

# Tensor Decomposition-based Beamspace ESPRIT Algorithm for Multidimensional Harmonic Retrieval

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# Outline

1. Problem Formulation
2. Proposed Method
3. Numerical Results
4. Conclusions

## Multidimensional ( $R$ -D) Harmonic Retrieval (HR)

For the  $k$ th snapshot, the **element-space** tensor  $\mathbf{x}_k$  has entries of the form:<sup>1</sup>

$$x_{m_1, \dots, m_R, k} = \sum_{l=1}^L \gamma_{l,k} \prod_{r=1}^R e^{jm_r \omega_{r,l}}, \quad (1)$$

where  $m_r = 0, 1, \dots, M_r - 1$ . Here,  $M_r$ ,  $R$  and  $L$  denote the number of sensors for the  $r$ th dimension, the number of dimensions and the number of  $R$ -D frequencies, respectively,  $\gamma_{l,k}$  represents the complex amplitude of the  $l$ th frequency at the  $k$ th snapshot, while  $\omega_{r,l} \in (-\pi, \pi)$  is the frequency in the  $r$ th dimension of the  $l$ th source.

The tensor  $\mathbf{x}_k$  can be expressed as

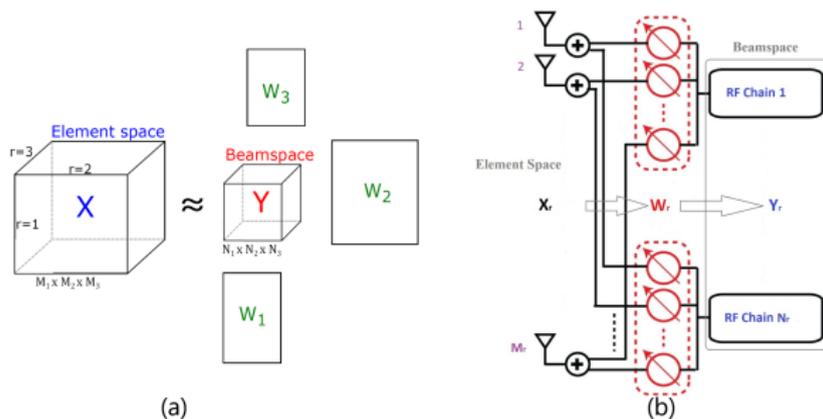
$$\mathbf{x}_k = \sum_{l=1}^L \gamma_{l,k} \mathbf{a}_{1,l} \circ \mathbf{a}_{2,l} \circ \dots \circ \mathbf{a}_{R,l} \in \mathbb{C}^{M_1 \times M_2 \times \dots \times M_R} \quad (2)$$

where  $\mathbf{a}_{r,l} = [1 \ e^{j\omega_{r,l}} \ \dots \ e^{j(M_r-1)\omega_{r,l}}]^T$  and  $\circ$  is the vector outer product.

<sup>1</sup>For notational compactness, noise is omitted in the equations

## From Element-space to Beamspace

**Beamspace** processing is an efficient and commonly used approach in HR. The measurements are obtained by *linearly transforming* the sensing data, thereby achieving a **compromise** between estimation accuracy and system complexity.



**Figure:** Illustration of measurements in beamspace (a) general case. (b) MIMO example with hybrid combining (**hardware constraints**).

## Beamspace Model

For beamspace measurements, after the  $r$ -mode product of  $\mathbf{x}_k$  with linear transformation matrix  $\mathbf{W}_r$ , the model (2) is modified to

$$\mathbf{y}_k = \sum_{l=1}^L \gamma_{l,k} \mathbf{b}_{1,l} \circ \mathbf{b}_{2,l} \circ \cdots \circ \mathbf{b}_{R,l}, \quad (3)$$

where the **beamspace array manifold** is defined as

$$\mathbf{B}_r = [\mathbf{b}_{r,1} \ \mathbf{b}_{r,2} \ \cdots \ \mathbf{b}_{r,L}] = \mathbf{W}_r^H \mathbf{A}_r \in \mathbb{C}^{N_r \times L}. \quad (4)$$

Here  $\mathbf{W}_r^H = [\mathbf{w}_{r,1} \ \mathbf{w}_{r,2} \ \cdots \ \mathbf{w}_{r,M_r}] \in \mathbb{C}^{N_r \times M_r}$ ,  $\mathbf{W}_r^H \mathbf{W}_r = \mathbf{I}_{N_r}$  is required to maintain whiteness in the beamspace output, and the **element-space array manifold**

$$\mathbf{A}_r = [\mathbf{a}_{r,1} \ \mathbf{a}_{r,2} \ \cdots \ \mathbf{a}_{r,L}] \in \mathbb{C}^{M_r \times L}. \quad (5)$$

$\Rightarrow$  The transformation matrix  $\mathbf{W}_r$  and number  $N_r$  should be chosen properly to cover the sector of source locations and most of the signal energy.

## Objective

Our objective is to estimate  $\omega_{r,l}$ , for  $r = 1, \dots, R$  and  $l = 1, \dots, L$ , from noisy measurements  $\tilde{\mathbf{Y}}_k$ .

- **Computationally Efficient**  $\Rightarrow$  Subspace-based **Search-free** method
- **Automatic Association**  $\Rightarrow$  **Joint** parameter **Estimation and Association**  
(For path  $l$ , what is  $\omega_{1,l}, \omega_{2,l}, \dots, \omega_{R,l}$ ?)

**A number of HR techniques are available in the literature (maximum likelihood, subspace, compressed sensing, ...)**

*Estimation of signal parameters via rotational invariance techniques (ESPRIT) and its variants have become one of the popular search-free signal subspace-based parameter estimation methods.*

$\Rightarrow$  **Beamspace tensor-ESPRIT**

## Idea 1: Multidimensional Parameter Association

In the CP decomposition, a tensor is decomposed into a sum of rank-one component tensors,

$$\tilde{\mathcal{Y}}_k = \sum_{l=1}^L \lambda_l \mathbf{u}_{1,l} \circ \mathbf{u}_{2,l} \circ \cdots \circ \mathbf{u}_{R,l}. \quad (6)$$

Both association and noise reduction are achieved simultaneously.

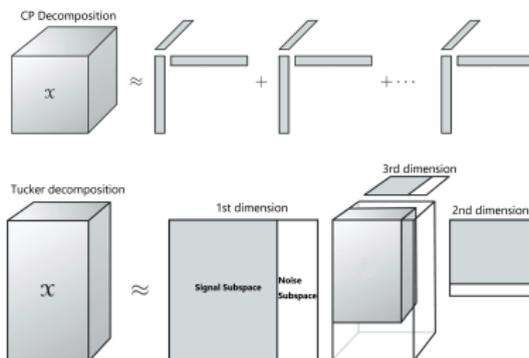


Figure: Illustration of 3-D CP and Tucker tensor decomposition.

## Idea 2: Shift Invariant Property

ESPRIT algorithms utilize the shift invariant property:

$$\mathbf{J}_r^{(1)} \mathbf{A}_r = \mathbf{J}_r^{(2)} \mathbf{A}_r \Phi_r, \quad (7)$$

where  $\Phi_r$  contains the frequencies of all sources in  $r$ th dimension,

$$\Phi_r = \text{diag} \left[ e^{-j\omega_{r,1}} \quad e^{-j\omega_{r,2}} \quad \dots \quad e^{-j\omega_{r,L}} \right], \quad (8)$$

$\mathbf{J}_r^{(1)} = [\mathbf{I}_{N_r-1} \quad \mathbf{0}_{(N_r-1) \times 1}]$  and  $\mathbf{J}_r^{(2)} = [\mathbf{0}_{(N_r-1) \times 1} \quad \mathbf{I}_{N_r-1}]$  are selection matrices.

In beamspace, the row transformation  $\mathbf{W}_r^H$  alters the transitional invariance structure in the array manifold, and consequently

$$\mathbf{J}_r^{(1)} \mathbf{B}_r \neq \mathbf{J}_r^{(2)} \mathbf{B}_r \Phi_r. \quad (9)$$

However, the shift invariance structure can be restored, if  $\mathbf{W}_r$  has a **similar structure**.

## Proposed Method

Suppose we are able to find a non-singular  $N_r \times N_r$  matrix  $\mathbf{F}_r$  that satisfies

$$\mathbf{J}_r^{(1)} \mathbf{W}_r = \mathbf{J}_r^{(2)} \mathbf{W}_r \mathbf{F}_r. \quad (10)$$

and

$$\mathbf{Q}_r = \mathbf{I}_{N_r} - \mathbf{w}_{r,M_r} \mathbf{w}_{r,M_r}^H - \left( \mathbf{F}_r^H \mathbf{w}_{r,1} \right) \left( \mathbf{F}_r^H \mathbf{w}_{r,1} \right)^H. \quad (11)$$

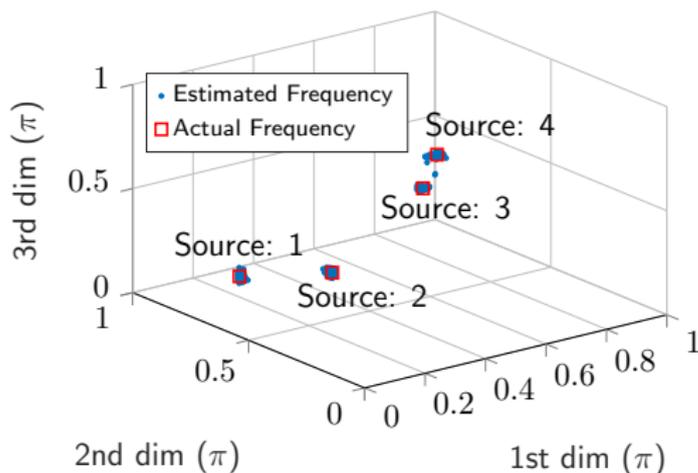
Then

$$\mathbf{Q}_r \mathbf{F}_r^H \mathbf{U}_r = \mathbf{Q}_r \mathbf{U}_r \mathbf{\Gamma}_r \quad (12)$$

where  $\mathbf{U}_r = [\mathbf{u}_{r,1} \quad \mathbf{u}_{r,2} \quad \cdots \quad \mathbf{u}_{r,L}]$ , its columns span the signal subspace,  $\mathbf{\Gamma}_r = \mathbf{D}_r \mathbf{\Phi}_r^H \mathbf{D}_r^{-1} \in \mathbb{C}^{L \times L}$  and  $\mathbf{D}_r \in \mathbb{C}^{L \times L}$  is a non-singular matrix.

1. CP decomposition on  $\tilde{\mathbf{y}}_k \Rightarrow \mathbf{U}_r, r = 1, 2, \dots, R$ .
2. Estimate  $\mathbf{F}_r$  from (10), construct  $\mathbf{Q}_r$  by (11), estimate  $\mathbf{\Gamma}_r$  from (12)
3. Frequency  $\omega_{r,l}$  is obtained from the  $l$ th eigenvalue of  $\mathbf{\Gamma}_r$ .

## Test 1: Parameter estimation for partially distinct frequencies.



4 sources with partially distinct frequencies.

In element space,

$$M_1 = M_2 = M_3 = 8.$$

In beamspace,

$$N_1 = N_2 = N_3 = 6.$$

SNR=20 dB, and the number of measurements is  $K=10$ .

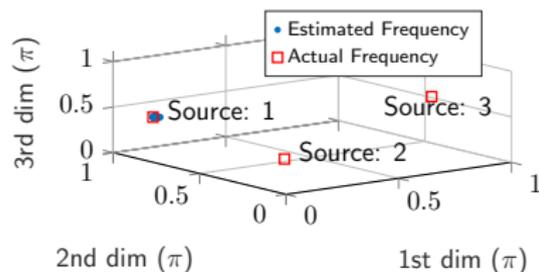
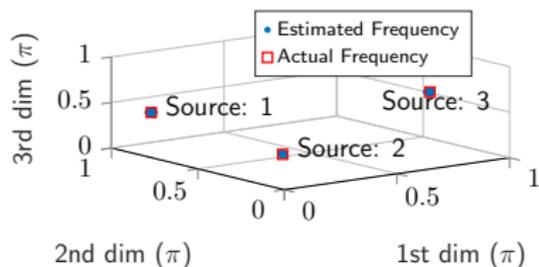
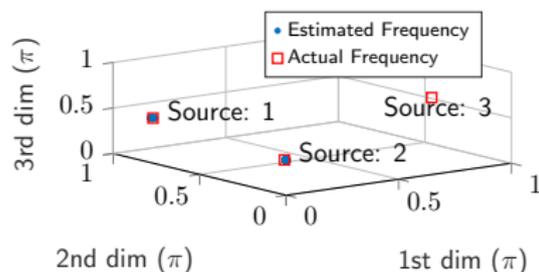
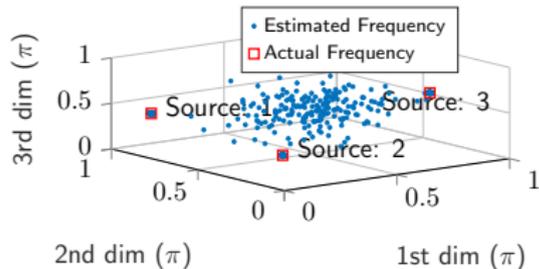
The 3-D HR frequencies are:

$$r = 1 : (\boxed{0.2\pi, 0.2\pi}, 0.6\pi, 0.8\pi)$$

$$r = 2 : (0.9\pi, \boxed{0.4\pi, 0.4\pi}, 0.6\pi)$$

$$r = 3 : (0.1\pi, 0.2\pi, \boxed{0.8\pi, 0.8\pi}).$$

## Test 2: Inaccurate source number information (3 sources).

(a) Assumed number of sources  $\hat{L} = 1$ .(c) Assumed number of sources  $\hat{L} = 3$ .(b) Assumed number of sources  $\hat{L} = 2$ .(d) Assumed number of sources  $\hat{L} = 4$ .

## Conclusions

A beamspace  $R$ -D tensor-ESPRIT algorithm is developed for multidimensional harmonic retrieval.

Source parameter estimation and association are achieved simultaneously.

Furthermore, the effect of *errors in the estimated number of sources* is investigated, as well as the applicability for *sources with partially distinct frequencies* is demonstrated.