

Integrated Grad-CAM: Sensitivity-Aware Visual Explanation of Deep Convolutional Networks via Integrated Gradient-Based Scoring

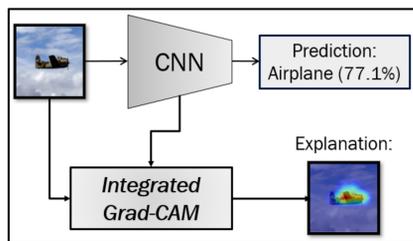
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Introduction

- **Explainable AI (XAI):** Understanding Convolutional Neural Networks (CNNs) is crucial for high-impact and high-risk applications in computer vision.
- **Our aim: Visual Explainability:** Visualizing the input features responsible for CNN prediction.



Background

- **Methods for visual explainability:**
 - **Backpropagation-based methods :** Computing the gradient of CNN's output to the input features or hidden neurons.
 - **CAM-based methods :** Visualizing the features extracted in a single layer of the CNNs.
 - **Perturbation-based methods :** Probing the model's behavior using perturbed copies of the input image.

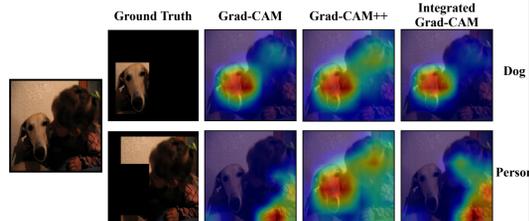
Contributions

- Our proposed approach: **Integrated Grad-CAM**
- Addressing the limitations of backpropagation in explaining non-linear models.
- Solving the gradient limitations by employing gradients.

Integrated Grad-CAM

Novelty:

Scoring the feature maps in the last convolutional layer of CNNs based on *Integrated Average Gradient* values, instead of "Average Gradient" values utilized in Grad-CAM.

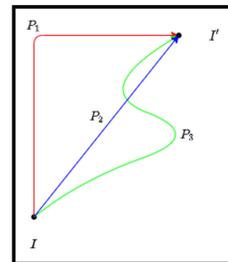


Intuition: Sensitivity axiom: (Sundararajan et al. '17) *For each pair of input and baseline differing only in one feature, an attribution method should highlight this difference by assigning different values corresponding to that feature.*

Idea: Calculating the integral of gradient values in a path that links a certain baseline to the input.

Path Integral

Defining a path linking a baseline I' and an input I :



Path equation: $\gamma(\alpha) = I' + f(\alpha) \times (I - I')$

$f(\alpha) : \mathbb{R} \rightarrow \mathbb{R} :$

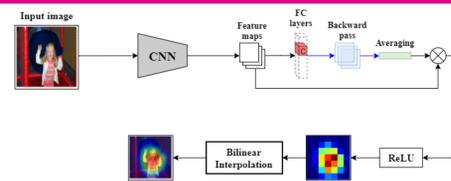
A differentiable and monotonically increasing function.

$0 \leq \alpha \leq 1: f(0) = 0$ and $f(1) = 1$.

For each pair of functions $(h(\cdot), g(\cdot))$:

$$\text{PathIG}_{h,g}(I) \equiv \int_{\alpha=0}^1 \frac{dh(\gamma(\alpha))}{dg(\gamma(\alpha))} [g(\gamma(\alpha)) - g(I')] d\alpha \quad (1)$$

Methodology



Feature maps derived from a convolutional layer (l): $\{A^1(I), A^2(I), \dots, A^N(I)\}$
Grad-CAM formulation:

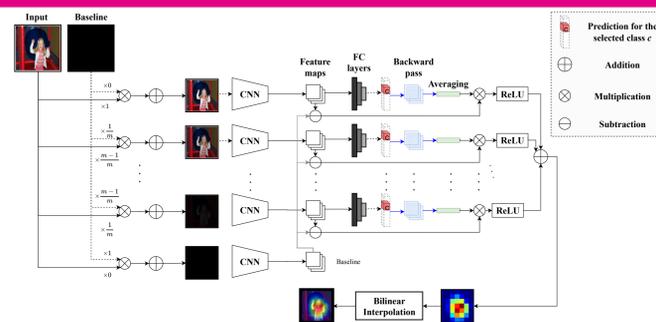
$$M_{\text{Grad-CAM}}^c = \text{ReLU} \left(\sum_{k=1}^N \left(\frac{1}{Z} \sum_{i,j} \frac{\partial y_c(I)}{\partial A_{ij}^k(I)} \right) A^k(I) \right) \quad (2)$$

Our method: Replacing gradient terms with integrated gradient terms:

$$M_{\text{IG-CAM}}^c = \int_{\alpha=0}^1 \text{ReLU} \left(\sum_{k=1}^N \sum_{i,j} \frac{\partial y_c(\gamma(\alpha))}{\partial A_{ij}^k(\gamma(\alpha))} [A^k(\gamma(\alpha)) - A^k(I')] \right) d\alpha \quad (3)$$

Limitation: The equation above is hard to implement.

Implementation



For simplicity, we assume the path between I' and I to be linear. Then, we approximate the equation (3) using *Reimann's approximation*.

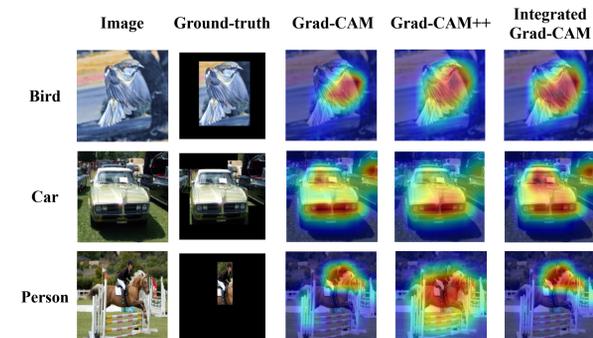
$$M^c \approx \sum_{t=1}^m \text{ReLU} \left(\frac{1}{m} \sum_{k=1}^N \sum_{i,j} \frac{\partial y_c(\gamma(\frac{t}{m}))}{\partial A_{ij}^k(\gamma(\frac{t}{m}))} [A^k(\gamma(\frac{t}{m})) - A^k(I')] \right) \quad (4)$$

The number of sampled points along the linear path: ' m ' (set to 20 by default.)

Experiments

Dataset: PASCAL VOC 2007

- **Purpose:** Multi-label image classification, Object Detection.
- Containing 4963 test images in 20 classes, Bounding boxes provided.
- A VGG-16 model and a ResNet-50 model trained on this dataset are utilized.



Quantitative Evaluation

Evaluation metrics:

- *Ground truth-based* like Energy-based Pointing Game (**EBPG**), Mean Intersection-over-Union (**mIoU**) and Bounding Box (**Bbox**) are used to verify the meaningfulness of explanation methods, and their ability in feature visualization.
- *Model truth-based* like **Drop** and **Increase rate** are employed to justify the faithfulness and validity of the generated explanations from the model's perspective.

Model	Metric	Grad-CAM	Grad-CAM++	Integrated Grad-CAM
VGG16	EBPG	55.44	46.29	55.94
	Bbox	51.7	55.59	55.6
	Drop Increase	49.47 31.08	60.63 23.89	47.96 31.47
ResNet-50	EBPG	60.08	47.78	60.41
	Bbox	60.25	58.66	61.94
	Drop Increase	35.80 36.58	41.77 32.15	34.49 36.84

Conclusion

Integrated Grad-CAM Takeaways:

- Circumvented the underestimations in Grad-CAM and Grad-CAM++.
- Addressed the issues caused by backpropagation in the methods above.
- Though slower than the conventional methods, offers an acceptable run-time to be used in real-world applications.
- The takeaways above are verified through extensive experiments on the PASCAL VOC 2007 dataset.

References

Selvaraju, Ramprasaath R., et al. "Grad-cam: Visual explanations from deep networks via gradient-based localization." (2018).
Sundararajan, Mukund, Ankur Taly, and Qiqi Yan. "Axiomatic attribution for deep networks." (2017).