



# TWO-DIMENSIONAL ANTI-JAMMING COMMUNICATION BASED ON DEEP REINFORCEMENT LEARNING

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## Abstract

In this paper, a two-dimensional anti-jamming communication scheme for cognitive radio networks is developed, in which a secondary user (SU) exploits both spread spectrum and user mobility to address jamming attacks, while not interfering with primary users (PUs). By applying a deep Q-network algorithm, this scheme determines whether to recommend that the SU leave an area of heavy jamming and chooses a frequency hopping pattern to defeat smart jammers. Without knowing the jamming model and the radio channel model, the SU derives an optimal anti-jamming communication policy using Q-learning in a proposed dynamic game, and applies a deep convolution neural network to accelerate the learning speed with a large number of frequency channels. The proposed scheme can increase the signal-to-interference-plus-noise ratio and improve the utility of the SU against cooperative jamming, compared with a Q-learning-only based benchmark system.

## System Model

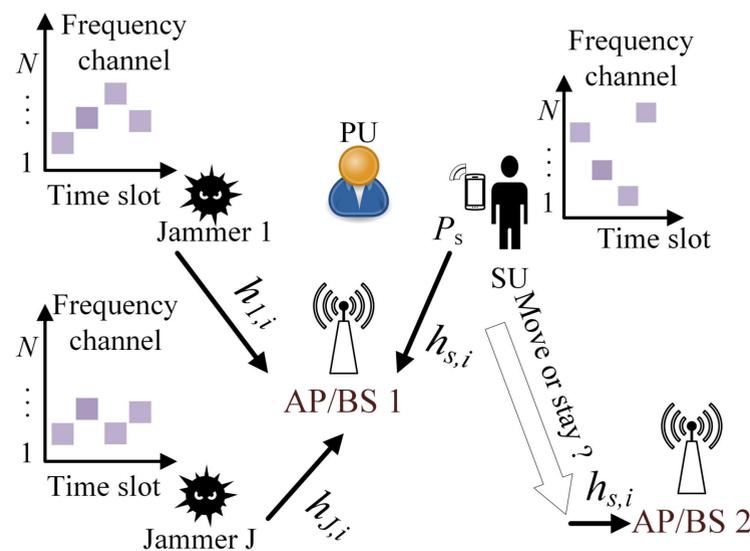


Figure 1. System model.

- SU chooses a communication channel and determines whether to leave the area
- $J$  smart jammers block communication channels cooperatively

## Game Model

The repeated interactions among an SU and jammers are formulated as a zero-sum dynamic anti-jamming communication game:

- The SU chooses an action  $x_k \in \{0, 1, \dots, N\}$ , if  $x_k = 0$ , the SU connects to a new AP/BS; otherwise, the SU uses channel  $x_k$  to send signals
- $J$  cooperative jammers randomly located in the CRN and choose their jamming channels
- Both the SU and  $J$  jammers should have to avoid interfering with the PU

Utility function:

$$u_k(x, \mathbf{y}) = \frac{P_s h_{s,x} \lambda_k}{\sigma + \sum_{j=1}^J P_j h_{j,y_j} f(x=y_j)} - C_m f(x=0)$$

Presence of PUs
SINR of signals
Cost of defense

$\sigma$  is the receiver noise power, and  $f(\xi)$  is an indicator function that equals 1 if  $\xi$  is true, and 0 otherwise.

System state:

Consist of the presence of PUs and the SINR of the signals at last time, i.e.,  $\mathbf{s}_k = [\lambda_{k-1}, \text{SINR}_{k-1}]$

## Method

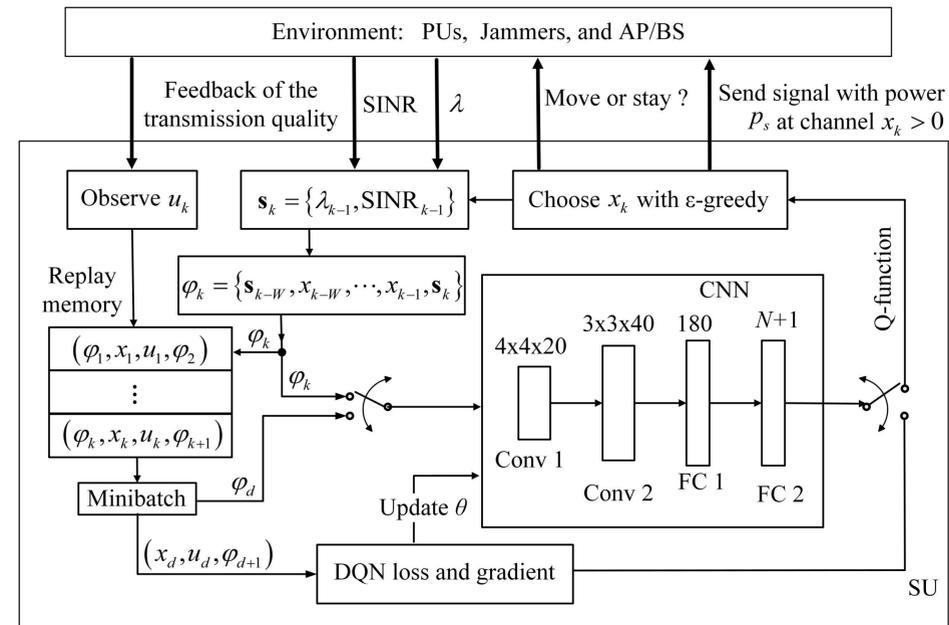


Figure 2. DQN-based 2-D anti-jamming communication system.

## Simulation results

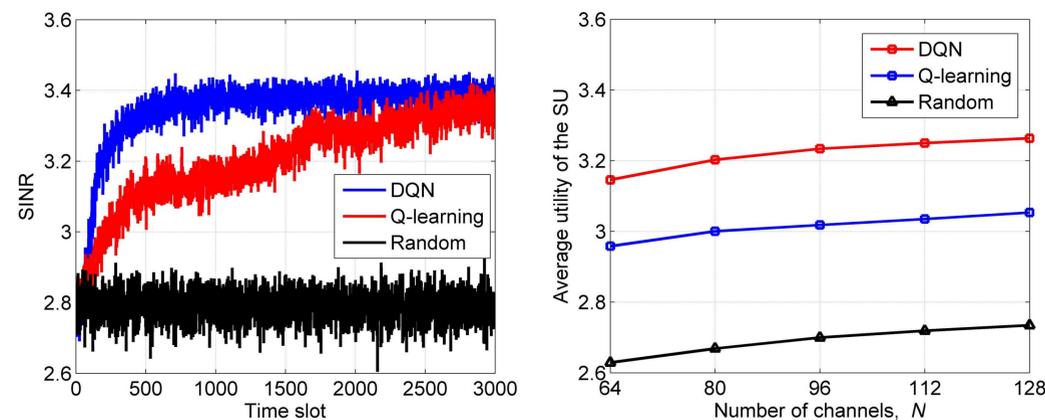


Figure 3. Performance of the DQN-based 2-D anti-jamming scheme.

## Challenges:

- Both the jamming model and the radio channel model are unaware to the SU
- The size of available system state set is large
- The size of feasible frequency channels is large

## Q-learning:

- Learning with incomplete information via trials
- Choose an action based on the Q-function, which is the expected discounted long-term utility for state  $\mathbf{s}$  and action  $x$
- Suffer from the curse of high-dimensional  $Q(\mathbf{s}_k, x_k) = (1 - \alpha)Q(\mathbf{s}_k, x_k) + \alpha(u_k + \gamma \max_{0 \leq x' \leq N} Q(\mathbf{s}_{k+1}, x'))$

## Deep Q-network :

- Combine reinforcement learning and deep learning
- Address the curse of high-dimensional of Q-learning by using convolutional neural network
- Significant improvements in the learning speed

$$L(\theta_k) = \mathbb{E} \left[ \left( u + \gamma \max_{0 \leq x' \leq N} Q(\phi', x'; \theta_{k-1}) - Q(\phi, x; \theta_k) \right)^2 \right]$$

## Conclusions

- We have formulated a dynamic anti-jamming communication game for CRNs, which exploits both **frequency hopping** and **user mobility** to improve the SINR of the signals against cooperative smart jammers
- A DQN-based 2-D communication system is proposed for an SU to achieve the optimal anti-jamming policy
- The proposed 2-D DQN-based anti-jamming system outperforms the Q-learning strategy with a **faster convergence rate**, higher SINR, lower cost of defense and higher utility of the SU

## References

1. L. Xiao, J. Liu, Q. Li, N. B. Mandayam, and H. V. Poor, "User-centric view of jamming games in cognitive radio networks," *IEEE Transactions on Information Forensics and Security*, vol. 10, no. 12, pp. 2578-2590, Dec. 2015.
2. V. Mnih, K. Kavukcuoglu, D. Silver, A. A. Rusu, J. Veness, M. G. Bellemare, A. Graves, M. Riedmiller, A. K. Fidjeland, and G. Ostrovski., "Human-level control through deep reinforcement learning," *Nature*, vol. 518, no. 7540, pp. 529-33, Jan. 2015.