### A Neural Network Alternative to Non-Negative Audio Models

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# Introduction

#### Supervised Single-channel Source Separation

Given a mixture of N sources

 $x(t) = \sum w_i s_i(t)$ , where  $w_i \in \mathbb{R}$  for  $i = \{1, \dots, N\}$ 

- Separate individual sources
- Training data in the form of alternate unmixed recordings of the source.
- Non-negative Matrix Factorization (NMF)
- Objective: Develop a neural network alternative to NMF

# Outline

Non-negative Matrix Factorization (NMF)

□ Non-negative Auto-encoder (NAE) equivalent to NMF

Supervised source separation using NAE models

Results

### NMF

#### NMF for matrices

 $\mathbf{X} = \mathbf{W}\mathbf{H}$   $\mathbf{X} \in \mathbb{R}_{>0}^{m \times n}, \ \mathbf{W} \in \mathbb{R}_{>0}^{m \times r}, \ \mathbf{H} \in \mathbb{R}_{>0}^{r \times n},$ 

#### NMF is posed as a minimization problem

 $\begin{array}{ll} \underset{\mathbf{W},\mathbf{H}}{\text{minimize}} & D(\mathbf{X},\mathbf{WH}) \\ \text{subject to} & \mathbf{W} \geq 0, \mathbf{H} \geq 0. \end{array}$ 

where  $\geq 0$  implies element-wise non-negativity

Commonly used Cost functions

# NMF: Piano example



#### No cross-cancellations

Part based decomposition

Meaningful basis vectors.

Can be used as a model for supervised source separation.



## Towards an NMF neural network

- Autoencoder: Reconstructs the input at the output
  - Encoder: Input to Code
  - Decoder: Code to approximation of input



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g(x) = max(x,0) or ln(1 + exp(x)) or |x| mapping to the space of positive real nos.





#### Without sparsity



#### With Sparsity

 $\mathbf{D} = KL(\mathbf{X} \mid\mid g(\mathbf{WH}))$ 

 $\mathbf{D} = KL(\mathbf{X} \mid\mid g(\mathbf{W}\mathbf{H})) + ||\mathbf{H}||_1$ 





# Supervised source separation

- Learn representative bases for all the sources.
  - Autoencoder training on unmixed training examples gives representative matrices Ws and Wn.
- The spectrogram of the mixture is the sum of spectrograms of the sources.

$$\mathbf{X}_m = \mathbf{S} + \mathbf{N} = g(\mathbf{W}_s \mathbf{H}_s) + g(\mathbf{W}_n \mathbf{H}_n)$$

Thus,

 $\mathbf{X}_m^T = g(\mathbf{H}_s^T \mathbf{W}_s^T) + g(\mathbf{H}_n^T \mathbf{W}_n^T)$ 

An output neural network with inputs:  $\mathbf{W}_s^T, \mathbf{W}_n^T$  and output:  $\mathbf{X}_m^T$ 

## Supervised source separation

#### Solve the minimization problem for Hs and Hn

 $\underset{\mathbf{H}_s,\mathbf{H}_n}{\text{minimize}} \quad KL(\mathbf{X}_m \mid\mid g(\mathbf{W}_s\mathbf{H}_s) + g(\mathbf{W}_n\mathbf{H}_n))$ 

Solved by training the output neural network

Reconstruct the sources

$$\hat{s}_i[n] = \mathrm{STFT}^{-1} \left( \frac{g(\mathbf{W}_i \mathbf{H}_i)}{\sum_{i \in \{s,n\}} g(\mathbf{W}_i \mathbf{H}_i)} \odot \mathbf{X}_m \odot e_m^{j \cdot \mathbf{\Phi}_m} \right) \text{ for } i \in \{s,n\}$$

where  $\Phi_m$  represents the phase of the mixture STFT<sup>-1</sup> represents the overlap and add STFT operation

## Results

NMF vs shallow- NAE Rank = 20

#### NMF vs multilayer NAE Rank = 20



## Results

NMF vs shallow- NAE Rank = 100

#### NMF vs multilayer NAE Rank = 100



# Conclusion

#### Non-negative Auto-encoder (NAE) audio models equivalent to NMF

Easily generalizable

#### Separation Performance

- Shallow NAE models equivalent to NMF
- Multilayer NAE models outperform NMF by ~ 1.5 dB (SDR)

#### Future work

- Alternate neural net architectures for NAE
- Towards an end-to-end neural net for source separation.

# **THANK YOU**

### Demo

	Ground truth	NMF (SDR = 6.05 dB)	Two layer NN (SDR = 5.4 dB)	Four layer NN (SDR = 7.1 dB)
Source 1 (Male)				
Source 2 (Female)				