### **Pilot Insertion with Index Modulation for OFDM-Based Vehicular Communications**

Qiang Li, Miaowen Wen, Yuekai Zhang, Jun Li, Fangjiong Chen, and Fei Ji

South China University of Technology HUAWEI Technologies Co., Ltd Guangzhou University

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## Background

### • Vehicular Communications

Vehicular communications play a vital role in the realization of Internet of Vehicle (IoV). Various vehicular communication solutions have been developed throughout the world.



### Background

#### Index Modulation

Index modulation (IM) is a kind of digital modulation technique that utilizes the index(es) of building block(s) of a communication system to convey additional information bits. <mark>01</mark>(00) Spatial 10(00)00(00)(00) $\nabla$ constellation Spatial 11(00)  $x_2$  $x_1$ Modulation (01)  $\nabla$  $x_2 = 0/1$ (10) $\nabla$ **01**(11) **10**(11) 00(11) (11)Spatial Modulation (SM)  $\nabla$ 11(11) Signal constellation

#### **Proposed Scheme** Positions are selected according to **Motivation** the information. The positions of pilots are fixed in fixed vehicular A Frequency OFDM-based current communications. This overhead lower N=16 the system spectral efficiency (SE). Data Idea To utilize the indices of pilots to Pilot carry additional information, thus improving the SE. The pilots can be used for either carrier phase tracking or channel estimation purpose. Carrier phase Time Time tracking is taken as an example in Conventional Proposed this talk.

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The process of  $p_1$  bits:

□ Equal-spaced pilot position selection (PPS), PPS-I

The spacing between any two adjacent pilot tones is  $n=N/N_p$ .

 $p_1 = \lfloor \log_2(n) \rfloor \Longrightarrow \mathcal{I} = \{d_0, n+d_0, \dots, (N_p-1)n+d_0\}, \ d_0 \in \{0, 1, \dots, n-1\}$ 

□ Unequal-spaced PPS, PPS-II

Divide both the N subcarriers and  $p_1$  bits into  $N_p$  sub-blocks, and select one pilot within n subcarriers for each sub-block.

$$p_1 = N_p \lfloor \log_2(n) \rfloor \Longrightarrow \mathcal{I} = \left\{ d^{(0)}, n + d^{(1)}, \dots, (N_p - 1)n + d^{(N_p - 1)} \right\}$$

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N: the total number



Transmitter Design

M-PSK constellation  $\mathcal{S}$  $p_2 = N_d \log 2(M)$  bits  $s = [S_0, S_1, \dots, S_{N_d-1}]^T$ Data symbols  $\mathbf{s} = [S_0, S_1, \dots, S_{N_d-1}]^T$ Pilot sequence  $\mathbf{c} = [C_0, C_1, \dots, C_{N_p-1}]^T$ the frequency-domain block  $\mathbf{x}_F = [X_0, X_1, \dots, X_{N-1}]^T$ where  $X_m = \begin{cases} C_k, & \text{for } m = i_k, k \in \{0, 1, \dots, N_p - 1\}, \\ S_{\kappa}, & \text{for } m = \overline{i}_{\kappa}, \kappa \in \{0, 1, \dots, N_d - 1\}. \end{cases}$  $\{\bar{i}_0, \bar{i}_1, \dots, \bar{i}_{N_d-1}\} \triangleq \bar{\mathcal{I}} = \mathcal{N} \setminus \mathcal{I}$  are the indices of data symbols. Finally, the time-domain transmit vector  $N \times N$  DFT matrix  $\mathbf{x}_T = [x_{0,}x_1, \dots, x_{N-1}]^T = \frac{1}{\sqrt{N}} \mathbf{F}_N^H \mathbf{x}_F, \_\_\_$ 8

#### Transmitter Design

#### Pilot symbols selection

To facilitate pilot position detection (PPD), the pilot symbols are required to be distinguishable from the data symbols as much as possible. Hence, in this paper,  $C_k$ ,  $k \in \{0, 1, ..., N_p - 1\}$  is equiprobably drawn from a rotated constellation  $S^{\theta}$  that is derived by rotating S with angle  $\theta$ , where  $\theta$  is selected as  $\theta = \pi/M$ .

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 $\mathcal{S}$ 

 $\otimes S^{\theta}$ 

For example, M=2

#### Receiver Design



Receiver Design

• Optimal ML Detector  $\hat{(\mathcal{I}, \hat{\mathbf{s}}, \hat{\varphi})} = \arg \min \left\| \mathbf{r}_F - \mathbf{X} \mathbf{h}_F e^{j\varphi} \right\|^2 \begin{array}{c} \text{high computational} \\ \text{complexity} \end{array}$  $\mathcal{I}, \mathbf{s}, \varphi$ □ Near-ML Detector For each realization of  $\mathcal{I}$ , denoted by  $(\mathcal{I})\eta$ ,  $\eta \in \{0, \ldots, 2^{p_1} - 1\}$ , the phase s given by  $(\varphi)_{\eta} = \angle \left( \sum_{k=0}^{N_p - 1} R_{(i_k)_{\eta}} (H_{(i_k)_{\eta}} C_k)^* \right)^{\text{the }k\text{-th entry of } (\mathcal{I})_{\eta}}$ estimate is given by Phase compensation  $\tilde{\mathbf{r}}_F = \mathbf{r}_F e^{-j(\varphi)_{\eta}}$ With  $(\mathcal{Z})\eta$ , the metric is  $(\Delta)_{\eta} = \sum_{k=0}^{N_p-1} \left| \tilde{R}_{(i_k)_{\eta}} - H_{(i_k)_{\eta}} C_k \right|^2 + \sum_{k=0}^{N_d-1} \left( \min_{S_k \in \mathcal{S}} \left| \tilde{R}_{(\bar{i}_k)_{\eta}} - H_{(\bar{i}_k)_{\eta}} S_k \right|^2 \right)$ Finally, we have  $\hat{\eta} = \operatorname*{arg\,min}_{\eta} (\Delta)_{\eta}$  and  $\hat{S}_{\kappa} = \operatorname*{arg\,min}_{S_{\kappa} \in S} \left| \tilde{R}_{(\bar{i}_{\kappa})_{\hat{\eta}}} - H_{(\bar{i}_{\kappa})_{\hat{\eta}}} S_{\kappa} \right|^2$ 11

### **Simulation Results**



- The BER curve of the near-ML detector almost overlaps that of the optimal ML detector for IGPI-OFDM with PPS-I.
- IGPI-OFDM with PPS-I achieves an SNR gain of about 1 dB over classical OFDM.
- The near-ML detector for IGPI-OFDM with PPS-II achieves SNR gains of about 3 dB over classical OFDM, and about 2 dB over IGPI-OFDM with PPS-I.

### **Simulation Results**



- Increasing  $\varepsilon$  deteriorates the performance at high SNR significantly for all schemes.
- At  $\varepsilon = 0.02/0.04$ , IGPI-OFDM with PPS-I/II performs better than classical OFDM, achieving lower error floors.
  - Interestingly, the performance improvement with  $\varepsilon =$ 0.04 is more notable than that with  $\varepsilon = 0.02$ .

### **Simulation Results**



• IGPI-OFDM with PPS-II performs the best among all schemes when SNR is greater than 19 dB, and about 3 dB SNR gain over IGPI-OFDM with PPS-I is achieved at BER=  $2 \times 10^{-4}$ .

### Conclusions

- The information-guided pilot insertion technique is propsoed, which exploits the pilot positions to convey additional information bits, to solve the low SE problem in the current OFDM-based vehicular communications system.
- Two different types of information-guided PPS schemes, which result in the equal-spaced and unequal-spaced pilot patterns, and the corresponding PPD methods have been investigated for carrier phase tracking.
- Simulation results have shown that the proposed IGPI-OFDM outperforms classical OFDM in terms of BER performance significantly.

# **THANK YOU**

### **Questions?**

