

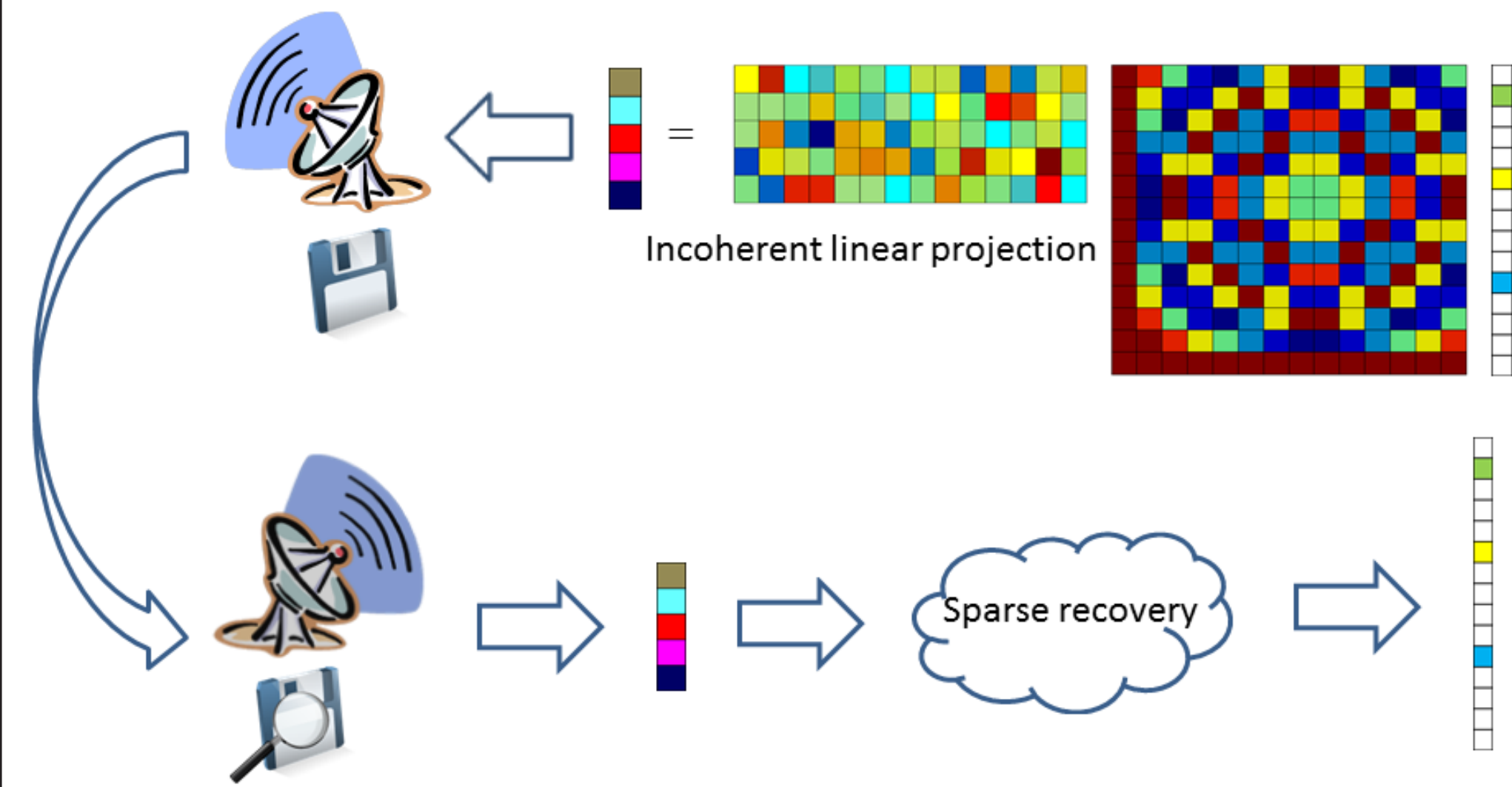
BAYESIAN SPARSE SIGNAL DETECTION EXPLOITING LAPLACE PRIOR

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MOTIVATION

- ▶ Most of the real signals are sparse



- ▶ Compressed Sensing allows for compression of sparse signals before transmission/storage and reconstruction when required.

- ▶ Many signal processing applications deal with drawing an inference from received data such as detection and classification of signals, and estimation of signal parameters.

- ▶ Applications in sensor networks, cognitive radio networks, and radar networks.

PROBLEM FORMULATION

- ▶ Consider a distributed network with P nodes that observe the sparse signals

- ▶ The observation model at the p -th node

$$\mathcal{H}_1 : z_p = x_p + \eta_p$$

$$\mathcal{H}_0 : z_p = \eta_p$$

- ▶ The compressed observation matrix at the FC can be represented as

$$\mathbf{Y} = \Phi \mathbf{Z} + \mathbf{W}$$

- ▶ The detection problem with compressed observation reduces to

$$\mathcal{H}_1 : \mathbf{Y} = \Phi \mathbf{X} + \mathbf{N}$$

$$\mathcal{H}_0 : \mathbf{Y} = \mathbf{N}$$

- ▶ Each x_p is modeled as a random signal.

SPARSE SIGNAL DETECTION

Likelihood Ratio Based Detection

- ▶ Direct Laplace prior on \mathbf{x}_p

- ▶ With $L = \frac{p(\mathbf{Y}|\mathbf{X}, \lambda, \mathcal{H}_1)}{p(\mathbf{Y}|\mathcal{H}_0)}$,

$$\Lambda_{MMV}(\lambda) = \int L p(\mathbf{X}|\lambda) d\mathbf{X} = \beta(\lambda) \prod_{p=1}^P \prod_{n=1}^N I_{p,n},$$

where $I_{p,n}$ is given by,

$$I_{p,n} = \sqrt{2\pi\sigma_0^2} \exp\left(-\frac{(v_{p,n} + \sigma_0^2\lambda)^2}{2\sigma_0^2 C}\right) Q\left(\frac{v_{p,n} + \sigma_0^2\lambda}{\sqrt{C}\sigma_0}\right) + \sqrt{2\pi\sigma_0^2} \exp\left(-\frac{(v_{p,n} - \sigma_0^2\lambda)^2}{2\sigma_0^2 C}\right) \left(1 - Q\left(\frac{v_{p,n} - \sigma_0^2\lambda}{\sqrt{C}\sigma_0}\right)\right).$$

Partial Estimate based Detection

- ▶ **Idea:** Signal Detection does not require complete signal reconstruction.

- ▶ Three stage hierarchical prior on \mathbf{x}_p which impose Laplace prior on signal coefficients.

- ▶ Estimate a fraction of signal.

- ▶ Algorithm

$$\text{Inputs : } \Phi, \mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_P]$$

Initialize $\zeta_j = 0, \forall j$. Set $k = 0$.

While $k \leq R$

Select a particular ζ_j^k out of $\zeta^k = [\zeta_1^k, \dots, \zeta_N^k]$.

$$\text{Update } \boldsymbol{\mu}_p = \boldsymbol{\Sigma}_p \Phi^T \mathbf{y}_p, \boldsymbol{\Sigma}_p = [\Phi^T \Phi + \mathbf{Z}]^{-1}$$

Update algorithm parameters, and $k = k + 1$.

end While

Detection decision:

If $\Lambda_{MT} = \frac{1}{RP} \sum_{r=1}^R \sum_{p=1}^P \mu_{p,r}^2 \geq \theta$, \mathcal{H}_1 is true, otherwise \mathcal{H}_0 is true where θ is the threshold.

SPARSE SIGNAL DETECTION (CONTD...)

- ▶ Can we further reduce computational complexity?

- ▶ Energy of signal on the most likely support as detection parameter.

- ▶ Algorithm

$$\text{Inputs : } \Phi, \mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_P]$$

Outputs : Decision statistic Λ_{prj} , Detection Decision

Solve for ζ_j such that $\frac{\partial \mathcal{L}(\zeta)}{\partial \zeta_j} = 0, \forall j$

Evaluate $l(\zeta_j), \forall \zeta_j$.

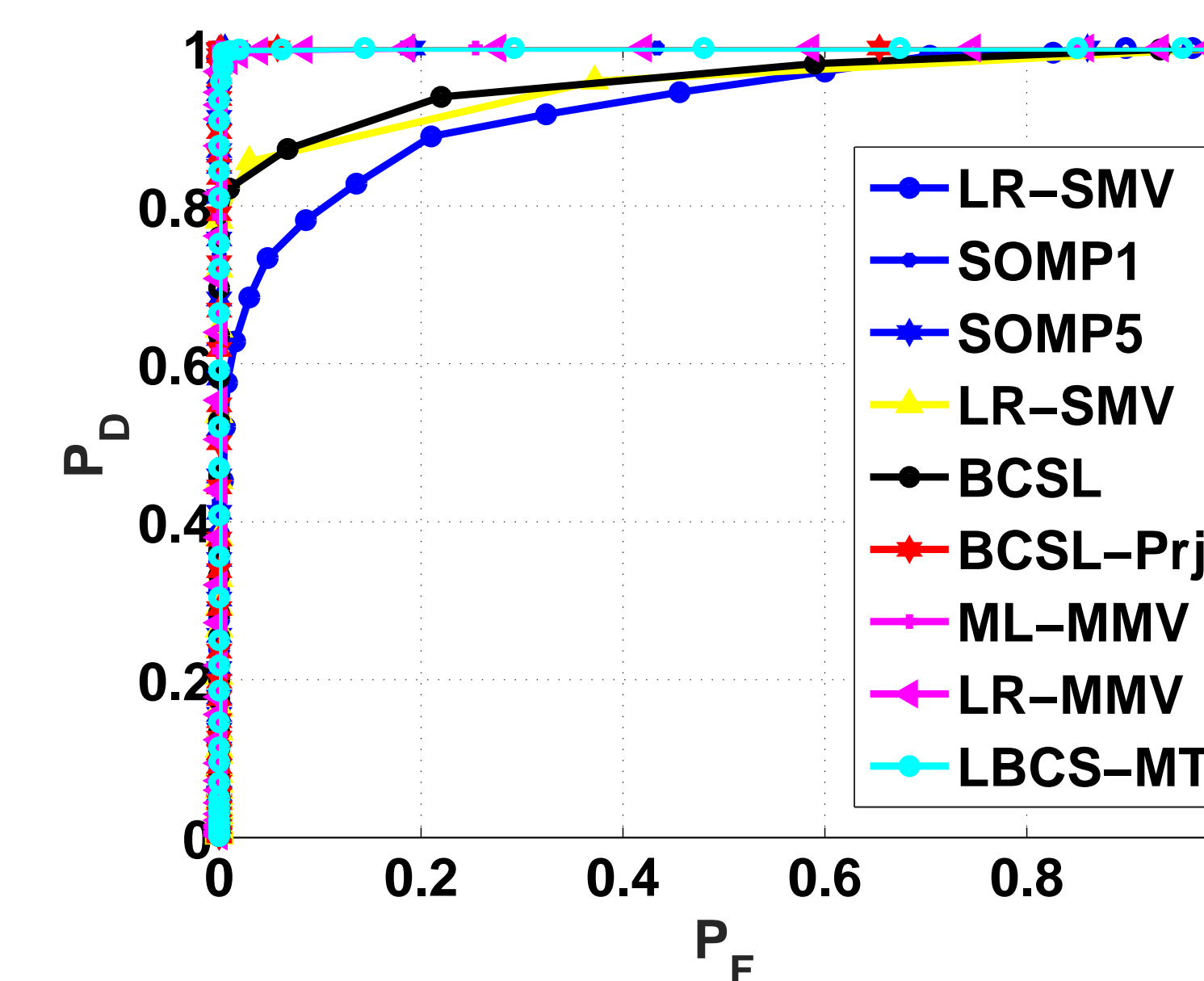
Arrange $l(\zeta_j)$ in descending order and choose K' indices j for the first K' largest $l(\zeta_j)$. Let $\hat{\mathcal{U}}$ be the set containing these indices

Detection decision:

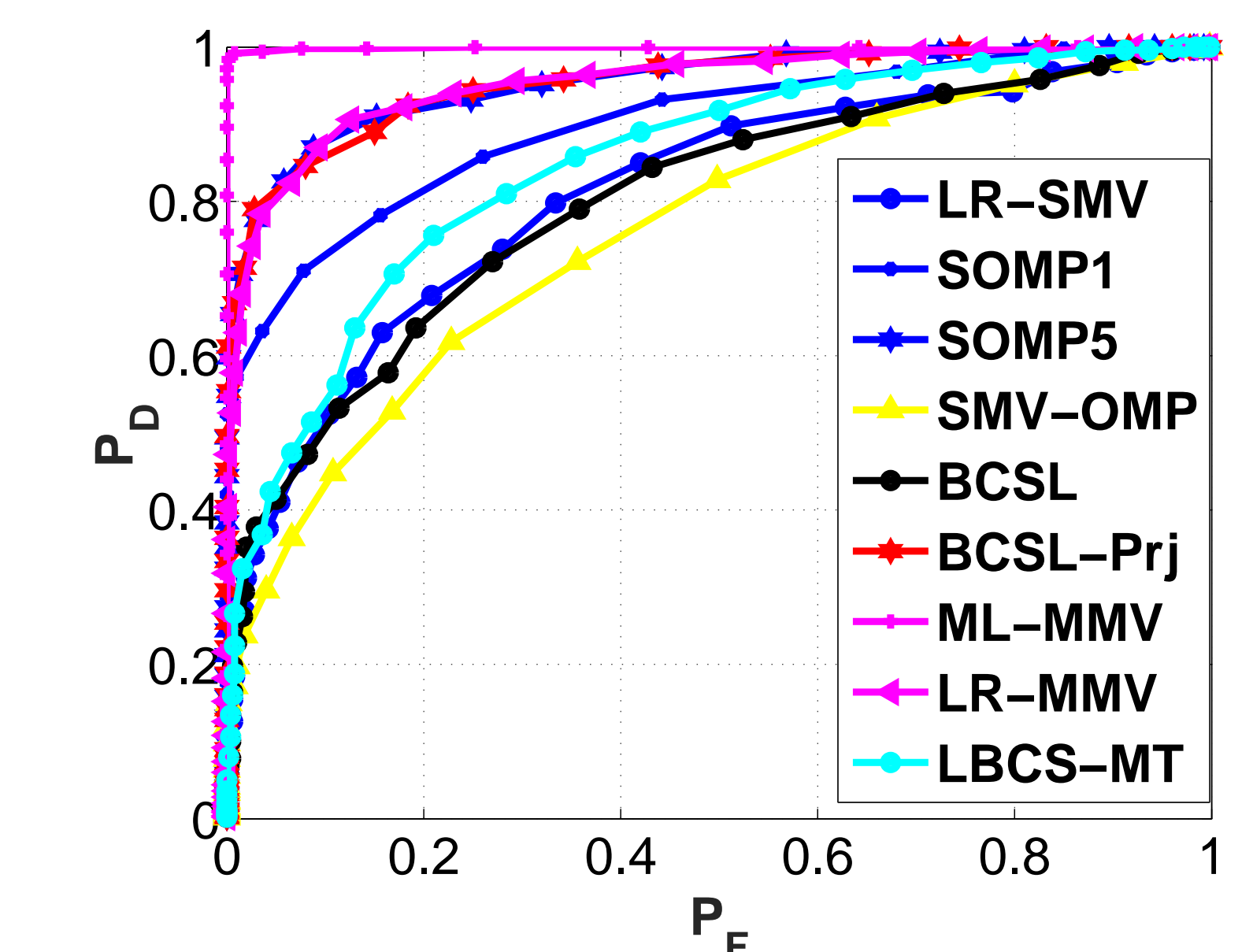
If $\Lambda_{prj} = \sum_{p=1}^P \|\boldsymbol{\Omega} \mathbf{y}_p\|_2^2 \geq \theta$, \mathcal{H}_1 is true, otherwise \mathcal{H}_0 is true where θ is the threshold.

RESULTS

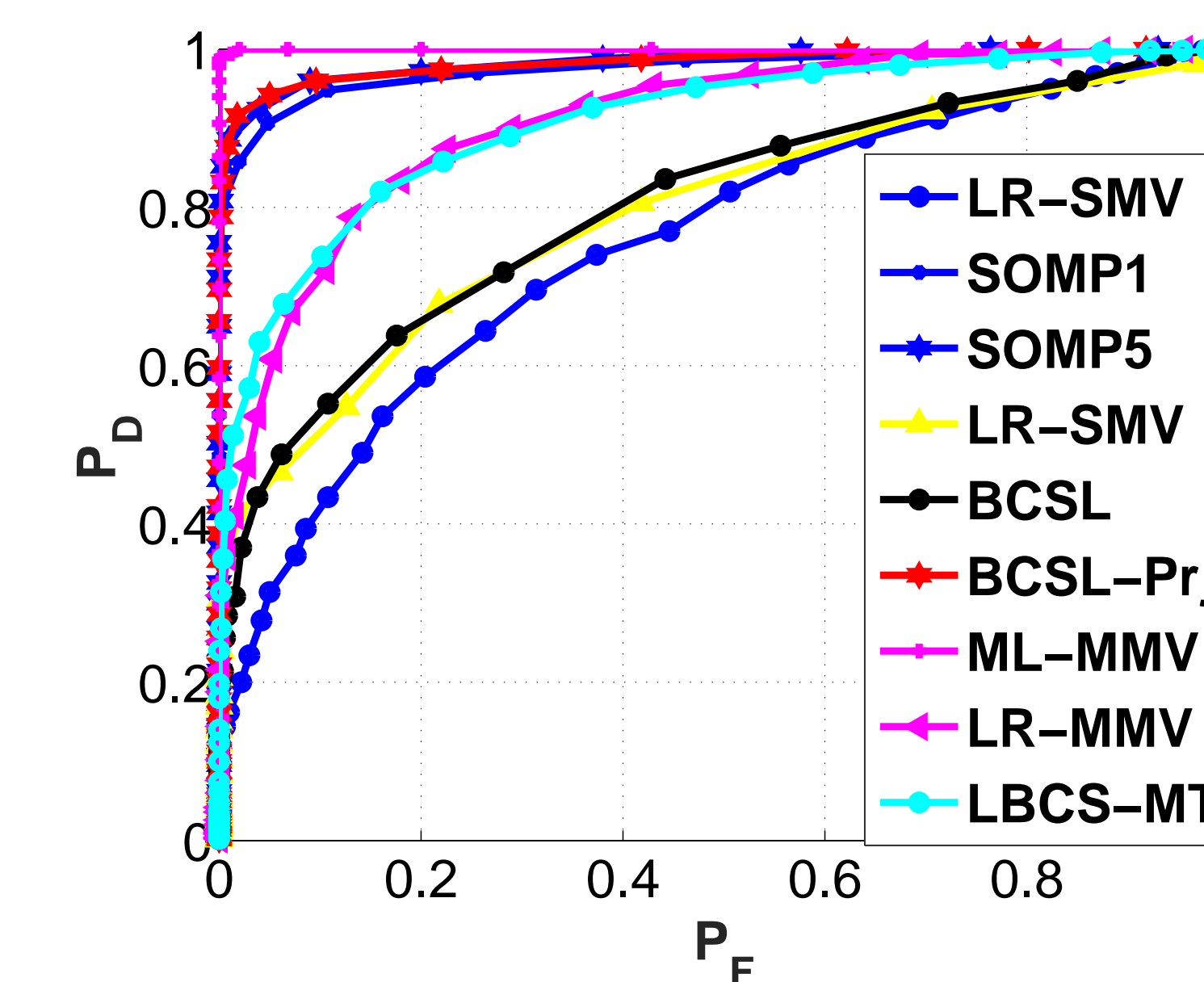
1. $M/N \approx 0.49, \eta = 1.76$ dB



3. $M/N = 0.1, \eta = 1.76$ dB



2. $M/N = 0.49, \eta = 13.98$ dB



4. Run Time Comparison

Run times when $N = 512$ and $K = 5$					
$M/N \rightarrow$	0.60	0.70	0.80	0.90	1.00
LR-MMV	0.70	0.76	0.89	0.96	0.93
LBCS-MT	0.82	1.43	2.01	1.60	1.22
BCSL-Prj	0.17	2.37	2.92	2.24	3.01
SOMP5	17.26	16.25	20.25	20.86	23.19

CONCLUSION

- ▶ Algorithms developed for sparse signal detection without signal reconstruction
- ▶ Reduction in computational complexity compared to the state-of-the-art algorithm.