

# ENHANCING NOISY LABEL LEARNING VIA UNSUPERVISED CONTRASTIVE LOSS WITH LABEL CORRECTION BASED ON PRIOR KNOWLEDGE

*Masaki Kashiwagi, Keisuke Maeda, Ren Togo, Takahiro Ogawa, Miki Haseyama*  
Hokkaido University, Japan

E-mail: kashiwagi@lmd.ist.hokudai.ac.jp

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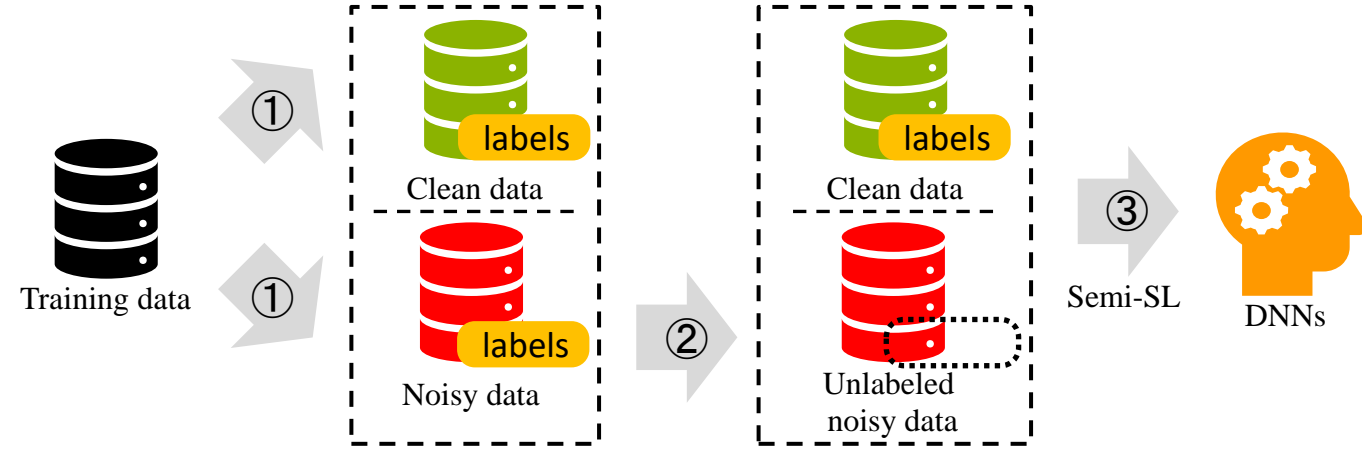
## INTRODUCTION

### Noisy Labels : Mistaken labels introduced into the training data

- It has been shown that deep neural networks (DNNs) trained on noisy labeled data suffer from degradation of generalization performance [4].
- Several noise-robust methods of noisy label learning (NLL) have been proposed [5].

### Sample Selection [10-12] : A mainstream NLL approach to filter out noisy labels

- Splitting the training data into clean data and noisy data
- Alleviating the negative impacts of noisy labels by discarding the labels of noisy data
- Semi-supervised learning (Semi-SL) with both clean and unlabeled noisy data



✓ Sample selection can robustly train on noisy labeled data by selective use of clean samples.

✗ When the noise ratio is high, inappropriate training data splitting can negatively impact classification performance.

Most of previous NLL methods are highly dependent only on the improvement of a classification loss.

### Multi-objective interpolation training (MOIT) [14] : Introducing another approach independent of classification loss to NLL

- In addition to conventional sample selection, MOIT focuses on similarities between feature representations of the samples.
- MOIT introduces a regularization of the contrastive loss based on supervised contrastive learning.

✓ MOIT can obtain noise-robust feature representations by introducing contrastive loss based on supervised approach.

✗ Supervised contrastive approaches may not eliminate the negative impacts of noisy labels.

## PROPOSED METHOD

### Proposed method (PM) : A novel sample selection-based NLL method via the unsupervised contrastive loss with label correction based on prior knowledge

- Label Correction Based on Prior Knowledge** : Reducing noise ratio of the training data before the start of NLL training

PM utilizes a latent space constructed by Contrastive Language-Image Pre-training [16] (CLIP) for label correction.

#### Approach 1

Utilizing prior knowledge of models pre-trained on large datasets

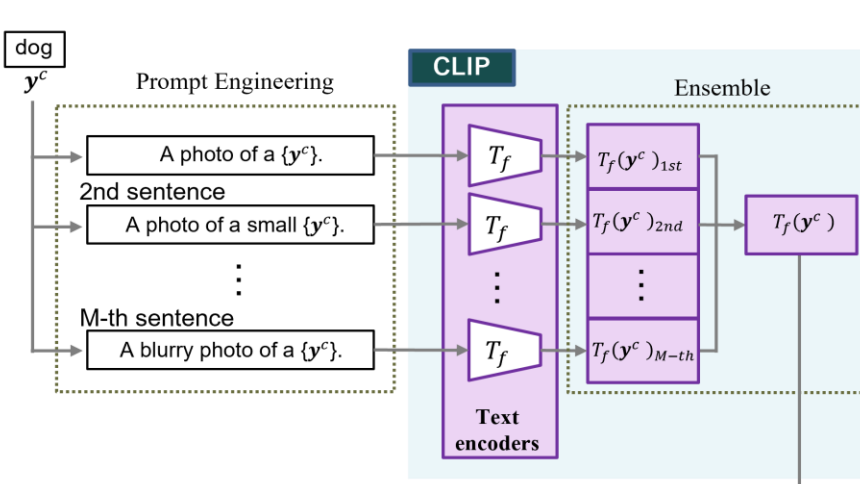
#### Step 1.1. Prompt engineering to obtain label-embedded representations

PM embeds candidate labels for each class into the latent space to obtain the respective label-embedded representations.

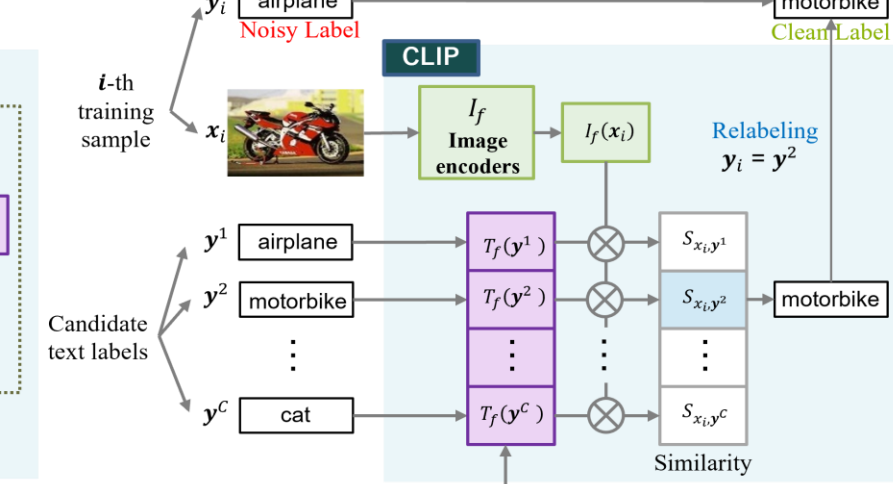
#### Step 1.2. Label correction based on the distance

For each obtained label-embedded representation of the classes and the image-embedded representation of the training images, the labels are corrected based on the distance between these embedded representations.

#### Step 1.1.



#### Step 1.2.



- Unsupervised Contrastive Loss Based on Clustering** : Obtaining noise-robust feature representations even in the existence of noisy labels via an unsupervised approach

PM introduces an unsupervised contrastive loss based on similarity between image features.

#### Approach 2

Introducing an unsupervised contrastive learning approach to NLL

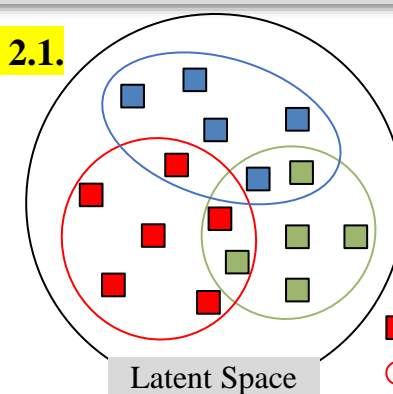
#### Step 2.1 Clustering on image features

PM performs clustering on image features extracted in the NLL training process.

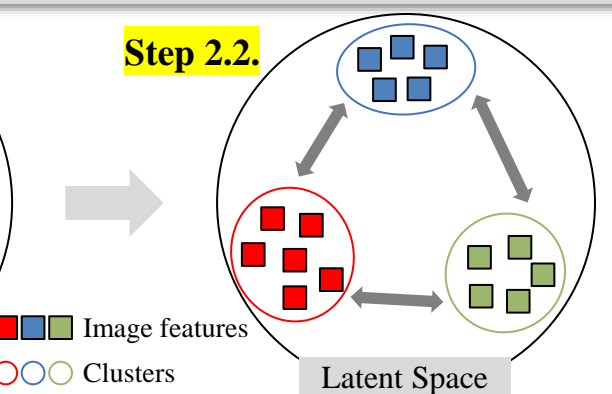
#### Step 2.2 Introducing an unsupervised contrastive loss

PM learns feature representations based on clustering results so that similar samples are close to each other.

#### Step 2.1.



#### Step 2.2.



- ✓ Approach 1 : Expected to improve sample selection under the high noise ratio due to the reduction of noisy labels before the start of NLL training
- ✓ Approach 2 : Expected to realize robust NLL against noisy labels without requiring label information for being based on an unsupervised approach

## EXPERIMENTAL RESULTS

### Conditions

#### ◆ Dataset : CIFAR-10 and CIFAR-100 [15]

- 10 and 100 classes, respectively
- 50,000 training data and 10,000 test data
- Training data was used by injecting symmetric label noise (Sym.).
  - Sym. randomly replaces the ground-truth labels with all candidate labels.
  - Noise Ratio was set to 80-90%.

#### ◆ Label correction

- Utilizing the ensemble of 80 different prompt engineering results.

#### ◆ Unsupervised contrastive loss $\mathcal{L}_{con}$

- Clustering method : k-means
- Number of clusters : 10 for CIFAR-10 and 20 for CIFAR-100
- Temperature parameter  $\tau$  : Experimentally set to 0.3

#### ◆ Implementation details

- PM employed ProMix [12] as the sample selection-based NLL method.
- Other settings such as hyperparameters are according to [12].
- Evaluation metric : Classification accuracy

#### ◆ Comparative Methods

- MOIT [14] : Supervised contrastive approach-based NLL method
- ProMix [12] : State-of-the-art sample selection-based NLL method
- PM w/o CLIP : Evaluation against label correction based on CLIP
- PM w/o  $\mathcal{L}_{con}$  : Evaluation against unsupervised contrastive loss

### Quantitative Results

#### PM vs MOIT and ProMix

- The robustness of PM under the high noise ratio is demonstrated.

#### PM vs PM w/o CLIP

- From PM > PM w/o CLIP, PM achieves high accuracy independent of the noise ratio.
- The effectiveness of Approach 1

#### PM vs PM w/o $\mathcal{L}_{con}$

- From PM  $\geq$  PM w/o  $\mathcal{L}_{con}$ , PM achieves performance equivalent to or better than PM w/o  $\mathcal{L}_{con}$  under both the high noise ratio.
- The effectiveness of Approach 2

#### Accuracy (%) comparisons on CIFAR-10 and CIFAR-100

Dataset	CIFAR-10		CIFAR-100	
	Sym.	90%	Sym.	90%
Methods \ Noise Ratio	80%	90%	80%	90%
MOIT	75.8	70.1	51.4	24.5
ProMix	95.5	93.4	69.4	42.9
PM w/o CLIP	95.9	93.5	68.2	34.6
PM w/o $\mathcal{L}_{con}$	96.7	96.8	71.9	71.6
PM	96.8	96.8	72.3	72.1

✓ We validated that PM achieves higher classification performance for NLL under high noise ratio.