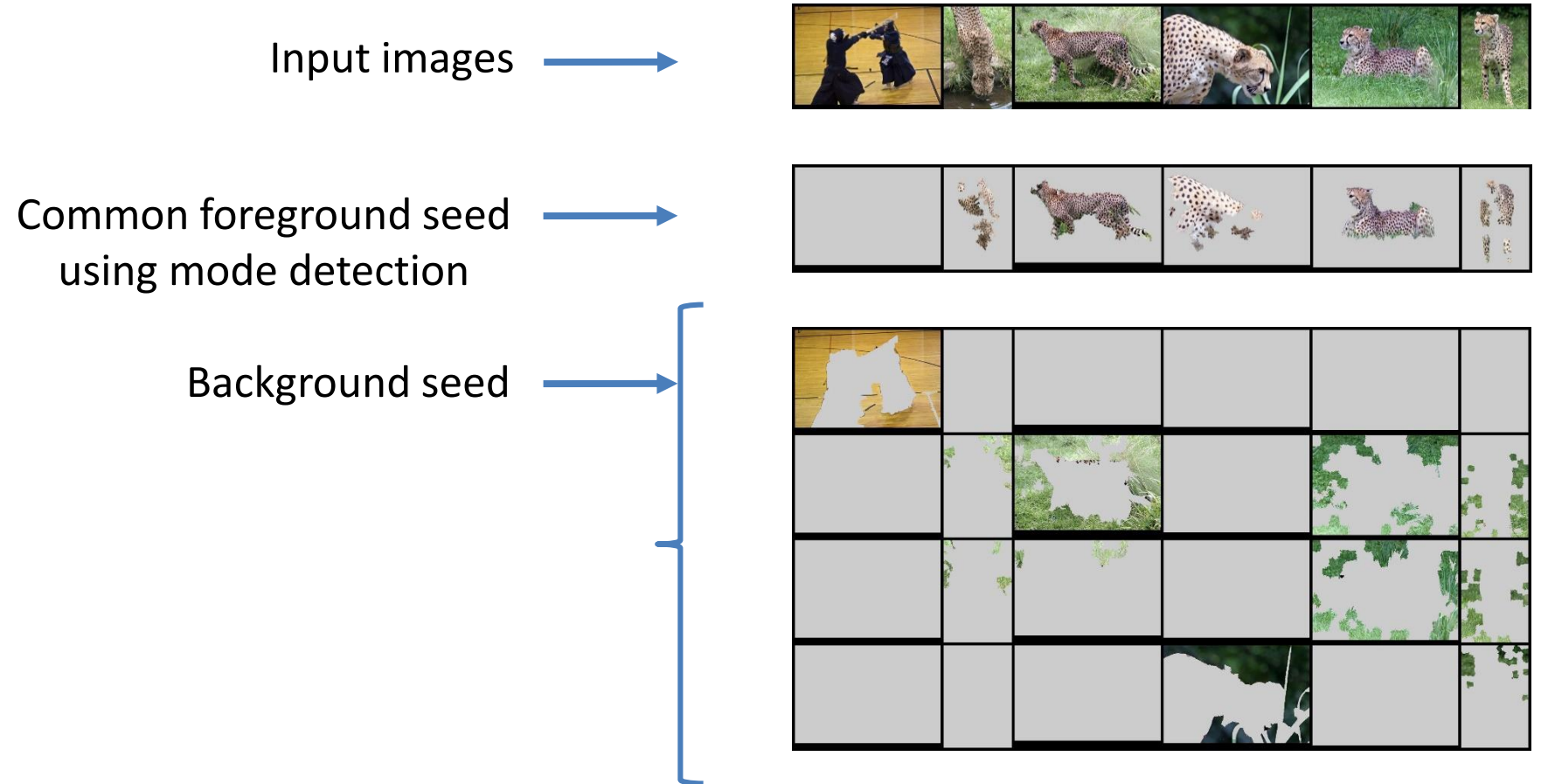
- Label assignment

$$\text{label}(\mathbf{s}_i) = \arg \max_j \mathbf{L}_{ij}^*$$

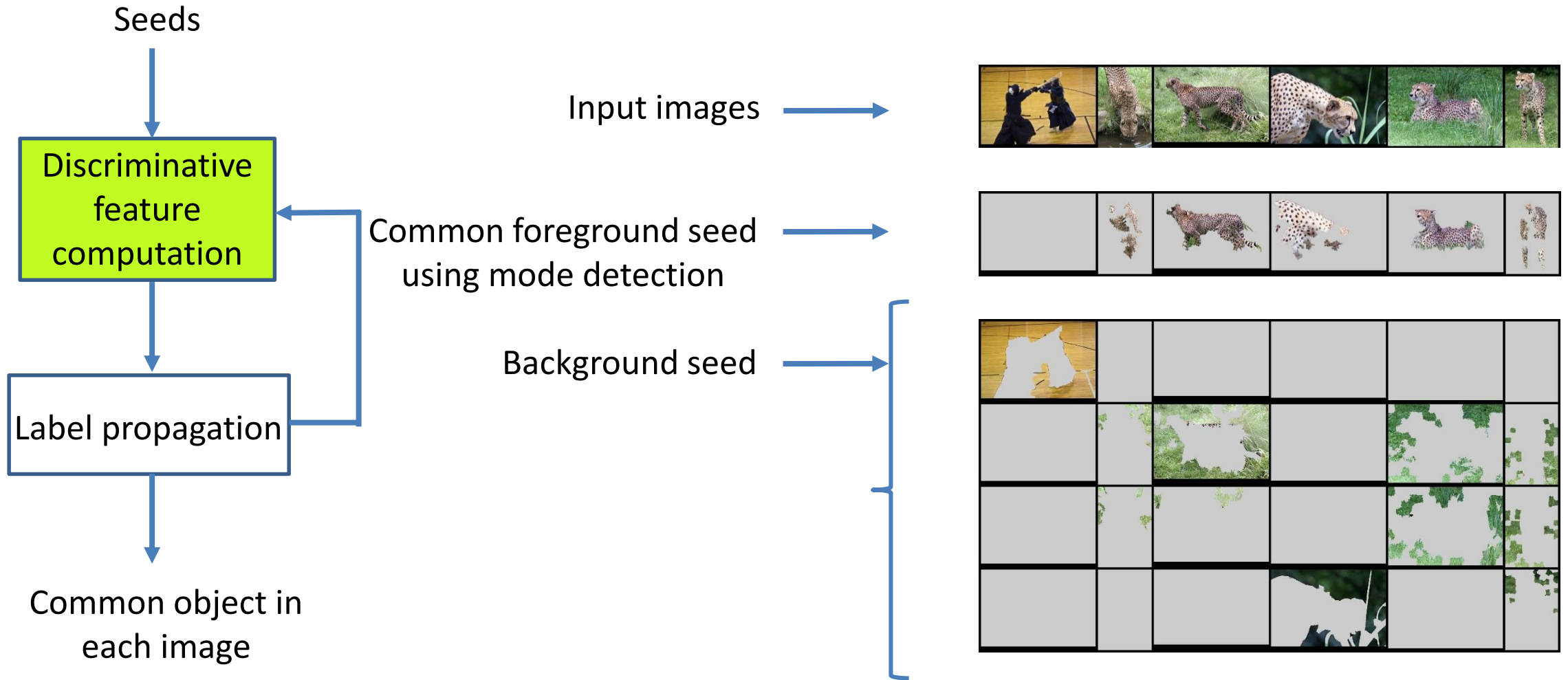
with spatial constraint



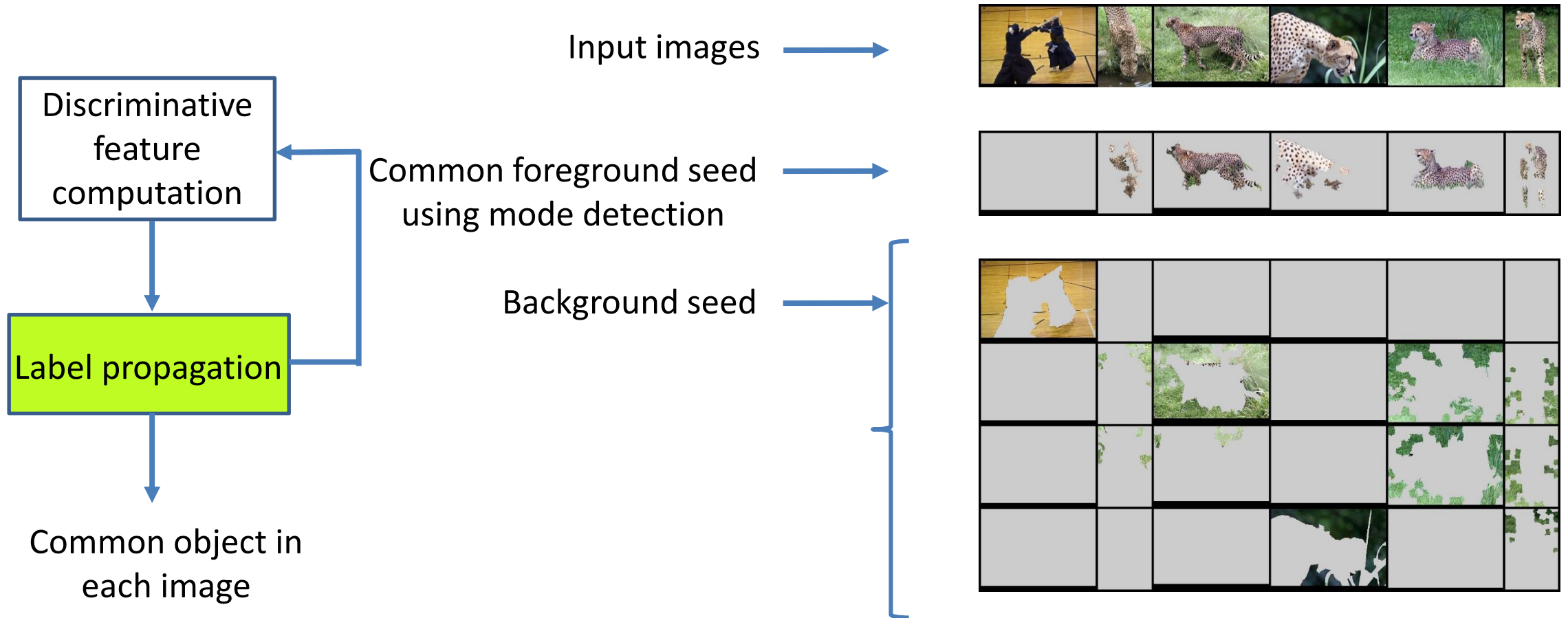
# Proposed method



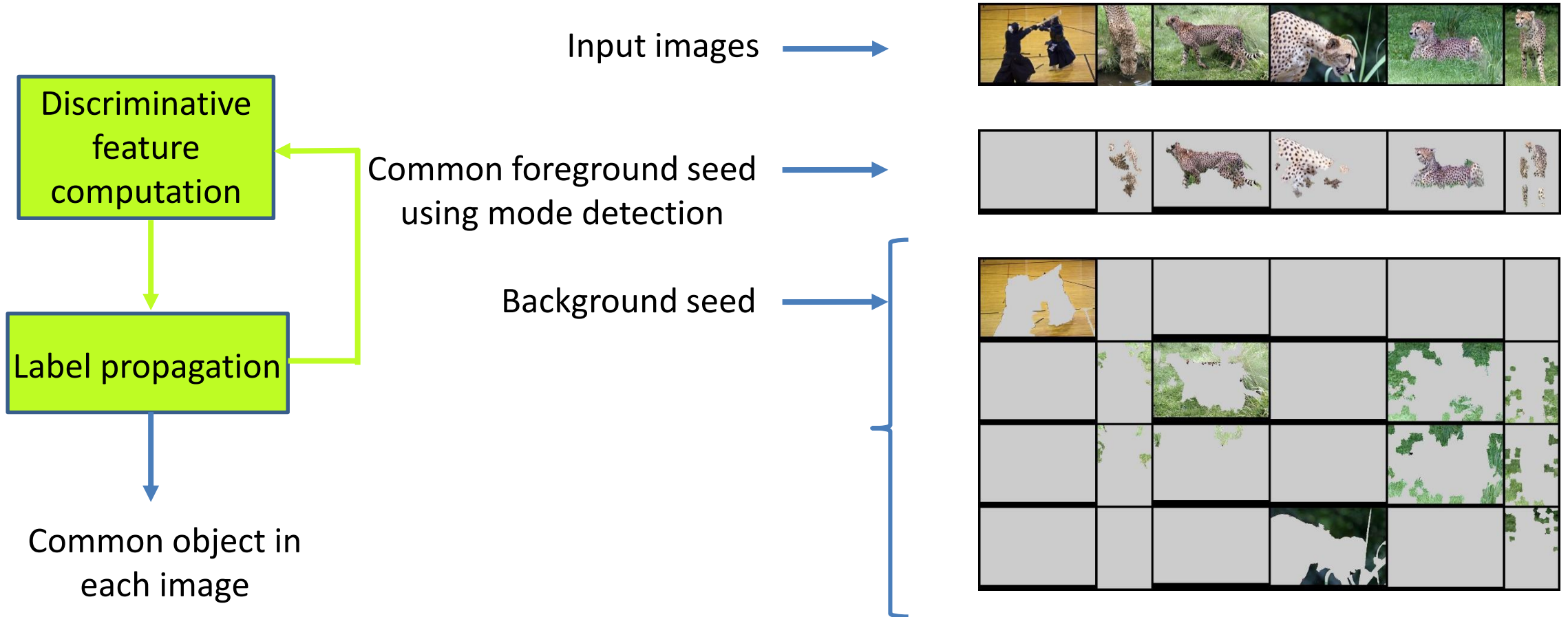
# Proposed method



# Proposed method

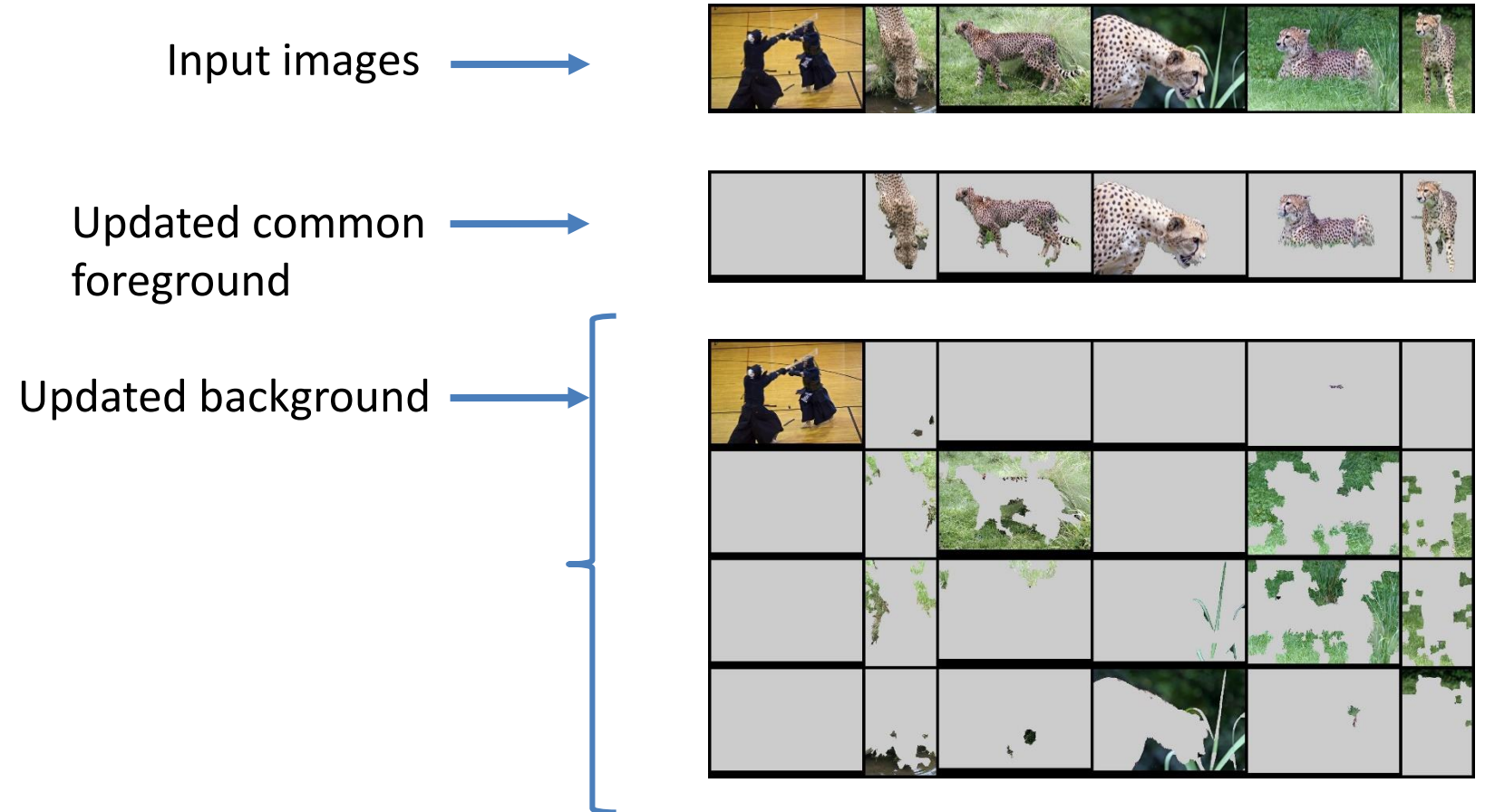
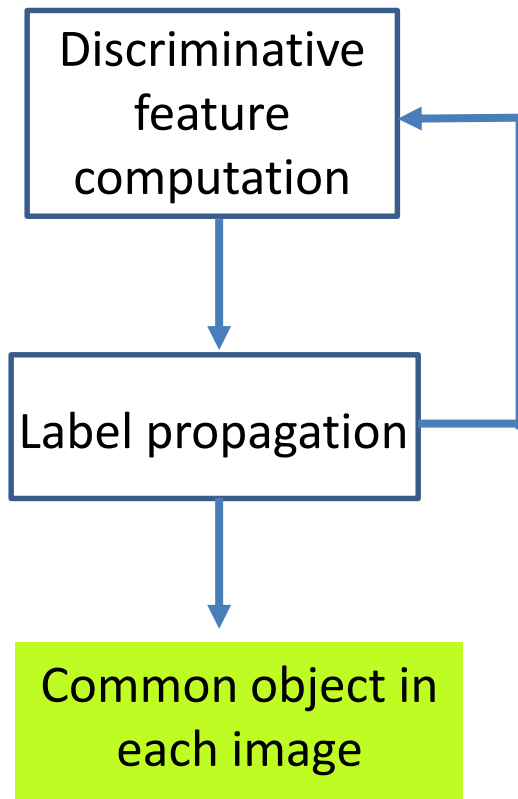


# Proposed method





# Proposed method



# Visual comparison

Input images

Rubinstein *et al.*, CVPR 2013

Joulin *et al.*, CVPR 2012

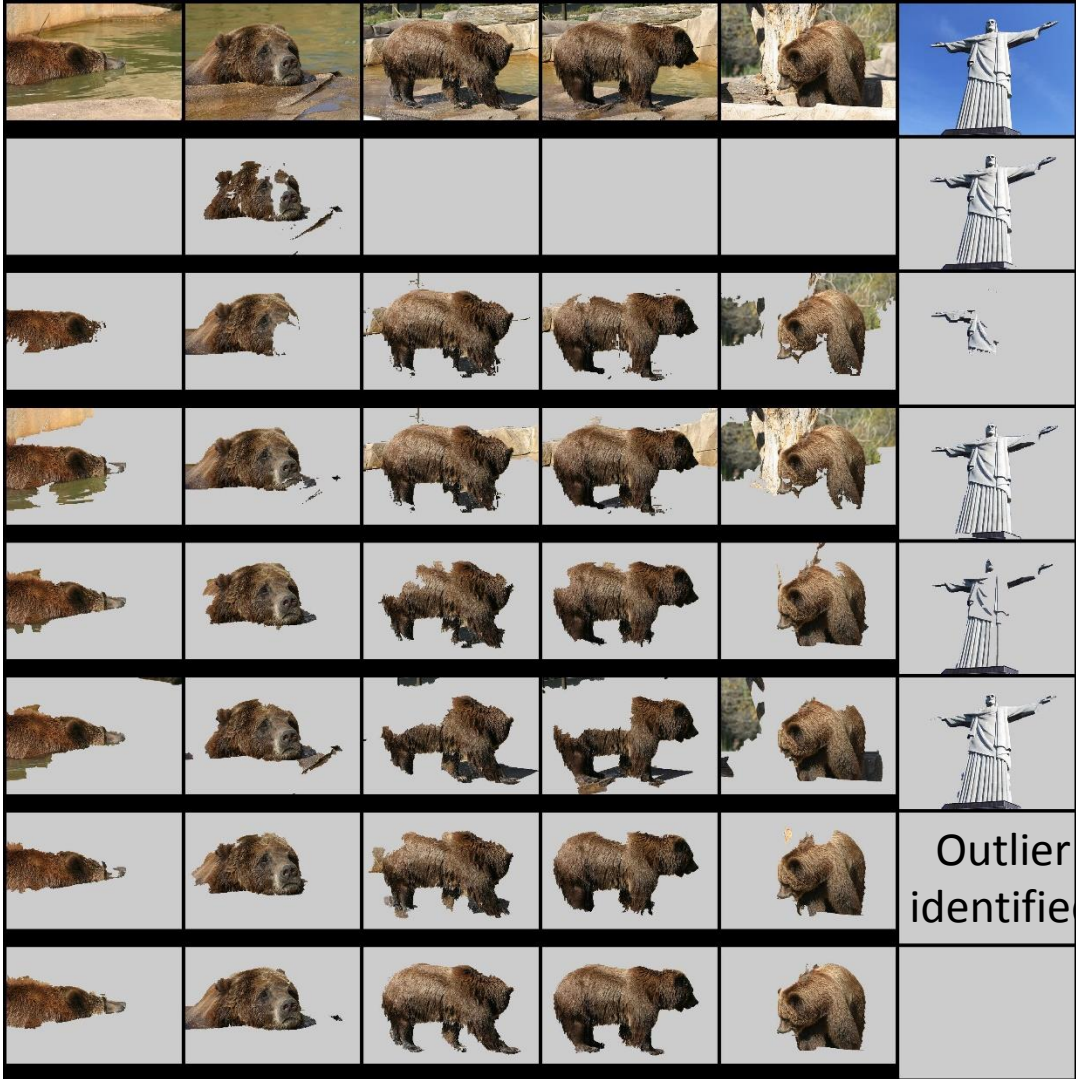
Joulin *et al.*, CVPR 2010

Lee *et al.*, CVPR 2015

Chang *et al.*, CVIU 2015

**Proposed method**

Ground-truth



Outlier identified

Image courtesy: iCoseg dataset

# Visual comparison

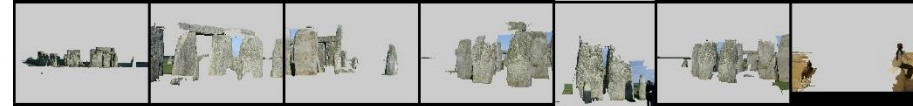
Input images



Rubinstein *et al.*, CVPR 2013



Joulin *et al.*, CVPR 2012



Joulin *et al.*, CVPR 2010



Lee *et al.*, CVPR 2015



Chang *et al.*, CVIU 2015



**Proposed method**



Ground-truth

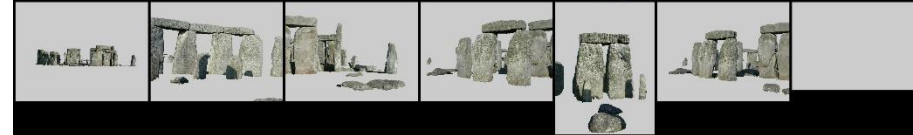


Image courtesy:  
iCoseg dataset

# Visual comparison

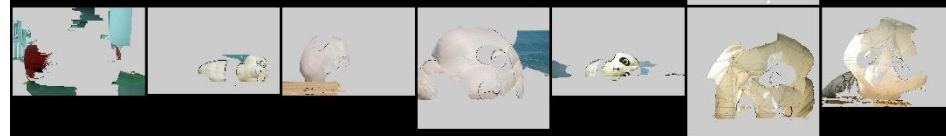
Input images



Rubinstein *et al.*, CVPR 2013



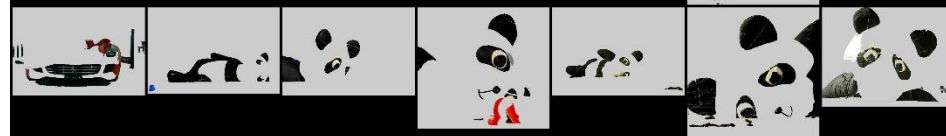
Joulin *et al.*, CVPR 2012



Joulin *et al.*, CVPR 2010



Lee *et al.*, CVPR 2015



Chang *et al.*, CVIU 2015



**Proposed method**

Outlier  
identified.



Ground-truth



Image courtesy:  
iCoseg dataset

# Quantitative results

- Datasets

- 570 outlier image sets created using images from iCoseg dataset
- MIT object discovery set of internet images

Methods \ Jaccard	PM	A	B	C	D	E	F
iCoseg 570	<b>0.71</b>	0.64	0.62	0.39	0.37	0.33	0.23
Internet dataset	<b>0.54</b>	0.44	0.40	-	-	-	-

PM : Proposed method

A : Lee *et al.*, CVPR 2015

B : Chang *et al.*, CVIU 2015

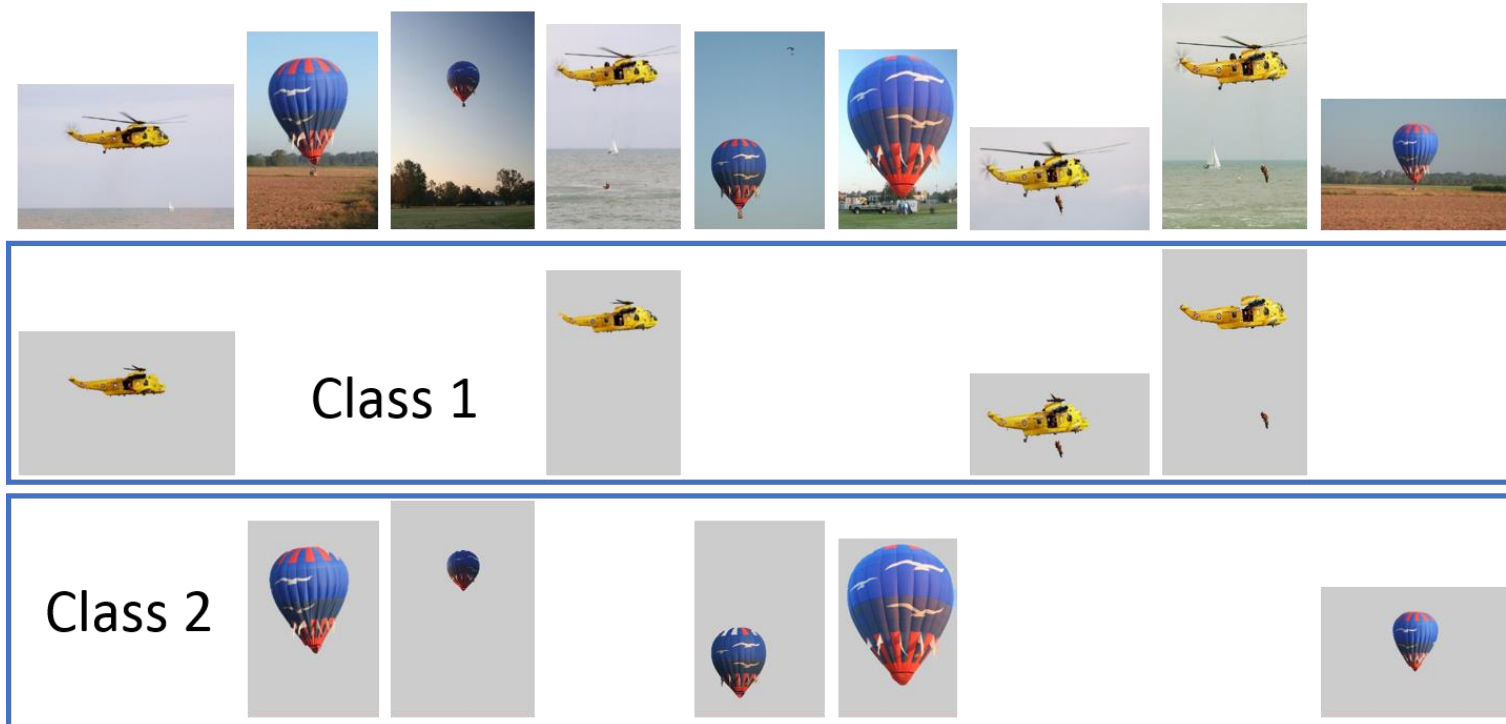
C : Joulin *et al.*, CVPR 2012

D : Rubinstein *et al.*, CVPR 2013

E : Joulin *et al.*, CVPR 2010

F : Kim *et al.*, ICCV 2011

# Multiple class co-segmentation



Most compact cluster

$$p_1 = \arg \max_j \{ \Gamma_j : \forall j \}$$

Second most compact cluster

$$p_2 = \arg \max_j \{ \Gamma_j : \forall j \setminus p_1 \}$$

Row 1: input set of 9 images containing objects of two classes

Row 2: common object of class 1 (Helicopter)

Row 3: common object of class 2 (Balloon)

Image courtesy:  
iCoseg dataset

# Conclusion

- Unsupervised method : feature selection is important
- More number of background classes helps
- Discriminative features using LDA
  - better separation between classes
- Label updating
  - corrects seeds selected without supervision

# Thank You