



# **Bayesian Quickest Change Point Detection with Multiple Candidates of Post-Change Models**

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# OUTLINE

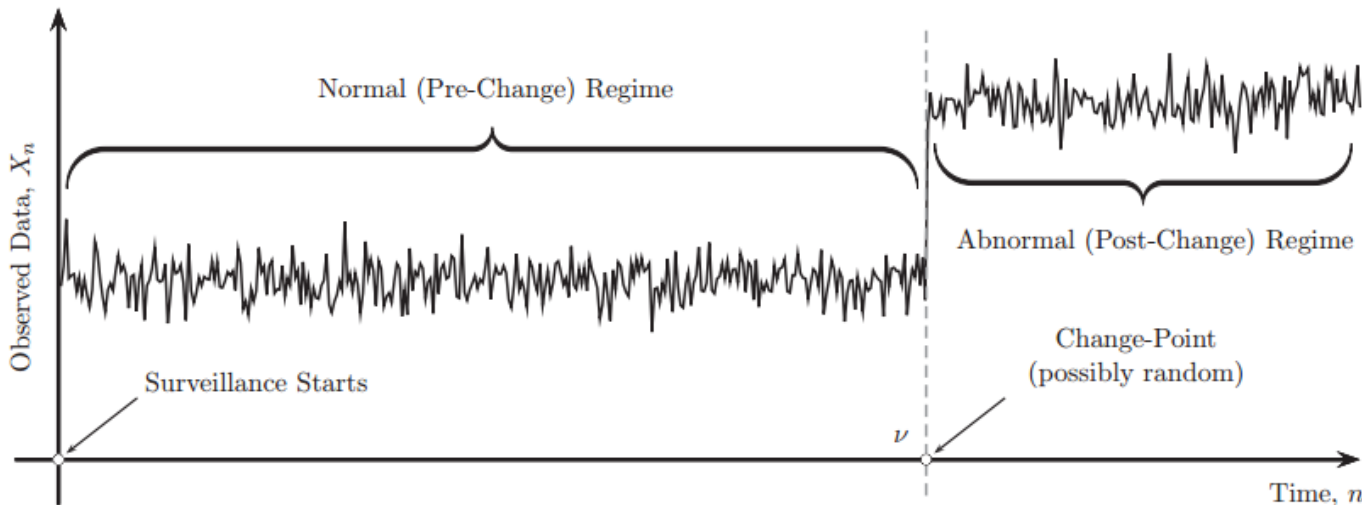
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- Introduction
- Problem Formulation
- Quickest Change Detection (QCD) Algorithm
- Analytical Results
- Simulation Results
- Conclusions

# INTRODUCTION (1/4)

- Change-point Detection:

- Process of identifying time instants at which the distribution of a random process changes.
- **Applications:** Signal and image processing, quality control engineering, seismology, financial markets, etc.



**Figure:** An example of the behavior observed sequences from a certain process of interest [1]

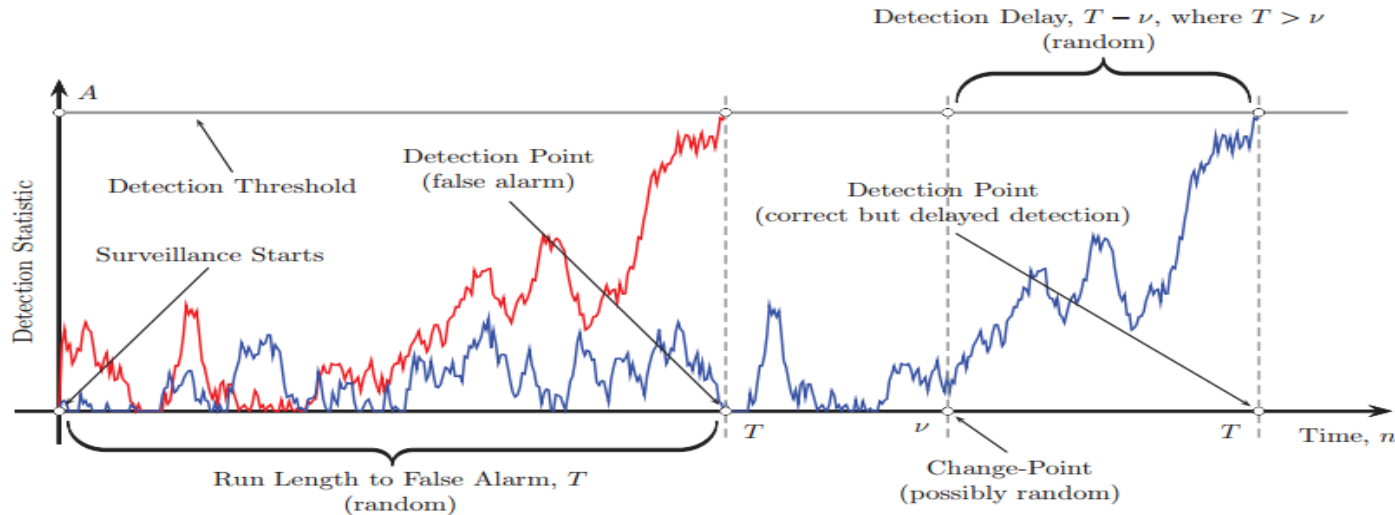
[1] Polunchenko, Aleksey S., and Alexander G. Tartakovsky. "State-of-the-art in sequential change-point detection." Methodology and computing in applied probability 14, no. 3 (2012): 649-684.

# INTRODUCTION (2/4)

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- Categories of Detection Procedures:
  - Based on nature of observations:
    - **Offline:** based on the observations of the entire time sequence
    - **Online:** based on currently observed samples (real-time)
  - Based on knowledge of change-point:
    - **Bayesian:** Prior probability of the change-point is known
    - **Non-Bayesian:** Prior is unknown

# INTRODUCTION (3/4)



**Figure:** Two possible scenarios: False alarm (red trajectory), and delayed detection (blue trajectory) [1]

- **Quickest Change Detection (QCD):**
  - Aims at minimizing detection delay with an upper bound on probability of false alarm [2]

[2] V. V. Veeravalli and T. Banerjee, “Quickest change detection,” in Academic Press Library in Signal Processing. Elsevier, 2014, vol. 3, pp. 209–255.

# INTRODUCTION (4/4)

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- Motivation:
  - There are limited works with unknown or uncertain post-change models.
  - For many applications, the post-change model might be from a finite set of possible models.
  - **Objective:** To design change detection algorithm for systems with multiple post-change models under Bayesian setting.

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# PROBLEM FORMULATION (1/3)

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- Notations:

- $X_n$ : a sequentially observed random sequence, where  $n = 1, 2, \dots$ .

- $\mathcal{F}_n^X = \sigma(\mathbf{X}^{1:n})$  is  $\sigma$  –algebra generated by  $\mathbf{X}^{1:n} = [X_1, \dots, X_n]$

- $\theta$ : Change point

- $f_{0,n}(X_n|\mathbf{X}^{1:n-1})$ : Probability density function (pdf) when  $n < \theta$ .

- $f_{i,n}(X_n|\mathbf{X}^{1:n-1})$  pdf when  $n \geq \theta$  for  $i = 1, 2, \dots, M$

- $M$ : number of post-change distribution models

- $\beta \in \{1, \dots, M\}$ : index for true post-change distribution



# PROBLEM FORMULATION (2/3)

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- Bayesian Setting:

- Probability mass function (PMF) for change-point  $\theta$

$$\mathbf{P}(\theta = k) = \pi_k, \text{ for } k = 1, 2, \dots.$$

- PMF for post-change model index:

$$\mathbf{P}(\beta = i) = \omega_i, \text{ for } i = 1, \dots, M.$$

- Sequential Test ( $\delta$ ):

- To detect change point  $\theta$  based on sequentially observed data  $X_n$

- $\hat{\theta}$ : estimate of change point

- Sequential test can be defined as  $\delta : \mathcal{F}_n^X \rightarrow \hat{\theta}$

- Needs to be designed by optimizing with respect to detection delay and false detection

# PROBLEM FORMULATION (3/3)

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- Performance Metrics:

- Average Detection Delay:

$$\text{ADD}(\delta) = \mathbb{E}[\hat{\theta} - \theta | \hat{\theta} \geq \theta]$$

- Probability of False Alarm:

$$\text{PFA}(\delta) = \mathbf{P}(\hat{\theta} < \theta | \mathcal{F}_n^X)$$

- Optimization Problem:

$$\begin{array}{lll} \text{(P1)} & \text{minimize} & \text{ADD}(\delta) \\ & \text{subject to} & \text{PFA}(\delta) < \alpha. \end{array}$$

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# QCD ALGORITHM (1/2)

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- Test Statistic:

- At moment  $n$ , the detector needs to decide between two hypotheses

$$\mathcal{H}_1 : \theta \leq n,$$

$$\mathcal{H}_0 : \theta > n.$$

- Test statistic is the ratio of posterior probabilities:

$$\begin{aligned}\Delta(n) &= \frac{\mathbf{P}(\mathcal{H}_1 | \mathcal{F}_n^X)}{\mathbf{P}(\mathcal{H}_0 | \mathcal{F}_n^X)} = \frac{\sum_{k=1}^n \pi_k \cdot d\mathbf{P}(\mathbf{x}^{1:n} | \theta = k)}{\Omega_n \cdot d\mathbf{P}(\mathbf{x}^{1:n} | \theta > n)} \\ &= \sum_{i=1}^M \omega_i \sum_{k=1}^n \frac{\pi_k}{\Omega_n} \prod_{t=k}^n \frac{f_{i,t}(X_t | \mathbf{X}^{1:t-1})}{f_{0,t}(X_t | \mathbf{X}^{1:t-1})},\end{aligned}$$

$$\text{where } \Omega_n = \mathbf{P}(\theta > n) = \sum_{k=n+1}^{\infty} \pi_k.$$

# QCD ALGORITHM (2/2)

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- Proposed Algorithm:

- **Definition 1:** For a given PFA upper bound  $\alpha$ , the change point is detected as

$$\delta_1 : \hat{\theta}_1 = \inf \left\{ n \geq 1 : \Delta(n) \geq \frac{1 - \alpha}{\alpha} \right\}$$

- $\delta_1$  can be considered as an extension of the **Shiryaev** procedure [3], which only considers the case of one known post-change model.

[3] A. N. Shiryaev, “On optimum methods in quickest detection problems,” *Theory of Probability & Its Applications*, vol. 8, no. 1, pp. 22–46, 1963.

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# ANALYTICAL RESULTS (1/4)

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- Probability of False Alarm:

- Lemma 1:  $\text{PFA}(\delta_1) \leq \alpha$

- Sketch of proof:

- Let  $p(n) = \mathbf{P}(\mathcal{H}_1 | \mathcal{F}_n^X) = \mathbf{P}(\theta \leq n | \mathcal{F}_n^X)$

- $\Delta(n) = \frac{\mathbf{P}(\mathcal{H}_1 | \mathcal{F}_n^X)}{\mathbf{P}(\mathcal{H}_0 | \mathcal{F}_n^X)} = \frac{p(n)}{1-p(n)}$

- $p(n) = 1 - \frac{1}{1+\Delta(n)}$

- Since,  $\delta_1 : \hat{\theta}_1 = \inf \left\{ n \geq 1 : \Delta(n) \geq \frac{1-\alpha}{\alpha} \right\}$

- $\Delta(\hat{\theta}_1) \geq \frac{1-\alpha}{\alpha} \implies p(\hat{\theta}_1) \geq 1-\alpha$

- $\text{PFA}(\delta_1) = \mathbf{P}(\hat{\theta}_1 < \theta | \mathcal{F}_n^X) = 1 - p(\hat{\theta}_1) \leq \alpha$

# ANALYTICAL RESULTS (2/4)

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- Average Detection Delay:

$$\begin{aligned}\text{ADD}(\delta) &= \frac{\mathbb{E}(\hat{\theta} - \theta)^+}{\mathbf{P}(\hat{\theta} \geq \theta)} \\ &= \frac{1}{\mathbf{P}(\hat{\theta} \geq \theta)} \sum_{k=1}^{\infty} \pi_k \mathbf{P}_k(\hat{\theta} \geq k) \mathbb{E}_k(\hat{\theta} - k | \hat{\theta} \geq k),\end{aligned}$$

–  $x^+ = \max(0, x)$

- $\mathbf{P}_k$ : probability measure when  $\theta = k$
- $\mathbb{E}_k$ : corresponding expectation operator



# ANALYTICAL RESULTS (3/4)

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- Asymptotic Notations:

- $f(x)$  and  $g(x)$  are continuous function such that

$$\lim_{x \rightarrow x_0} f(x) = \lim_{x \rightarrow x_0} g(x) = \infty.$$

- Notation 1:  $f(x) \underset{x \rightarrow x_0}{\preceq} g(x) \iff \lim_{x \rightarrow x_0} \frac{f(x)}{g(x)} \leq 1.$

- If both  $f(x) \underset{x \rightarrow x_0}{\preceq} g(x)$  and  $g(x) \underset{x \rightarrow x_0}{\preceq} f(x)$ , then two functions are asymptotically equivalent.

$$f(x) \underset{x \rightarrow x_0}{\asymp} g(x) \iff \lim_{x \rightarrow x_0} \frac{f(x)}{g(x)} = 1.$$

# ANALYTICAL RESULTS (4/4)

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- Asymptotic Optimality of Proposed QCD Algorithm:

- Theorem 1:**  $\mathbb{E}_k[(\hat{\theta}_1 - k)^+] \underset{\alpha \rightarrow 0}{\asymp} \min_i \left[ \frac{\log\left(\frac{1-\alpha}{\alpha}\right) - \log \omega_i}{D_i + |\log(1-\rho)|} \right]$

- Theorem 2:**  $\mathbb{E}_k[(\hat{\theta}_1 - k)^+] \underset{\alpha \rightarrow 0}{\asymp} \min_i \left[ \frac{\log\left(\frac{1-\alpha}{\alpha}\right) - \log \omega_i}{D_i + |\log(1-\rho)|} \right]$

- Theorem 3:**  $\text{ADD}(\delta_1) \underset{\alpha \rightarrow 0}{\asymp} \min_i \left[ \frac{\log\left(\frac{1-\alpha}{\alpha}\right) - \log \omega_i}{D_i + |\log(1-\rho)|} \right]$

- Here,

- $D_i = \mathbb{E} \left[ \log \frac{f_i(X)}{f_0(X)} \right]$  is Kullback-Leibler (KL) divergence.
- $\pi_k = (1-\rho)^{k-1} \rho$  is the prior PMF of change-point  $\theta$ .

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# SIMULATIONS (1/2)

- **Environment:**

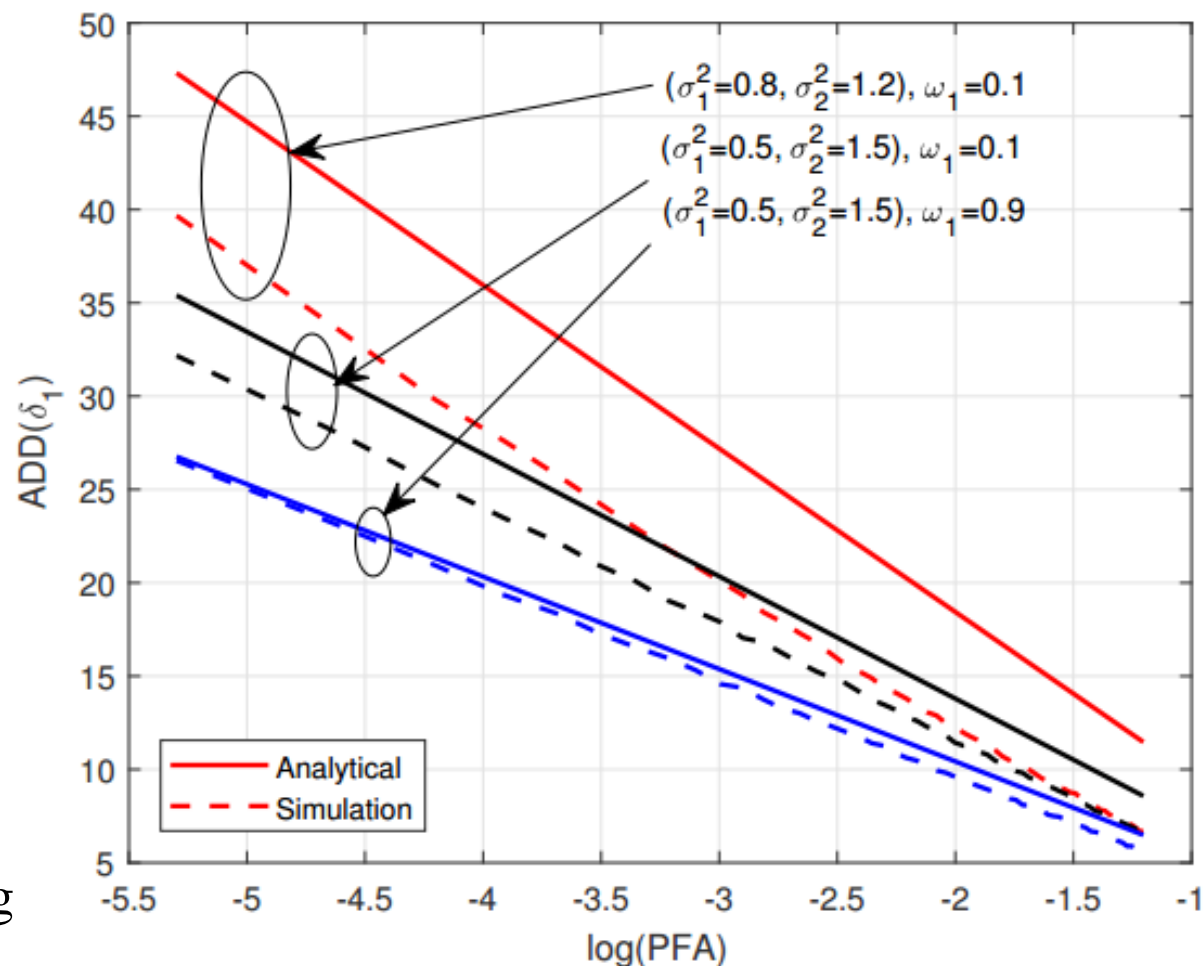
- Two post-change models
- Models follow Normal distribution,

$$f_i \sim \mathcal{N}(0, \sigma_i^2)$$

- For pre-change model,

$$\sigma_0^2 = 1$$

- Geometric dist.  $\rho = 0.1$
- Asymptotic results give good predictions regarding trend of detection delay.



**Figure:** Average Detection Delay

# SIMULATIONS (2/2)

- Environment:

- Models follow:

$$f_i \sim \mathcal{N}(\mu_i, 1)$$

- For pre-change model,

$$f_0 \sim \mathcal{N}(1, 1)$$

- Four post-change models

$$\begin{aligned} \mu_1 &= 0.6, \mu_2 = 0.8, \\ \mu_3 &= 1.2, \mu_4 = 1.4 \end{aligned}$$

- Mixture model in Shiryaev Procedure [3]:

$$h(x) = \sum_{i=1}^4 \omega_i f_i(x)$$

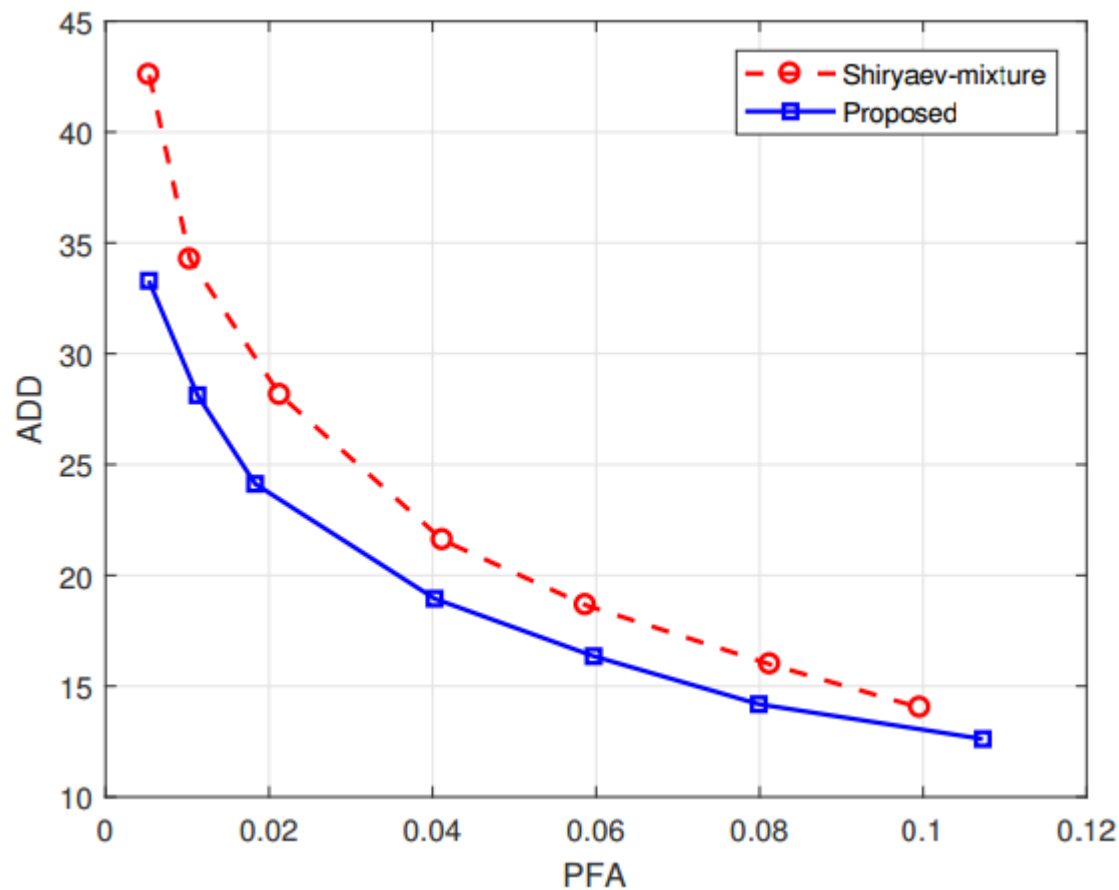


Figure: Tradeoff between ADD and PFA

[4] T. L. Lai, "Information bounds and quick detection of parameter changes in stochastic systems," IEEE Transactions on Information Theory, vol. 44, no. 7, pp. 2917–2929, 1998

# CONCLUSIONS

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- **Summary:**
  - Proposed a threshold-based sequential test for Bayesian QCD when there are multiple possible post-change models.
  - Analytical ADD has been obtained through asymptotic analysis when the PFA is small.
  - Proposed algorithm is asymptotically optimal in terms of ADD.
  - Proposed algorithm outperforms the Shiryaev procedure with a mixture post-change model.
- **Future Direction:**
  - QCD algorithm in non-Bayesian setting.
  - Detection of multiple change-points.
  - Both change-point detection and identification of post-change model.

# REFERENCES

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- [1] Polunchenko, Aleksey S., and Alexander G. Tartakovsky. "State-of-the-art in sequential change-point detection." *Methodology and computing in applied probability* 14, no. 3 (2012): 649-684.
  
- [2] V. V. Veeravalli and T. Banerjee, "Quickest change detection," in *Academic Press Library in Signal Processing*. Elsevier, 2014, vol. 3, pp. 209–255.
  
- [3] A. N. Shiryaev, "On optimum methods in quickest detection problems," *Theory of Probability & Its Applications*, vol. 8, no. 1, pp. 22–46, 1963.
  
- [4] T. L. Lai, "Information bounds and quick detection of parameter changes in stochastic systems," *IEEE Transactions on Information Theory*, vol. 44, no. 7, pp. 2917–2929, 1998

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**Thanks!**  
for your attention

Questions?